Reading: Strogatz, chapter 9 and sections 4.4-4.6, 6.7, 10.6, 12.3, and 12.4; Baker&Gollub, pp 4-5 and pp 40-60; “Coping with Chaos...,” chapter 5; section 3 of Liz’s TSA Notes.

Parts of sections 4.5, 4.6, 9.1 and 9.2 in Strogatz are mathematically quite dense. Read for content here; look at the equations, but don’t worry about understanding the derivations or the deep mathematical implications.

Note: this week’s reading assignment is substantial and the programming workload has been adjusted accordingly.


Bibliography:


Problems:

0. Play with some of the tones at tones.wolfram.com and think about how they were generated. (No need to turn anything in here, but this will come back as an in-class thought experiment in a week or two.)

1. Write an adaptive time-step fourth-order Runge-Kutta integrator. A picture with definition of terms appears below:
\( \Delta_1 = x_2 - x_1 \).

Error condition: \( ||\Delta_1||_\infty \leq 0.001 \).

Note: \( ||1, -2, -1||_\infty = 2 \) and \( ||1, -2, -1||_2 = \sqrt{1^2 + (-2)^2 + (-1)^2} \). The former is the “largest element” operator and the latter is Euclidean length.

(No need to turn anything in here either; the following problems will put this beast through its paces.)

2. (a) Use your adaptive integrator to plot a picture of the chaotic attractor in the Lorenz system:

\[
\dot{\vec{x}}(\vec{x}, a, r, b) = \begin{bmatrix}
\dot{x} \\
\dot{y} \\
\dot{z}
\end{bmatrix} = \begin{bmatrix}
a(y - x) \\
rx - y - xz \\
xy - bz
\end{bmatrix}
\]

with \( a = 16, r = 45, b = 4 \), starting from the initial condition \((x, y, z) = (-13, -12, 52)\). Unless you have a 3D plotter, you will have to choose a projection to make the plot; most books (e.g., Gleick) use the \( x - z \) plane.

(b) Use your nonadaptive integrator from PS4 to plot a trajectory from the same initial condition using a timestep of 0.001. Overlay your plots from (a) and (b)—e.g., with different color points. Do the two solutions (adaptive and non) agree? (It may help to do this with only a short segment of the trajectory, so you can see what’s going on.) Are the points produced by the adaptive solver evenly spaced in time?

(c) What happens if you keep \( a \) and \( b \) fixed and change \( r \)? (no need to turn in plots; simply describe what happens in the language of nonlinear dynamics). Hints: try a few \( r \) values between 0 and 1, several between 13.5 and 14, and a bunch between 23 and 30. Also, don’t confine your explorations to a small area of the state space; try lots of different initial conditions.

3. Use your adaptive integrator to plot a picture of the chaotic attractor in the Rössler system:

\[
\dot{\vec{x}}(\vec{x}, a, b, c) = \begin{bmatrix}
\dot{x} \\
\dot{y} \\
\dot{z}
\end{bmatrix} = \begin{bmatrix}
-(y + z) \\
x + ay \\
b + z(x - c)
\end{bmatrix}
\]

with \( a = .398, b = 2, c = 4 \). Again, choose any projection you wish.

4. Now go back to the Lorenz system and the parameter values given in problem 2. Your task in this problem is to explore the effects of loosening the error bounds. Increase the allowed error from 0.01 until you see the dynamics break down. Turn in one or two plots in this series, the last clearly showing the altered dynamics. How is this related to the results of the timestep explorations you did on the last problem set?