



Quantum Searching- Grover , Optimality

PHYS/CSCI 3090

Prof. Alexandra Kolla

Alexandra.Kolla@Colorado.edu

ECES 122

Prof. Graeme Smith

Graeme.Smith@Colorado.edu

JILA S326

<https://home.cs.colorado.edu/~alko5368/indexCSCI3090.html>

Come see us!

- Alexandra Kolla/ Graeme Smith: Friday 3:00-4:00 pm, over zoom.
- Ariel Shlosberg: Tu/Th 2:00-4:00pm, over zoom
- Steven Kordonowy: Th 11am-12pm, over zoom.
- Matteo Wilczak: Wednesday, 1-2pm, over zoom.

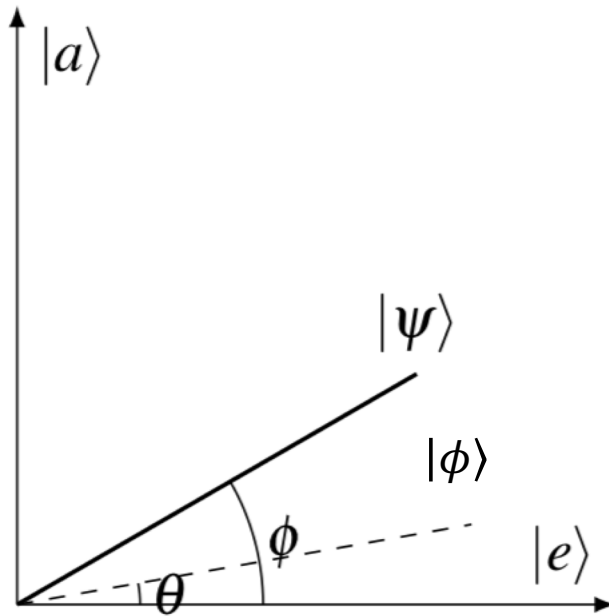
Today

- Homework out, due next Monday at noon on Canvas

Today

- Optimality of Grover

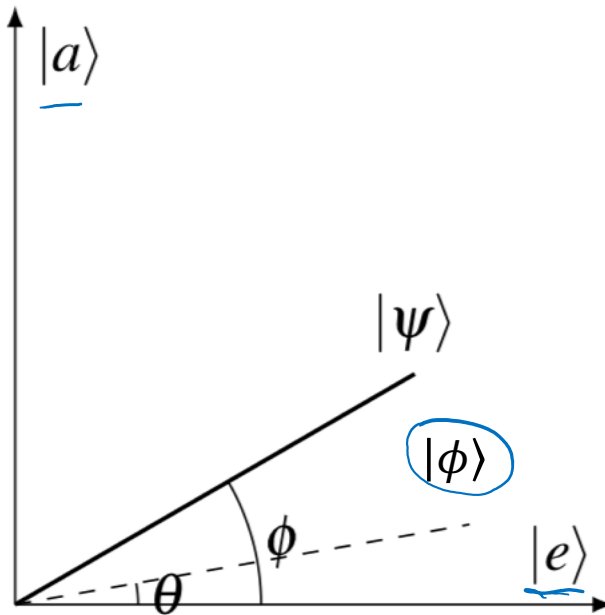
The start of one iteration



The start of one iteration

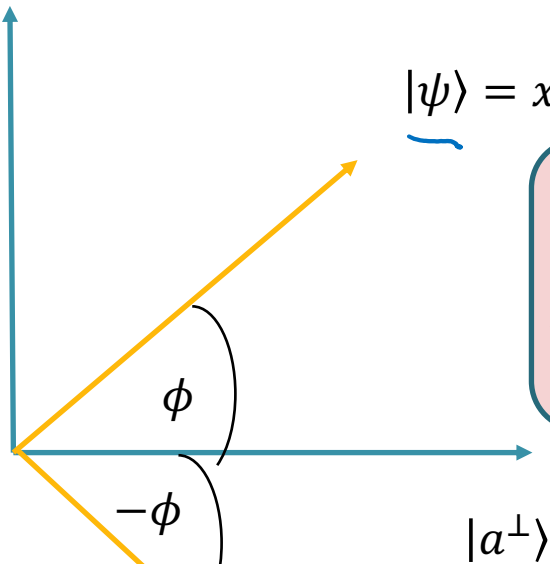
$$|\phi\rangle = \frac{1}{\sqrt{N}} \sum_{0 < x \leq N} |x\rangle_n$$

$$|e\rangle = \frac{1}{\sqrt{N-1}} \sum_{x \neq a} |x\rangle_n$$



After V

$|a\rangle$



$$|\psi\rangle = x_1 |a^\perp\rangle + y_1 |a\rangle$$

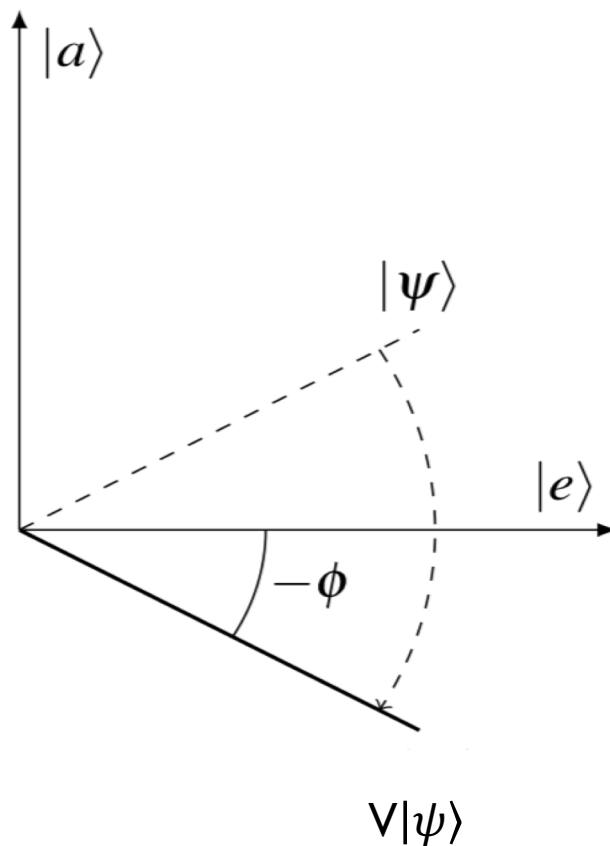
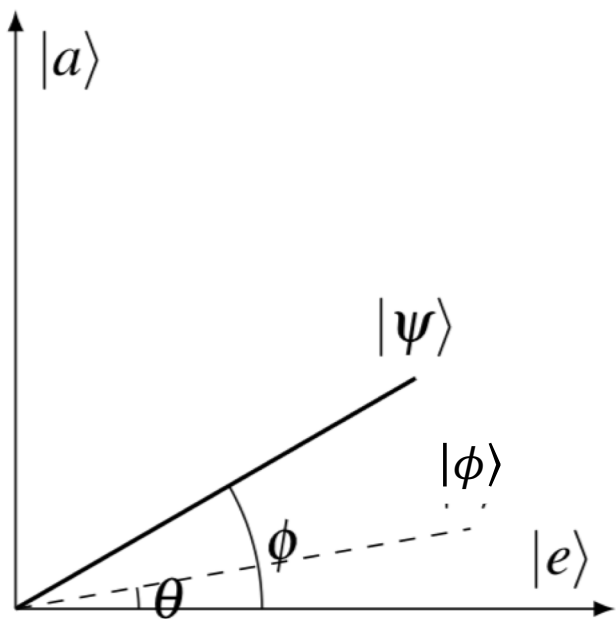
$V = I - 2|a\rangle\langle a|$
Corresponds to a flip over $|e\rangle = \frac{1}{\sqrt{N-1}} \sum_{x \neq a} |x\rangle_n$
Which is perpendicular to $|a\rangle$

$$V|\psi\rangle = x_1 |a^\perp\rangle - y_1 |a\rangle$$

After V

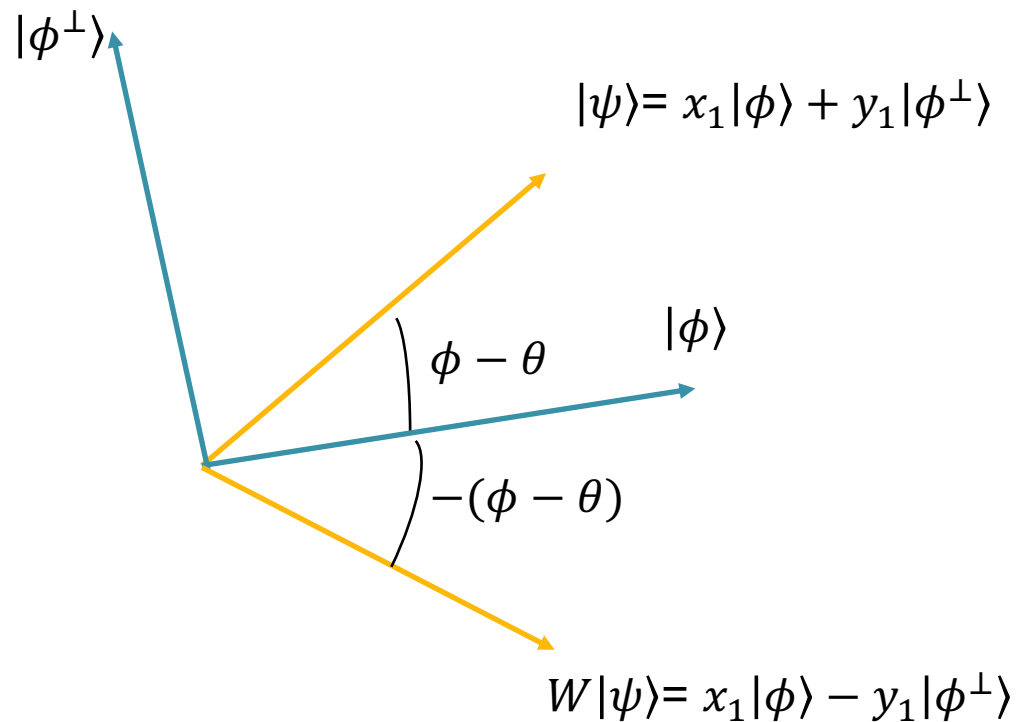
$V = I - 2|a\rangle\langle a|$
Corresponds to a flip over $|e\rangle$

$$|e\rangle = \frac{1}{\sqrt{N-1}} \sum_{x \neq a} |x\rangle_n$$



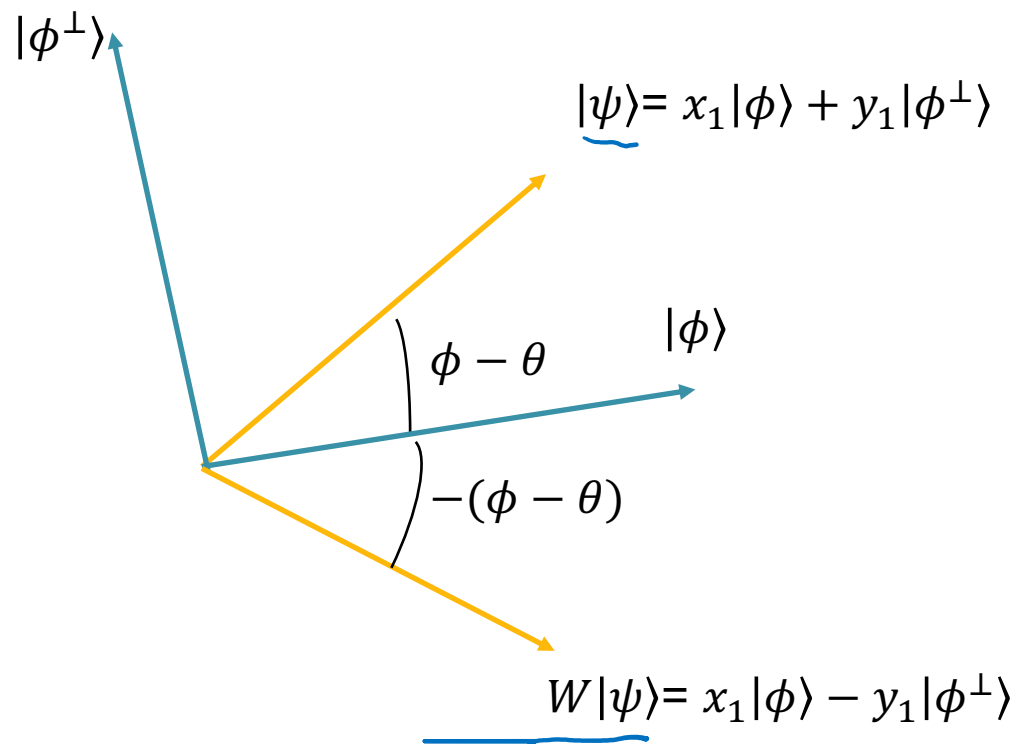
After W

$W = 2|\phi\rangle\langle\phi| - I$
Corresponds to a flip over $|\phi\rangle$



After W

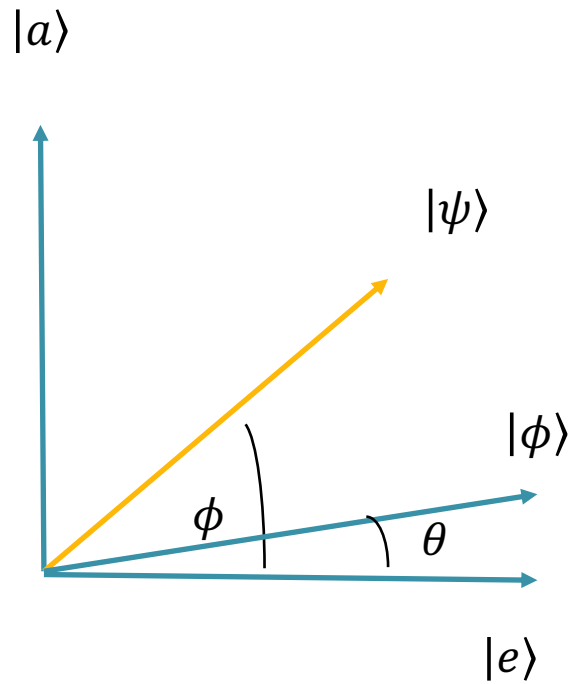
$W = 2|\phi\rangle\langle\phi| - I$
Corresponds to a flip over $|\phi\rangle$



Putting it together

$$|\phi\rangle = \frac{1}{\sqrt{N}} \sum_{0 < x \leq N} |x\rangle_n$$

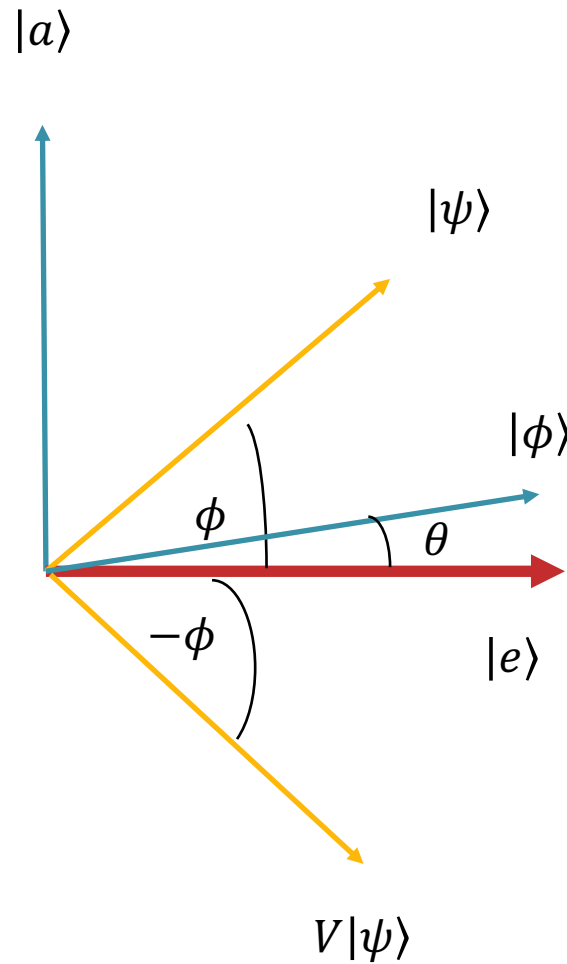
$$|e\rangle = \frac{1}{\sqrt{N-1}} \sum_{x \neq a} |x\rangle_n$$



Putting it together

$$|\phi\rangle = \frac{1}{\sqrt{N}} \sum_{0 < x \leq N} |x\rangle_n$$

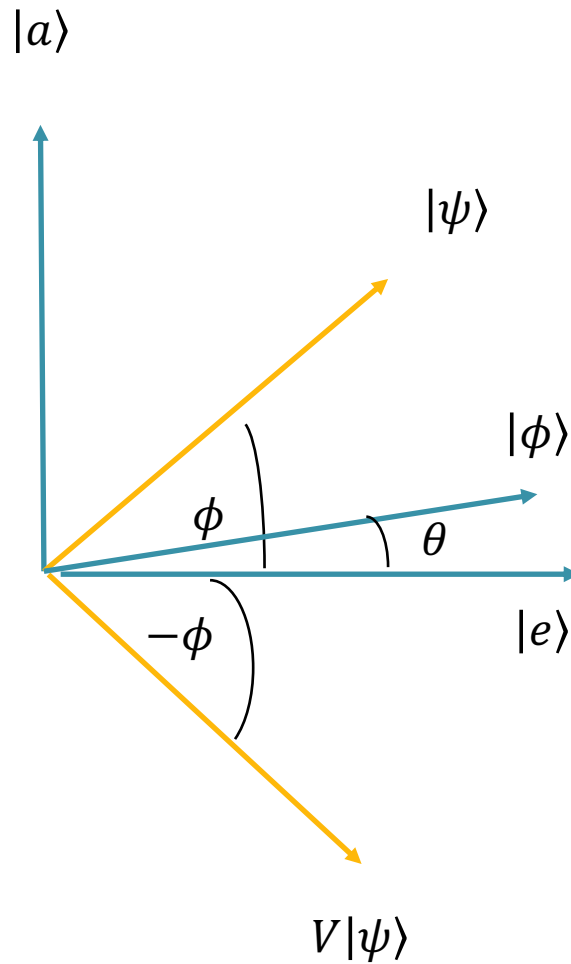
$$|e\rangle = \frac{1}{\sqrt{N-1}} \sum_{x \neq a} |x\rangle_n$$



Putting it together

$$|\phi\rangle = \frac{1}{\sqrt{N}} \sum_{0 < x \leq N} |x\rangle_n$$

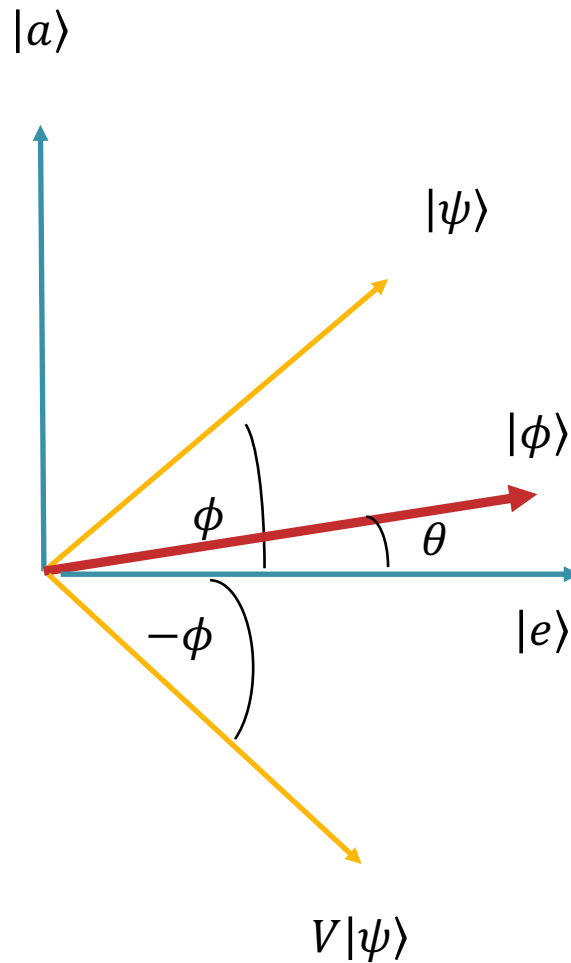
$$|e\rangle = \frac{1}{\sqrt{N-1}} \sum_{x \neq a} |x\rangle_n$$



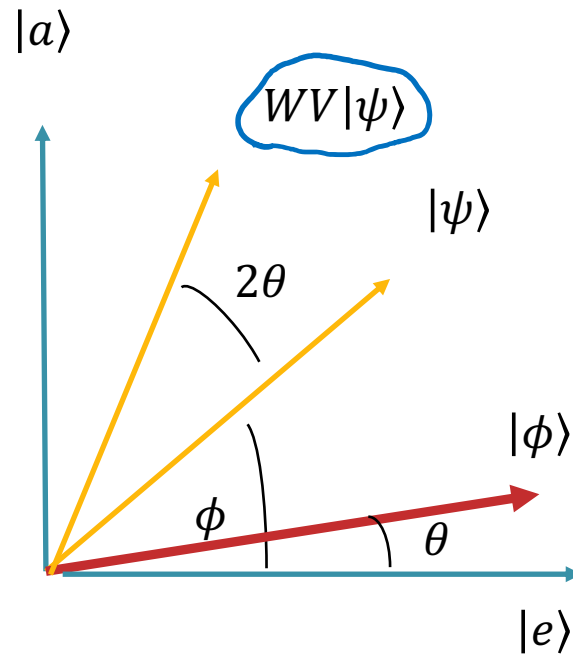
Putting it together

$$|\phi\rangle = \frac{1}{\sqrt{N}} \sum_{0 < x \leq N} |x\rangle_n$$

$$|e\rangle = \frac{1}{\sqrt{N-1}} \sum_{x \neq a} |x\rangle_n$$



Putting it together

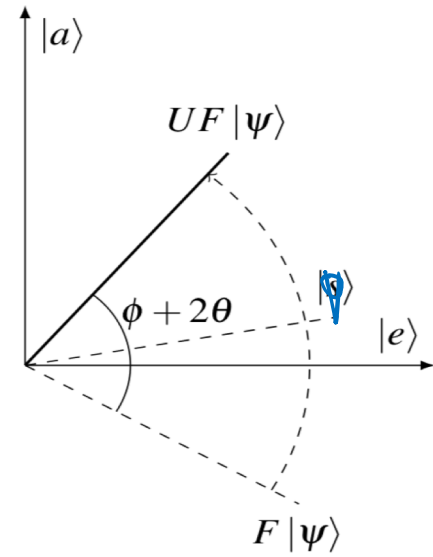
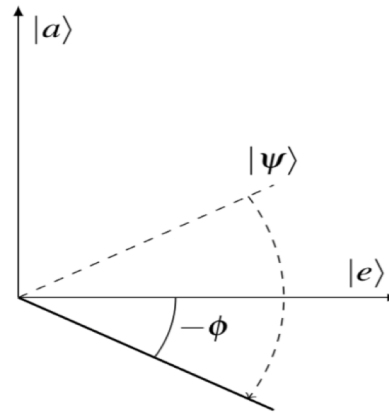
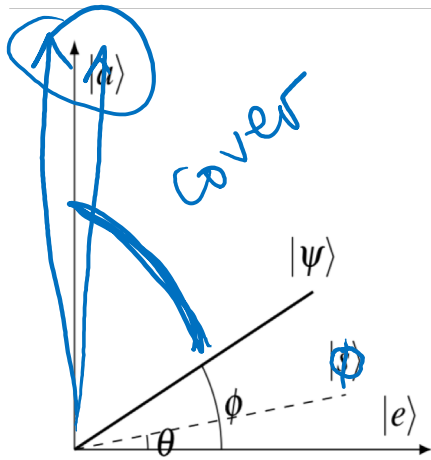


$$|\phi\rangle = \frac{1}{\sqrt{N}} \sum_{0 < x \leq N} |x\rangle_n$$

$$|e\rangle = \frac{1}{\sqrt{N-1}} \sum_{x \neq a} |x\rangle_n$$

In the end

$$|e\rangle = \frac{1}{\sqrt{N-1}} \sum_{x \neq a} |x\rangle_n$$



The Algorithm

- We concluded that V corresponds to a reflection over $|e\rangle$ (perp to $|a\rangle$) and W corresponds to a reflection over $|\phi\rangle$ (uniform superposition, and also starting state).
- If we define θ as the angle between $|\phi\rangle$ and $|e\rangle$, and ϕ as the angle between $|\psi\rangle$ and $|e\rangle$ (where $|\psi\rangle$ is the state at the current iteration), we see that the transformations perform the following rotations:
 - $\phi \xrightarrow{V} -\phi \xrightarrow{W} \underbrace{\phi + 2\theta}$

The Algorithm

- After one iteration, we rotate the state vector by $2\theta = 2 \arcsin\left(\frac{1}{\sqrt{N}}\right) \sim 2/\sqrt{N}$
- Since we start out at state $|\phi\rangle$ (uniform) almost orthogonal to $|a\rangle$, (Assuming N is large), we need to rotate by $\frac{\pi}{2}$.
- So we need about $\frac{\frac{\pi}{2} - \theta}{2\theta} \sim \theta(\sqrt{N})$ applications of the algorithm.

The Algorithm-Is it optimal?

- Why can't we design another quantum algorithm with less queries?
- How do we even prove optimality?
- To prove optimality, we show that any sequence of unitary operators (combined with calls to the oracle) that distinguish between the function that has 0 everywhere and the function which is 1 at the a 'th position requires at least $\underline{Q}(\sqrt{N})$ calls of the oracle.

2^n inputs . f_0, f_a differ in only 1

$$f_0(x) = 0 \quad \forall x$$
$$f_a(x) = \begin{cases} 0 & \forall x \neq a \\ 1 & x = a \end{cases}$$

The Algorithm-Is it optimal?

- Let U_1, U_2, \dots be some unitaries and U_f the oracle corresponding to a function f .
- Let $|v_{f,k}\rangle = \underbrace{U_k U_f U_{k-1} U_f \dots U_1}_{\text{iteration } i}$ $|\phi\rangle$ be the state of the input register after k iterations of this new algorithm.
- Let $|\phi_k\rangle = \underbrace{U_k U_{k-1} \dots U_1}_{\text{iteration } i}$ $|\phi\rangle$

f_0, f_a

1 iteration: $U_i U_f$

The Algorithm-Is it optimal?

- Let U_1, U_2, \dots be some unitaries and U_f the oracle corresponding to a function f .

- ① • Let $|v_{f,k}\rangle = U_k U_f U_{k-1} \dots U_1 |\phi\rangle$ be the state of the input register after k iterations of this new algorithm.

- ② • Let $|\phi_k\rangle = U_k U_{k-1} \dots U_1 |\phi\rangle$

- Question: For what f is $|v_{f,k}\rangle = |\phi_k\rangle$?

Answer: $U_f = I \Leftrightarrow f = f_0 \checkmark$

$$f_0 \rightarrow U_{f_0} = I$$

$$f_a \rightarrow U_{f_a} = I - 2|a\rangle\langle a|$$

$$f: |x_0, 1\rangle \rightarrow |x_0, 1\rangle$$

The Algorithm-Is it optimal?

- Let U_1, U_2, \dots be some unitaries and U_f the oracle corresponding to a function f .
- Let $|v_{f,k}\rangle = U_k U_f U_{k-1} U_f \dots U_1 |\phi\rangle$ be the state of the input register after k iterations of this new algorithm.
- Let $|\phi_k\rangle = U_k U_{k-1} \dots U_1 |\phi\rangle$
- Question: For what f is $|v_{f,k}\rangle = |\phi_k\rangle$?
- $|\phi_k\rangle$ corresponds to the function which is zero everywhere (no marked element)

The Algorithm-Is it optimal?

- Let U_1, U_2, \dots be some unitaries and U_f the oracle corresponding to our “marked element” function $f, f(a)=1$.
- Let $|v_{f,k}\rangle = U_k U_f U_{k-1} U_f \dots U_1 |\phi\rangle$ be the state of the input register after k iterations of this new algorithm.
- Let $|\phi_k\rangle = U_k U_{k-1} \dots U_1 |\phi\rangle$
- Question: is $|\phi_k\rangle$ independent of a ?

The Algorithm-Is it optimal?

- Let U_1, U_2, \dots be some unitaries and U_f the oracle corresponding to our “marked element” function f , $f(a)=1$.
- Let $|v_{f,k}\rangle = U_k U_f U_{k-1} U_f \dots U_1 |\phi\rangle$ be the state of the input register after k iterations of this new algorithm.
- Let $|\phi_k\rangle = U_k U_{k-1} \dots U_1 |\phi\rangle$
- Since the oracle depends on a , U_f changes with a , and so does $|v_{f,k}\rangle$.
- Since no measurement is done till the end, we can get no information about a before measuring, so the U_i are independent of a , and so is $|\phi_k\rangle$.

The Algorithm-Is it optimal?

- $|v_{f,k}\rangle = U_k U_f U_{k-1} U_f \dots U_1 |\phi\rangle$, $|\phi_k\rangle = U_k U_{k-1} \dots U_1 |\phi\rangle$
- Define $\underline{t_{a,k}} = ||v_{f,k}\rangle - |\phi_k\rangle|$.
- Measures the error between a run of the algorithm where f is zero everywhere, or 1 at a marked element a .

Optimality Proof- Big picture

We will show:

$$\text{Claim 1: } t_{a,k} = \left| \left| \nu_{f,k} \right\rangle - \left| \phi_k \right\rangle \right| \leq \sum_{i=1 \text{ to } k} 2 \langle a, \phi_i \rangle$$

- Assume our new algorithm runs for T steps.
- Since our algorithm needs to distinguish between the function which is zero everywhere and the one which has 1 at a , $t_{a,T}$ must be large.
- Recall $t_{a,T}$ is the difference between the output vectors when these two functions (zero everywhere, or 1 at a) are used as inputs.
- So for the sake of argument say that we need $t_{a,T} > 1/2$ for the algorithm to be successful.

Optimality Proof

- Assume Claim 1:

$$t_{a,k} = \left| \left| v_{f,k} \right\rangle - \left| \phi_k \right\rangle \right| \leq \sum_{i=1 \text{ to } k} 2 \langle a, \phi_i \rangle$$

k-steps algo, $|\phi_i\rangle = U_i v_{i-1} \dots U_1 |b\rangle$

- Show that we need at least $T = \Omega(\sqrt{N})$ iterations (invocations of U_f) to achieve

$$t_{a,T} > 1/2.$$

Optimality Proof-Main Tool

- Cauchy-Schwartz Inequality

Version 1: For any two vectors $|v\rangle, |u\rangle$ the following is true:

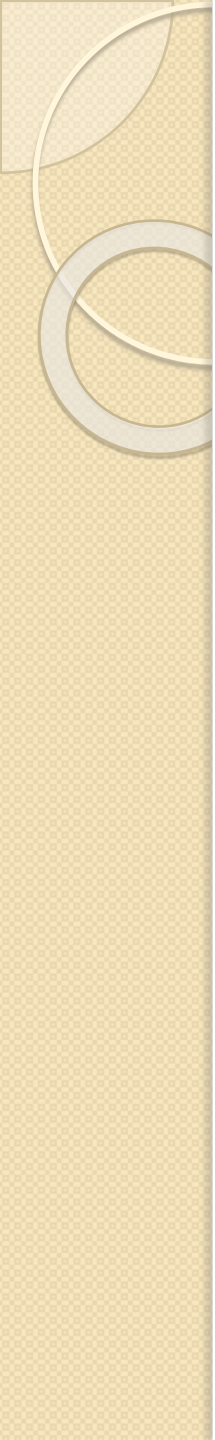
$$|\langle v, u \rangle| \leq \|v\| \|u\|$$

Version 2 (for reals):

$$\begin{aligned} & \sqrt{\langle v, v \rangle} \sqrt{\langle u, u \rangle} \\ &= \sqrt{\sum v_i^2} \sqrt{\sum u_i^2} \end{aligned}$$

$$\sum_{i=1}^n v_i u_i \leq \sqrt{\sum_{i=1}^n v_i^2} \sqrt{\sum_{i=1}^n u_i^2}$$

Question: derive Version 2 from Version 1.



Optimality Proof

- Assume Claim 1:

$$t_{a,k} = \left| \langle v_{f,k} | - | \phi_k \rangle \right| \leq \sum_{i=1 \text{ to } k} 2 \langle a, \phi_i \rangle$$

- Show that we need at least $T = \Omega(\sqrt{N})$ iterations (invocations of U_f) to achieve $t_{a,T} > 1/2$.

Proof: $\frac{1}{2} < t_{a,T} \stackrel{\text{claim 1 } T-1}{\leq} \sum_{i=1}^{T-1} \underbrace{2}_{v_i} \underbrace{\langle a, \phi_i \rangle}_{u_i} \stackrel{\text{Cauchy-Schwarz}}{\leq}$

$$\left(\sum v_i u_i \leq \sqrt{\sum v_i^2} \cdot \sqrt{\sum u_i^2} \right)$$

$$\leq \sqrt{\sum_{i=1}^{T-1} 4} \cdot \sqrt{\sum_{i=1}^{T-1} \langle a, \phi_i \rangle^2} = 2\sqrt{T-1} \cdot \sqrt{\sum_{i=1}^{T-1} \langle a, \phi_i \rangle^2}$$

Optimality Proof

- Assume Claim 1:

$$t_{a,k} = \left| \left| \nu_{f,k} \right\rangle - \left| \phi_k \right\rangle \right| \leq \sum_{i=1 \text{ to } k} 2 \langle a, \phi_i \rangle$$

- Show that we need at least $T = \Omega(\sqrt{N})$ iterations (invocations of U_f) to achieve $t_{a,T} > 1/2$.
- Proof:

$$\frac{1}{2} < t_{a,T} \leq \sum_{i=1 \text{ to } T-1} 2 \langle a, \phi_i \rangle \leq \sqrt{\sum_{i=1}^{T-1} 2^2} \sqrt{\sum_{i=1}^{T-1} \langle a, \phi_i \rangle^2} \leq 2\sqrt{T-1} \sqrt{\sum_{i=1}^{T-1} \langle a, \phi_i \rangle^2}$$

Optimality Proof

- Assume Claim 1:

$$t_{a,k} = ||v_{f,k}\rangle - |\phi_k\rangle| \leq \sum_{i=1 \text{ to } k} 2\langle a, \phi_i \rangle$$

- Show that we need at least $T = \Omega(\sqrt{N})$ iterations (invocations of U_f) to achieve $t_{a,T} > 1/2$.

- Proof:

$$\frac{1}{2} < t_{a,T} \leq 2\sqrt{T-1} \sqrt{\sum_{i=1}^{T-1} \langle a, \phi_i \rangle^2}$$

Question: how to bound $\sqrt{\sum_{i=1}^{T-1} \langle a, \phi_i \rangle^2}$?

Optimality Proof

- Question:

Assume we are given that $\{|a_1\rangle, \dots, |a_N\rangle\}$ is an orthonormal basis for the N -dimensional Hilbert space. Let $|\phi\rangle$ be an arbitrary unit vector on this space. What is $\sum_{i=1}^N \langle a_i, \phi \rangle^2$?

$$= 1$$

$$\Leftrightarrow \|\phi\| = 1$$

Optimality Proof

$$\frac{1}{2} < t_{a,T} \leq 2\sqrt{T-1} \sqrt{\sum_{i=1}^{T-1} \langle a, \phi_i \rangle^2}$$

Question: how to bound $\sqrt{\sum_{i=1}^{T-1} \langle a, \phi_i \rangle^2}$?

Optimality Proof

$$\sum_a \langle a, \phi_i \rangle^2 = 1 \text{ for all } i$$

↳ sum over all n -bit vectors, $\{a\}$

$$\text{So } \sum_{i=1 \text{ to } T-1} \sum_a \langle a, \phi_i \rangle^2 = T - 1$$

$$\sum_{i=1 \text{ to } T-1} \sum_a \langle a, \phi_i \rangle^2 = \sum_a \sum_i \langle a, \phi_i \rangle^2 = T - 1$$

Thus there exists an a such that

$$\sum_i \langle a, \phi_i \rangle^2 < \frac{T-1}{N}$$

what if
 $\forall a \sum_i \langle a, \phi_i \rangle^2 > \frac{T-1}{N}$
?

- Chose that a as our worst case for the algorithm.

Optimality Proof

$$\frac{1}{2} < t_{a,T} \leq 2\sqrt{T-1} \sqrt{\sum_{i=1}^{T-1} \langle a, \phi_i \rangle^2}$$

For the worst case a we chose:

$$\frac{1}{2} < t_{a,T} \leq 2\sqrt{T-1} \sqrt{\frac{T-1}{N}} = \frac{T-1}{\sqrt{N}}$$

We need to take $T = \Omega(\sqrt{N})$ as desired.

$$\begin{aligned} T-1 &> \sqrt{N}/2 \\ T &> \frac{\sqrt{N}}{2} + 1 \end{aligned}$$