University of Colorado  
Department of Computer Science  
Chaotic Dynamics – CSCI 4446/5446  
Spring 2023  
Problem Set 7

Issued: 28 February 2023  
Due: 7 March 2023

Reading: Strogatz, sections 6.0-6.5; Liz’s notes on the variational equation; Parker&Chua, Appendix B.

Online assignment: Tuesday: unit 3.5 and 6.4 videos. Thursday: unit 6.5 video. Friday: quiz 6.4.

Bibliography:


Problems:

1. \[
\mathbf{F}(\mathbf{x}, a, r, b) = \begin{bmatrix}
\dot{x} \\
\dot{y} \\
\dot{z}
\end{bmatrix} = \begin{bmatrix}
a(y - x) \\
rx - y - xz \\
xy - bz
\end{bmatrix}
\] (1)

2. \[
\dot{\delta} = D_x \mathbf{F} \delta
\]

yields an \( n \times n \) matrix of the derivatives of the variations \( \dot{\delta} \). \( \delta_{xy} \), for instance, is the component of the \( x \)-variation that comes from the previous \( y \)-variation, and \( \dot{\delta}_{xy} \) is its rate of change with time.
3. A combination of this variational derivative and the original system derivative from PS5 can be used to integrate the \((n^2+n)\)-dimensional variational equation

\[
\begin{bmatrix}
\dot{x} \\
\dot{\delta}
\end{bmatrix} =
\begin{bmatrix}
\vec{F} \\
D_x\vec{F} \cdot \delta
\end{bmatrix}
\]

from the initial condition

\[
\begin{bmatrix}
\vec{x}_0 \\
I
\end{bmatrix}
\]

with \(t = t_0\). The time evolution of the first \(n\) elements of this set of initial conditions follows the trajectory \(\phi_t(\vec{x}_0, t_0)\). The row and column sums of the matrix formed by the next \(n^2\) elements are different ways to look at the evolved versions of the initial variations: the first column sum, for example, gives the \(x\) component of the evolved variation, while the first row sum tells you what the \(x\)-piece of the original variation has grown into.

Integrate the Lorenz variational equation using RK4 (not ARK4) from the following initial conditions for 100 steps. Use \(a = 16, r = 45, b = 4\), and a timestep of .001. In each case, give

- the components of the evolved matrix \(\delta\)
- the evolved variations (the column sums of \(\delta\))

at the endpoint of the trajectory. Use \(t_0 = 0\) (this is really immaterial, as the system is autonomous). You need only turn in these twelve numbers for each of the following questions; no plots or intermediate values are necessary.

(a) \([x\ y\ z\ \delta_{xx}\ \delta_{xy}\ \delta_{xz}\ \delta_{yy}\ \delta_{yz}\ \delta_{zx}\ \delta_{zy}\ \delta_{zz}] = [0\ 1\ 2\ 1\ 0\ 0\ 0\ 1\ 0\ 0\ 1]\)
(b) \([10\ -5\ 2\ 1\ 0\ 0\ 0\ 1\ 0\ 0\ 1]\)
(c) \([0\ -1\ 2\ 1\ 0\ 0\ 0\ 1\ 0\ 0\ 1]\)

(d) Look carefully at the evolved matrices of variations and describe some of their interesting features. From which point [(a), (b), or (c)] do the variations grow fastest? In which direction \((x, y, z)\)? Do you notice any symmetries or gross differences between the different points \((e.g.,\ \text{“the y-variation grows really fast near point A, but less so near point B...”}})\)?