

# CSCI 5582 Artificial Intelligence

Lecture 7  
Jim Martin

9/19/06

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## Today 9/19

- Review (and finish) search
- Break
- Game Playing Search

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## Review

- Optimization/Local Search
- Constraint Satisfaction Search

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## Local Search

- Hillclimbing
- Random-Restart Hillclimbing
- Simulated Annealing

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## Constraint Satisfaction

- In CSP problems, states are represented as sets of variables, each with values chosen from some domain
- A goal test consists of satisfying constraints on sets of variable/value combinations
- A goal state is one that has no constraint violations

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5

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## Approaches to CSPs

- As a kind of backtracking search
- As a kind of iterative improvement

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## Making Backtracking Work

- What it means to be a goal (or not) can be decomposed
  - In CSPs a state is a goal state if *all* of the constraints are satisfied.
  - A state fails as a goal state if *any* constraint is violated
  - Therefore we can check for violations as variables are assigned values

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7

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## Informed Backtracking CSP Search

- The previous discussion didn't use any notion of heuristic.
- There are two places heuristics can help
  - Which variable to assign next
  - Which value to assign to a variable

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8

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## Generic CSP Heuristics

- Variables
  - Degree heuristic
    - The one involved in the largest number of constraints
  - Choose the most constrained variable
    - The one with the minimum remaining values
- Values
  - Choose the least constraining value

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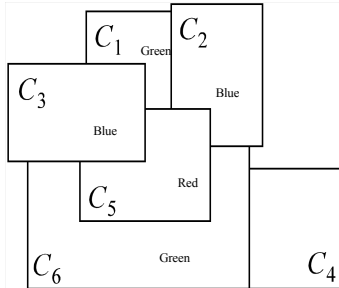
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## Graph Coloring



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## Iterative Improvement

- Sometimes it's better to look at these problems as optimization problems.
- Where you want to optimize (minimize) the number of constraints violated (to zero would be good)

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11

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## How?

- Randomly assign values to all the variables in the problem (from their domains)
- Iteratively fix the variables (reassign values) that are conflicted.
- Continue until there are no conflicts or no progress

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12

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## Min Conflict Heuristic

- Randomly choose a variable from the problematic ones.
- Reassign its value to be the one that results in the fewest conflicts
- Continue until there are no conflicts

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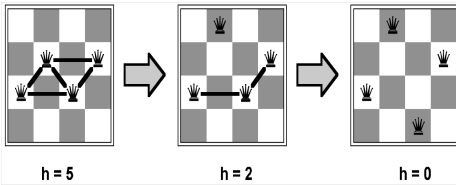
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## Min Conflict Example

- States: 4 Queens, 1 per column
- Operators: Move queen in its column
- Goal test: No attacks
- Evaluation metric: Total number of attacks



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14

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## Min Conflict Performance

- Min Conflict seems to have astounding performance.
- For example, it's been shown to solve arbitrary size (in the millions) N-Queens problems in constant time.
- This appears to hold for arbitrary CSPs with the caveat...

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15

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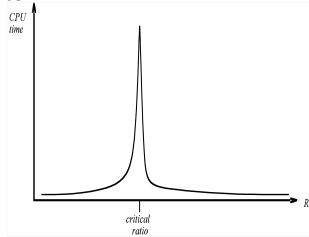
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## Min Conflict Performance

- Except in a certain critical range of the ratio constraints to variables.



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## Preferences and Constraints

- In practice, applications can get fairly messy
  - Sometimes you want the lowest cost zero conflict solution
  - Sometimes constraints are preferences not true constraints
  - Sometimes some constraints are more important than other constraints. That is, the cost of violating some constraints is more than the cost of violating others.

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## Admin/Break

- Questions?
- Quiz will be on Thursday for the first 30 minutes or so.
  - Focus is on search
  - Chapters 3,4,5 and 6 (today)

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## Game Playing Search

- Why study games?
- Why is search a good idea?

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## Typical Assumptions

- Some major assumptions we've been making:
  - Only an agent's actions change the world
  - World is deterministic and accessible
- Pretty much true in lots of games

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20

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## Why Search?

- Ignoring computational complexity, games are a perfect application for a complete search.
- Of course, ignoring complexity is a bad idea, so games are a good place to study resource bounded searches.

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21

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## MiniMax

- From among the moves available to you, take the best one
- Where the best one is determined by a search using the MiniMax strategy

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22

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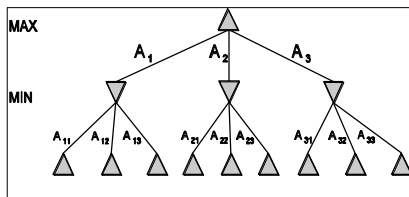
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## MiniMax

- I'll choose the best move for me (max)
- You'll choose the best move for you (min)



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23

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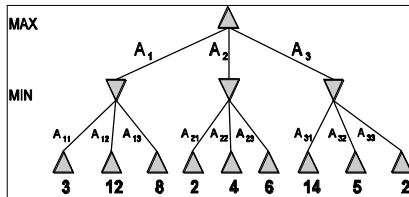
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## MiniMax

- I'll choose the best move for me (max)
- You'll choose the best move for you (min)



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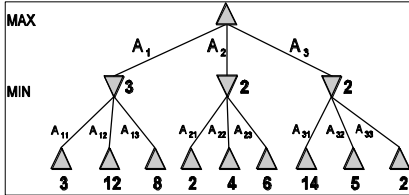
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## MiniMax

- I'll choose the best move for me (max)
- You'll choose the best move for you (min)



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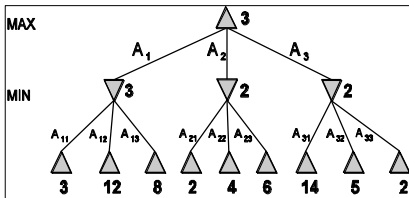
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## MiniMax

- I'll choose the best move for me (max)
- You'll choose the best move for you (min)



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26

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## Ideal Case

- Search all the way to the leaves (end game positions)
- Return the leaf (leaves) that leads to a win (for me)
- Anything wrong with that?

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27

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## More Realistic

- Search ahead to a non-leaf (non-goal) state and evaluate it somehow
- Chess
  - 4 ply is a novice
  - 8 ply is a master
  - 12 ply can compete at the highest level
- In no sense can 12 ply be likened to a search of the whole space

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28

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## Evaluation Functions

- Need a numerical function that assigns a value to a non-goal state
  - Has to capture the notion of a position being good for one player
  - Has to be fast
  - Has to be fast
  - Typically a linear combination of simple metrics

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29

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## MiniMax Implemented

- Depth-first, left to right, recursive, depth-limited search
- Only the leaves are evaluated
- Return values represent the best value found below that point in the tree (not the specific moves taken)

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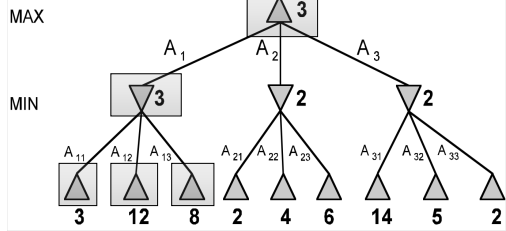
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## Once More



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## Extensions

- Pruning
- Openings and Closings
- Managing Time

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## Alpha-Beta Pruning

- Often you can ignore entire sections of the search space and come up with the same answer
- Specifically, if you're exploring a line of play that leads to a worse position for you than another one you've already discovered, then don't explore that line anymore.

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33

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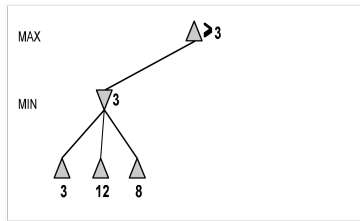
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## Alpha-Beta Pruning



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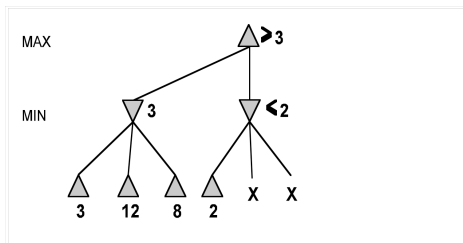
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## Alpha Beta Pruning



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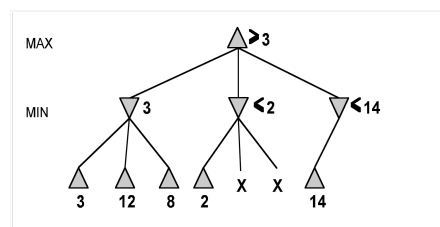
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## Alpha-Beta Pruning



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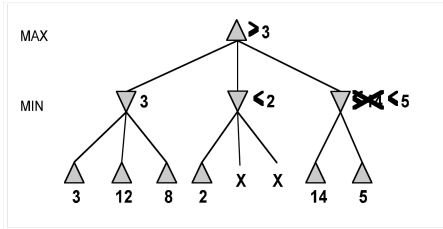
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## Alpha-Beta Pruning



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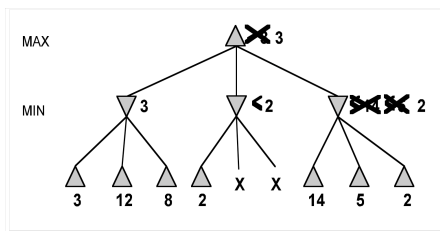
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## Alpha-Beta Pruning



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38

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## How does AB Help?

- After all, all it does is return the same answer you would have gotten otherwise.
- So what's the big deal?

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39

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## How does AB Help

- It helps if you can use the time saved to look deeper into the tree.
- Moving from  $b^d$  to  $b^{d/2}$  means that that you can go to 8 ply in the same time it took to go to 4
- Or going from novice to master with the same smarts
- This assumes that you have some way to manage the clock

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40

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## Improving AB

- Recall that MiniMax is normally a depth-first, left to right, procedure.
- AB works better if the most informative nodes are evaluated first (on the left, as opposed to the right).

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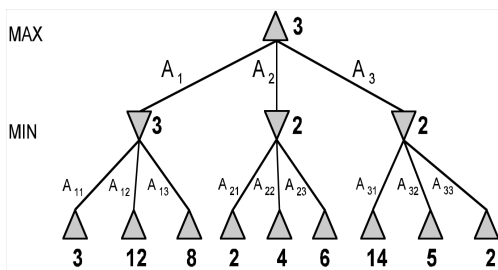
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## Improving AB



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42

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## Dealing with Time

- In tournament play, you have a time constraint.
- Need some effective way to manage the clock.
- I.e. you need to be sure that you have a move to make when the bell goes off.

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43

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## Iterative Deepening (again)

- Run MiniMax inside an ID wrapper.
- Remember the best move from previous rounds
- Keep iterating until some time limit is reached
- Key point: You always have an answer available

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44

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## Openings and Closings

- Do we really need a search right from the start?
- Or at the end?

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## Game Trivia

- Chinook had closing book with 400 Billion positions
- Deep Blue examined ~100 Billion boards per move
- Often reached 14 ply
- Better pruning/move ordering beats faster better hardware

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46

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## Next Time

- Quiz (30 min)
- Start on Chapter 7

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