

Multilayer Networks

Computational Linguistics: Jordan Boyd-Graber University of Maryland SLIDES ADAPTED FROM ANDREW NG





Input

Vector $x_1 \dots x_d$

inputs encoded as real numbers



Input

Vector $x_1 \dots x_d$

$$f\left(\sum_{i}W_{i}x_{i}+b\right)$$

multiply inputs by



Input

Vector $x_1 \ldots x_d$

$$f\left(\sum_{i}W_{i}x_{i}+b\right)$$

add bias

Output

Output



Input

Vector $x_1 \ldots x_d$

$$f\left(\sum_{i}W_{i}x_{i}+b\right)$$

Activation
$$f(z) \equiv \frac{1}{1 + \exp(-z)}$$

pass through nonlinear sigmoid

Why is it called activation?



In the shallow end

- This is still logistic regression
- Engineering features x is difficult (and requires expertise)
- Can we learn how to represent inputs into final decision?

Better name: non-linearity



Logistic / Sigmoid

$$f(x) = \frac{1}{1 + e^{-x}}$$
 (1)

$$f(x) = \tanh(x) = \frac{2}{1 + e^{-2x}} - 1$$
(2)

ReLU

$$f(x) = \begin{cases} 0 & \text{for } x < 0 \\ x & \text{for } x \ge 0 \end{cases}$$
(3)

• SoftPlus: $f(x) = \ln(1 + e^x)$



$$a_1^{(2)} = f\left(W_{11}^{(1)}x_1 + W_{12}^{(1)}x_2 + W_{13}^{(1)}x_3 + b_1^{(1)}\right)$$



$$a_{2}^{(2)} = f\left(W_{21}^{(1)}x_{1} + W_{22}^{(1)}x_{2} + W_{23}^{(1)}x_{3} + b_{2}^{(1)}\right)$$



$$a_{3}^{(2)} = f\left(W_{31}^{(1)}x_{1} + W_{32}^{(1)}x_{2} + W_{33}^{(1)}x_{3} + b_{3}^{(1)}\right)$$



$$h_{W,b}(x) = a_1^{(3)} = f\left(W_{11}^{(2)}a_1^{(2)} + W_{12}^{(2)}a_2^{(2)} + W_{13}^{(2)}a_3^{(2)} + b_1^{(2)}\right)$$

 For every example x, y of our supervised training set, we want the label y to match the prediction h_{W,b}(x).

$$J(W,b;x,y) \equiv \frac{1}{2} ||h_{W,b}(x) - y||^2$$
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- We also want the weights not to be too large

$$\frac{\lambda}{2} \sum_{l=1}^{n_l-1} \sum_{i=1}^{s_l} \sum_{j=1}^{s_{l+1}} \left(W_{ji}^{l} \right)^2 \tag{5}$$

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Sum over all layers

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Sum over all destinations

Putting it all together:

$$J(W,b) = \left[\frac{1}{m}\sum_{i=1}^{m}\frac{1}{2}||h_{W,b}(x^{(i)}) - y^{(i)}||^2\right] + \frac{\lambda}{2}\sum_{l=1}^{n_l-1}\sum_{j=1}^{s_l}\sum_{j=1}^{s_{l+1}}\left(W_{ji}^l\right)^2 \quad (6)$$

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- Initialize W and b to small random value near zero
- Adjust parameters to optimize J

Gradient Descent

Goal

Optimize J with respect to variables W and b



- For convenience, write the input to sigmoid

$$z_i^{(l)} = \sum_{j=1}^n W_{ij}^{(l-1)} x_j + b_i^{(l-1)}$$
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- For output nodes, the error is obvious:

$$\delta_{i}^{(n_{l})} = \frac{\partial}{\partial z_{i}^{(n_{l})}} ||y - h_{w,b}(x)||^{2} = -\left(y_{i} - a_{i}^{(n_{l})}\right) \cdot f'\left(z_{i}^{(n_{l})}\right) \frac{1}{2}$$
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 Other nodes must "backpropagate" downstream error based on connection strength

$$\delta_{i}^{(l)} = \left(\sum_{j=1}^{s_{l+1}} W_{ji}^{(l+1)} \delta_{j}^{(l+1)}\right) f'(z_{i}^{(l)})$$
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(chain rule)

Partial Derivatives

For weights, the partial derivatives are

$$\frac{\partial}{\partial W_{ij}^{(l)}} J(W,b;x,y) = a_j^{(l)} \delta_i^{(l+1)}$$
(10)

For the bias terms, the partial derivatives are

$$\frac{\partial}{\partial b_i^{(l)}} J(W,b;x,y) = \delta_i^{(l+1)}$$
(11)

But this is just for a single example ...

Full Gradient Descent Algorithm

- 1. Initialize $U^{(l)}$ and $V^{(l)}$ as zero
- 2. For each example $i = 1 \dots m$
 - 2.1 Use backpropagation to compute $\nabla_W J$ and $\nabla_b J$
 - **2.2** Update weight shifts $U^{(l)} = U^{(l)} + \nabla_{W^{(l)}} J(W, b; x, y)$
 - **2.3** Update bias shifts $V^{(l)} = V^{(l)} + \nabla_{b^{(l)}} J(W, b; x, y)$
- 3. Update the parameters

$$W^{(l)} = W^{(l)} - \alpha \left[\left(\frac{1}{m} U^{(l)} \right) \right]$$
(12)
$$b^{(l)} = b^{(l)} - \alpha \left[\frac{1}{m} V^{(l)} \right]$$
(13)

Repeat until weights stop changing

But it is not perfect

- Compare against baselines: randomized features, nearest-neighbors, linear models
- Optimization is hard (alchemy)
- Models are often not interpretable
- Requires specialized hardware and tons of data to scale