



Visual Question Answering Models

Fall 2021



Overview

Introduction

Bottom-up and Top-down Attention Model

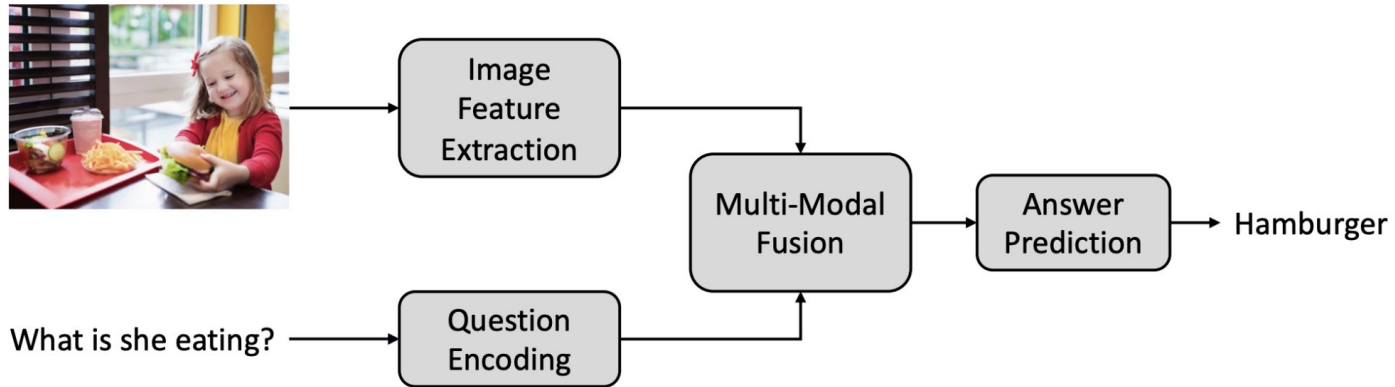
Vision Language Pre-training

Oscar Model

Grid Features vs Region Based Features

Without Convolution or Region Supervision

How does a typical VQA system work?





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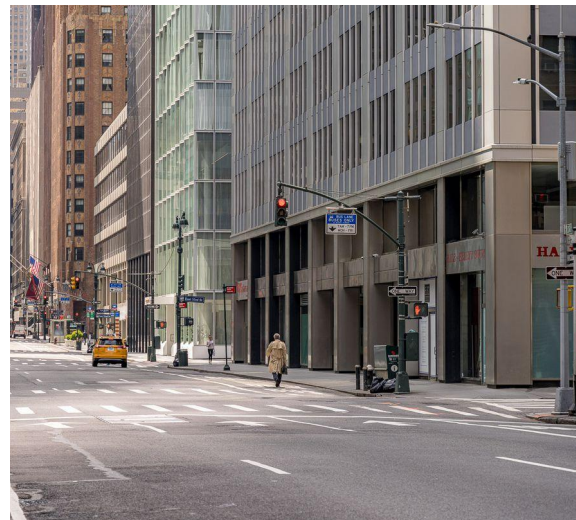
Grid Features vs Region Based Features

Without Convolution or Region Supervision

Visual Attention

Fine-grained visual processing is often essential for visual and language tasks.

Learn to focus on image regions related to the task.



Q: What color is the traffic light?

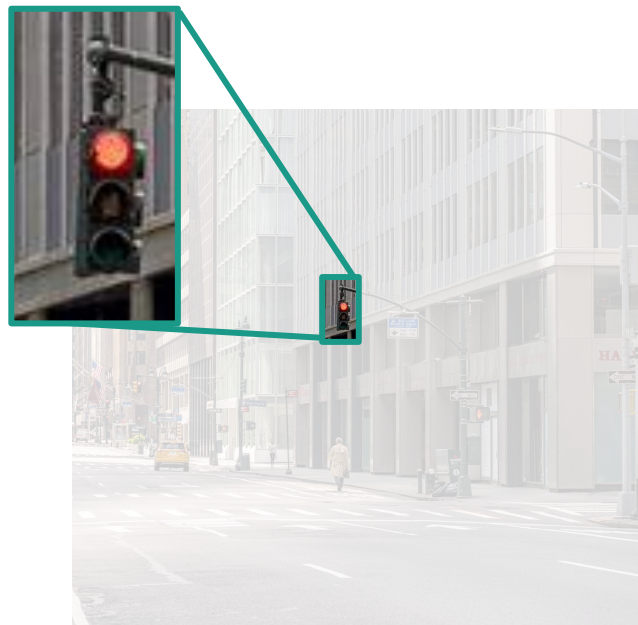
Image: metouhey.com

Bottom-up and top-down attention for image captioning and vqa. In CVPR. IEEE, 2018.

Visual Attention

Fine-grained visual processing is often essential for visual and language tasks.

Learn to focus on image regions related to the task.



Q: What color is the traffic light?

A: Red

Image: metouhey.com

Bottom-up and top-down attention for image captioning and vqa. In CVPR. IEEE, 2018.

Visual Attention

Fine-grained visual processing is often essential for visual and language tasks.

Learn to focus on image regions related to the task.



Q: Is the child holding a bottle or a can?

Image: visualqa.org

Bottom-up and top-down attention for image captioning and vqa. In CVPR. IEEE, 2018.

Visual Attention

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Learn to focus on image regions related to the task.



Q: Is the child holding a bottle or a can?

A: Bottle

Image: visualqa.org

Bottom-up and top-down attention for image captioning and vqa. In CVPR. IEEE, 2018.



Visual Attention

Learn to focus on image regions related to the task.

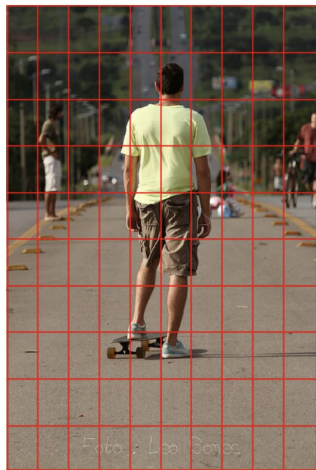
attended feature ← $\hat{v} = f(h, V)$

1. Set of attention candidate

2. Text content representation

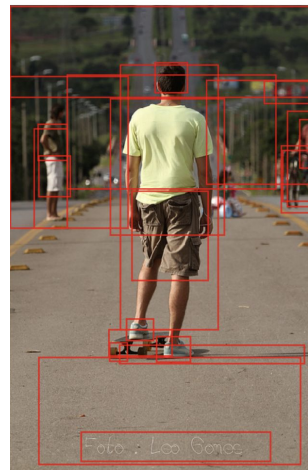
3. Learned attention function

Attention Candidates



Spatial output of a CNN
 $V = \{v_1, \dots, v_{100}\}$

10 x 10 grids



Object-based attention
 $V = \{v_1, \dots, v_k\}$

k regions

Visual Attention

Enabling attention to be calculated at the level of objects and other salient image regions.

It is the natural basis for attention to be considered.

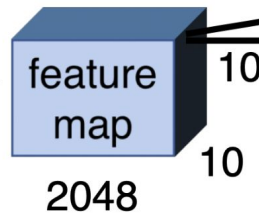
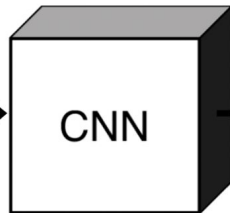
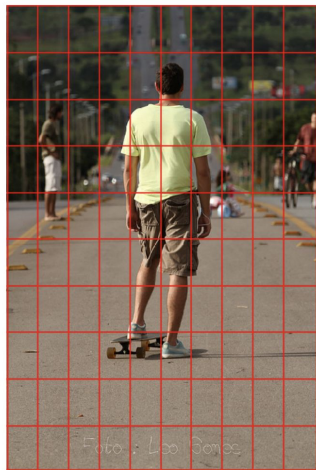


C: A **young man** on a **skateboard** looking down **street** with **people** watching.

Q: Is the **boy** in the **yellow shirt** wearing **head protective gear**?

A: No

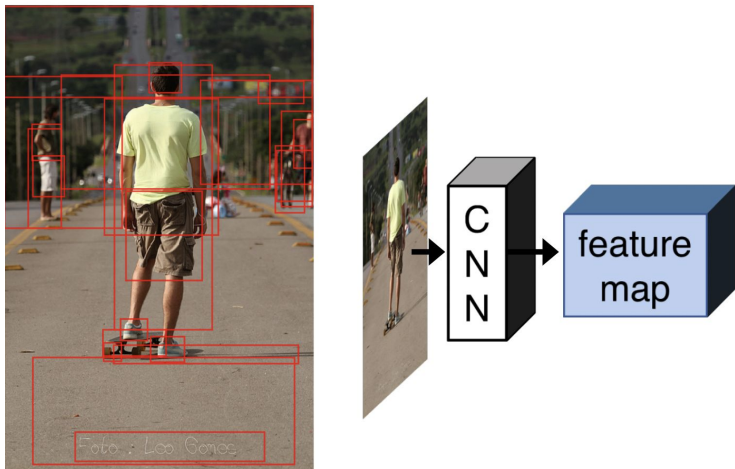
Spatial output of a CNN



$$V = \{v_1, \dots, v_{100}\}$$

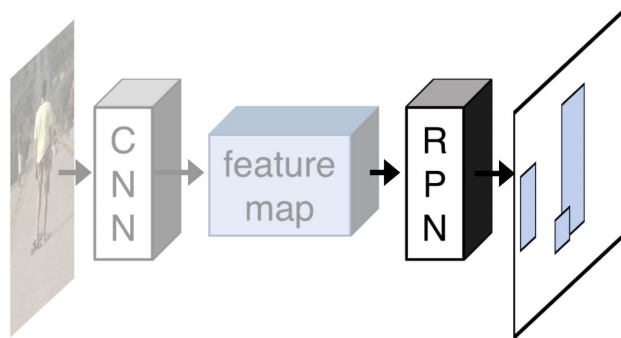
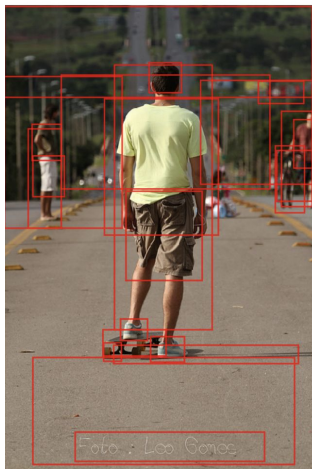
Bottom-up and top-down attention for image captioning and vqa. In CVPR. IEEE, 2018.

Bottom-Up Attention - Fast R-CNN



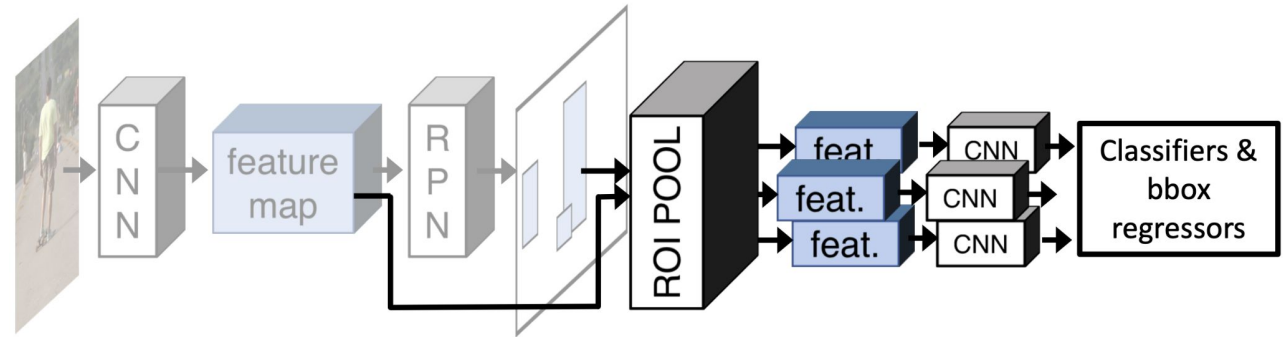
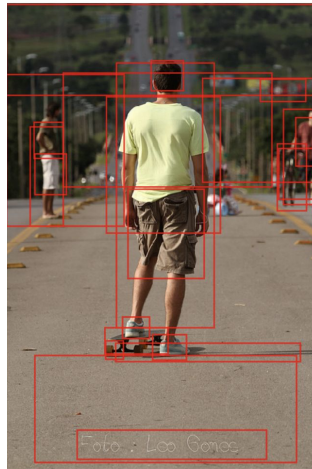
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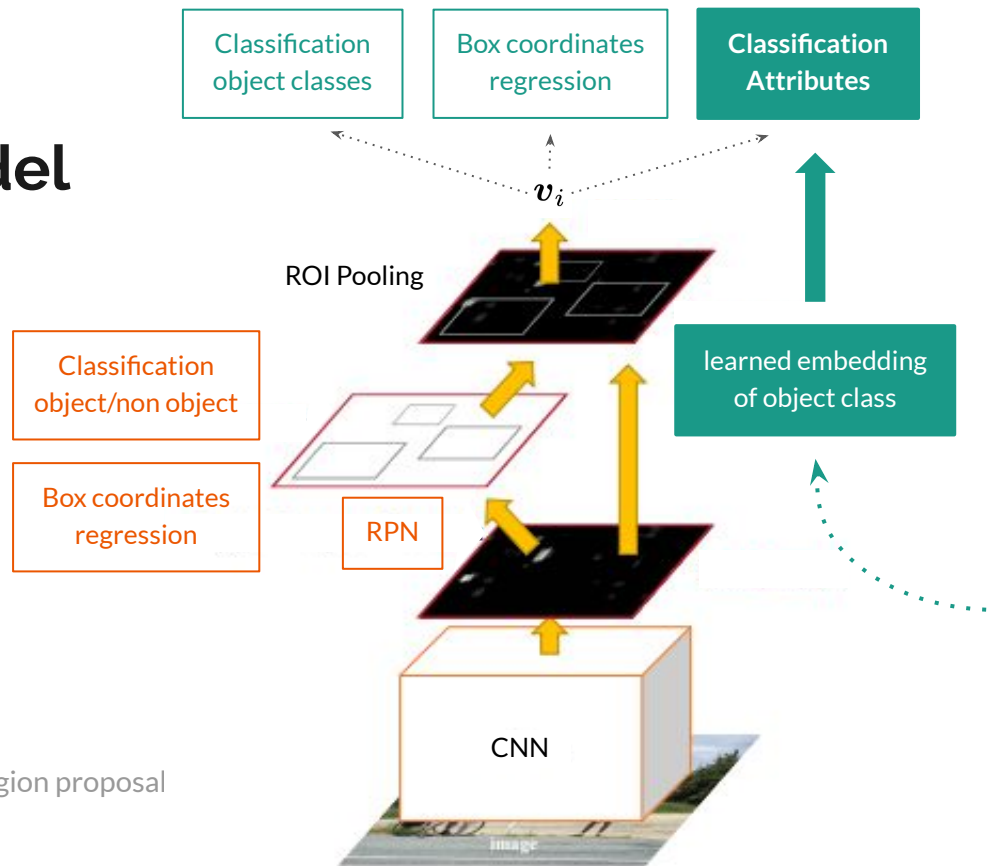
Bottom-up and top-down attention for image captioning and vqa. In CVPR. IEEE, 2018.

Bottom-up Attention Model

For each selected region i , v_i is defined as the mean-pooled convolutional feature from this region.

The original Faster R-CNN multi-task loss function contains four components. They add an additional multi-class loss component to train the attribute predictor.

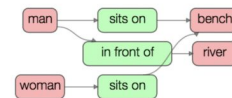
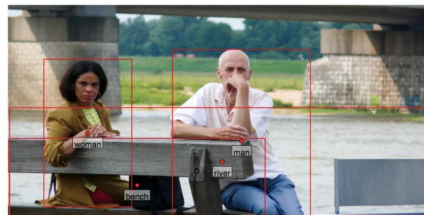
Faster R-CNN: Towards real-time object detection with region proposal networks. In NIPS, 2015



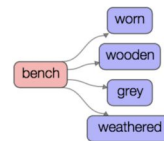
Pre-training Visual Genome Dataset

Visual Genome is a dataset, a knowledge base, an ongoing effort to connect structured image concepts to language.

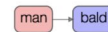
To aid the learning of good feature representations, we add an additional training output for predicting attribute classes (in addition to object classes).



A man and a woman sit on a park bench along a river.



Park bench is made of gray weathered wood



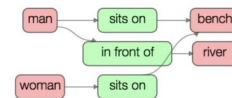
The man is almost bald

Visual genome: Connecting language and vision using crowdsourced dense image annotations. In arXiv, 2016.

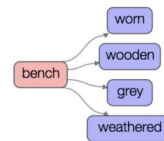
Pre-training Visual Genome Dataset

1600 Object classes.

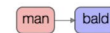
400 Attribute classes.



A man and a woman sit on a park bench along a river.

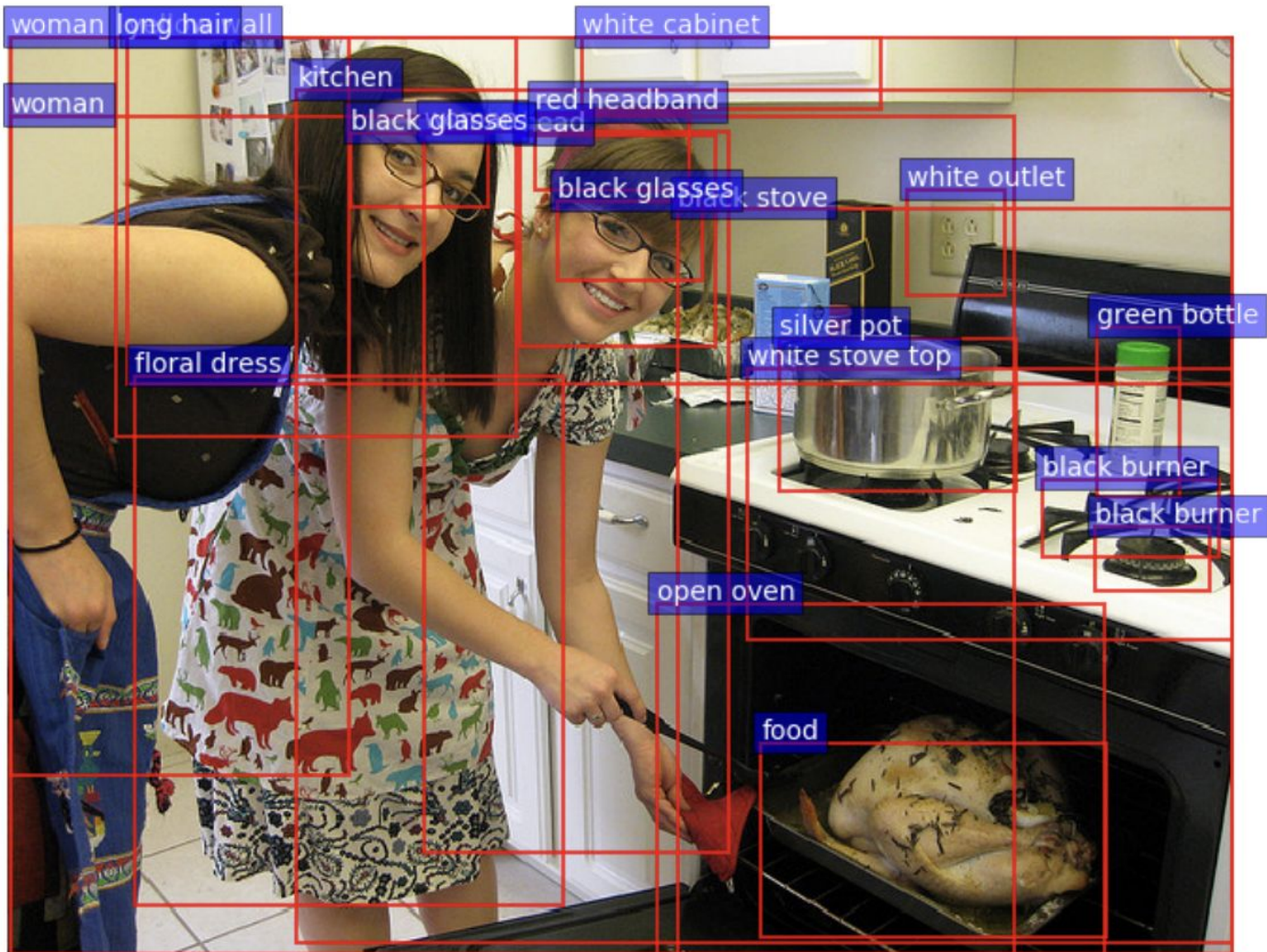


Park bench is made of gray weathered wood



The man is almost bald

Visual genome: Connecting language and vision using crowdsourced dense image annotations. In arXiv preprint arxiv:1602.07332, 2016.



woman long hair all

white cabinet

woman

kitchen

red headband

black glasses

black glasses

stove

white outlet

floral dress

silver pot

green bottle

white stove top

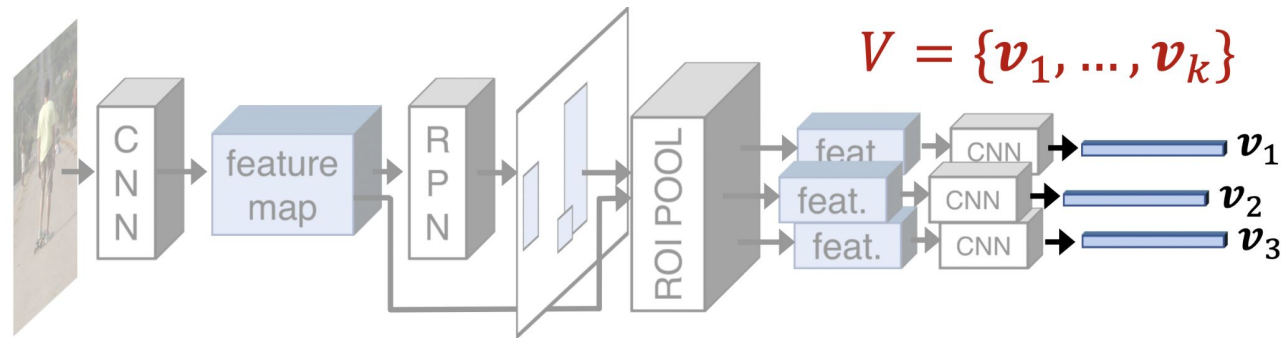
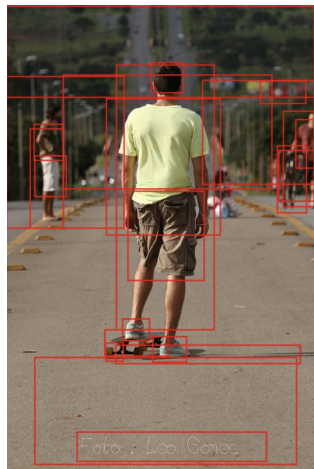
black burner

black burner

open oven

food

Bottom-Up Attention - Fast R-CNN



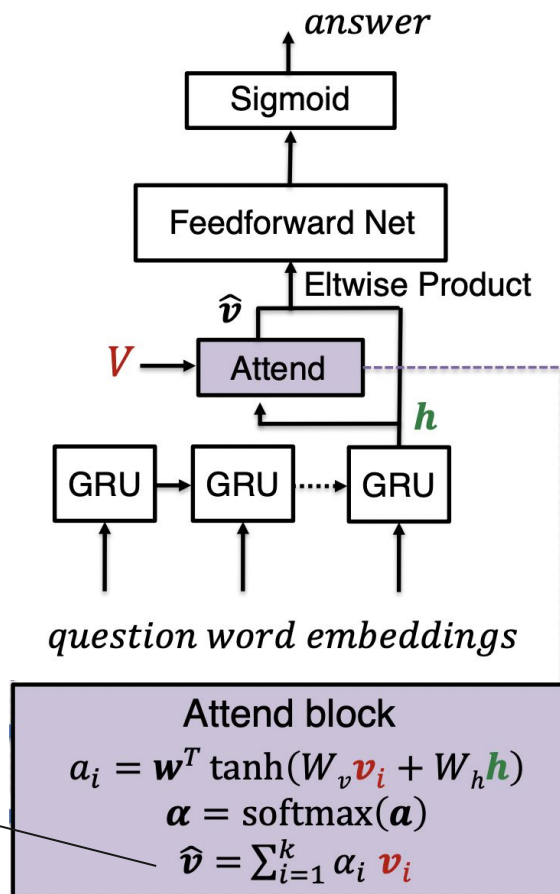
Bottom-up and top-down attention for image captioning and vqa. In CVPR. IEEE, 2018.

VQA Model

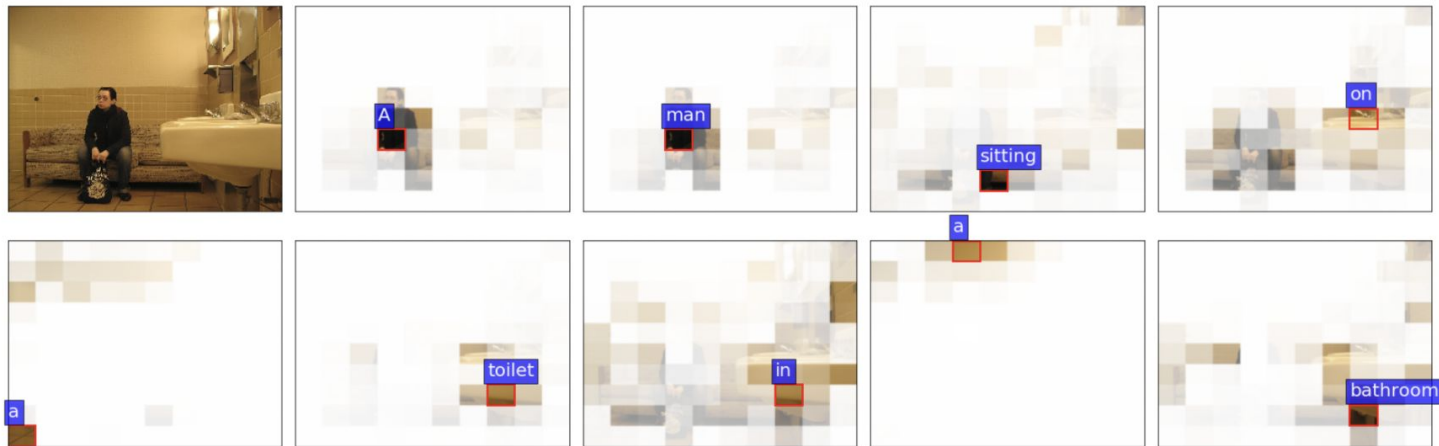
Given a set of spatial image features V , their proposed VQA model also uses a 'soft' top-down attention mechanism to weight each feature, using the question representation as context.

$$\hat{v} = f(h, V)$$

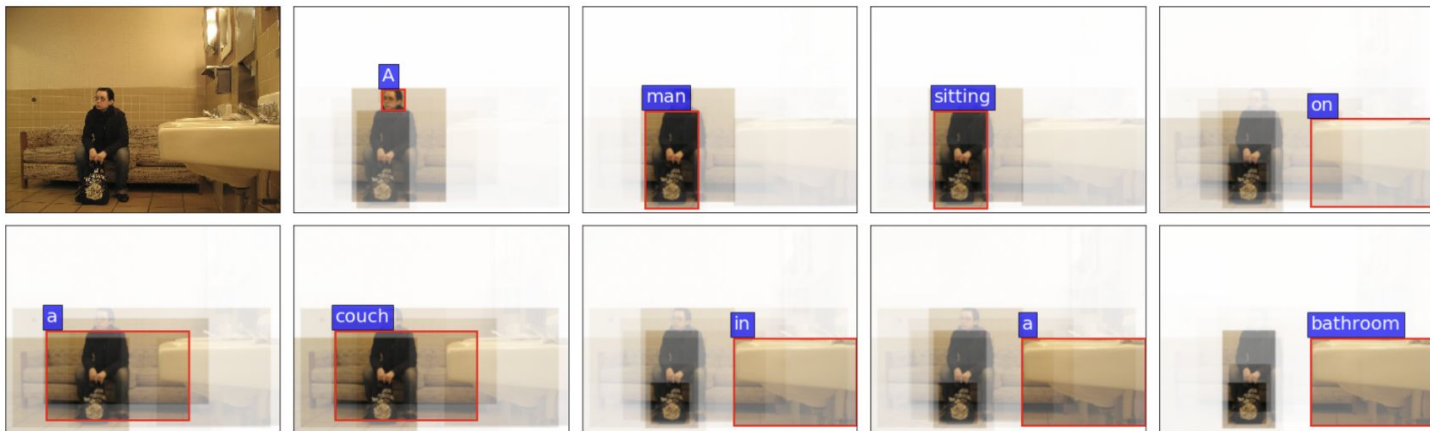
Bottom-up and top-down attention for image captioning and vqa.
In CVPR. IEEE, 2018.



ResNet (10x10): A man sitting on a **toilet** in a bathroom.



Up-Down (Ours): A man sitting on a **couch** in a bathroom.

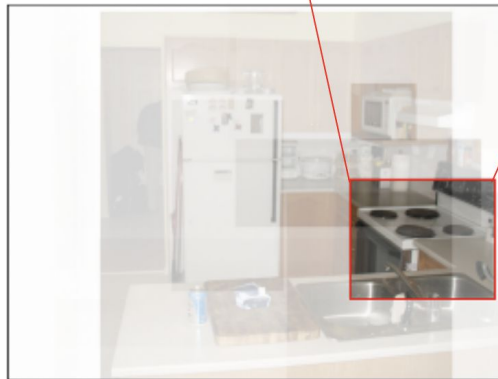


VQA examples

Q: What room are they
in?



A: **kitchen**

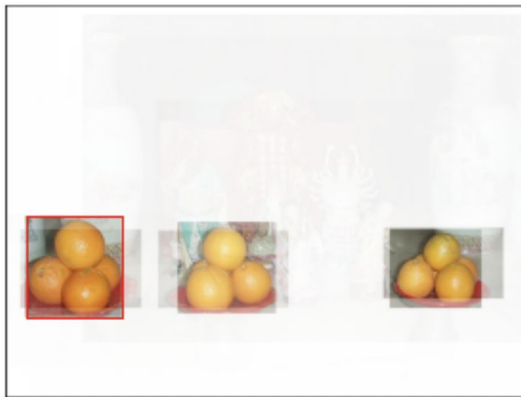


Bottom-up and top-down attention for image captioning and vqa. In CVPR. IEEE, 2018.

VQA examples - Counting

Q: How many oranges
are on pedestals?

A: ~~two~~

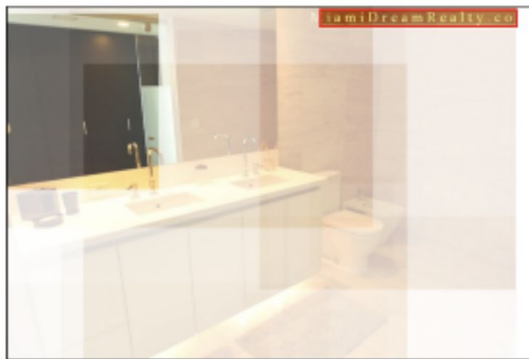


Bottom-up and top-down attention for image captioning and vqa. In CVPR. IEEE, 2018.

VQA examples - Reading

Q: What is the name of
the realty company?

A: **none**



Bottom-up and top-down attention for image captioning and vqa. In CVPR. IEEE, 2018.



Results

VQA v2 val set (single-model):

	Yes/No	Number	Other	Overall
ResNet (1×1)	76.0	36.5	46.8	56.3
ResNet (14×14)	76.6	36.2	49.5	57.9
ResNet (7×7)	77.6	37.7	51.5	59.4
Up-Down (Ours)	80.3	42.8	55.8	63.2

+4%

Bottom-up and top-down attention for image captioning and vqa. In CVPR. IEEE, 2018.



Benefits

Natural approach

Unifies vision & language tasks with object detection models

Transfer learning by pre-training on object detection datasets

Complementary to other models (just swap attention candidates)

Can be fine-tuned

Bottom-up and top-down attention for image captioning and vqa. In CVPR. IEEE, 2018.



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Vision Language Pre-training

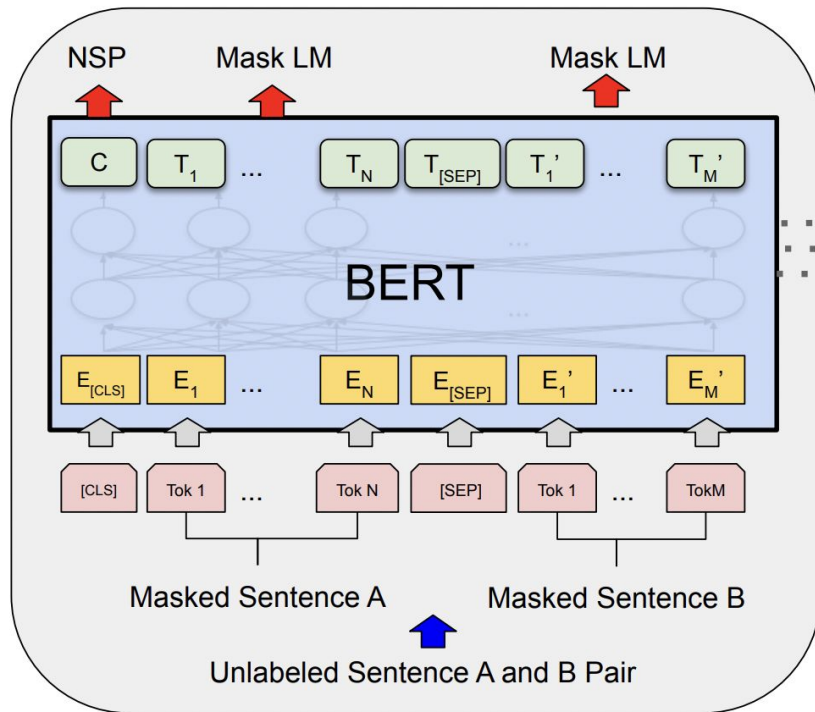
One of the important factors for performance improvement is pre-training on massive amounts of datasets.

IMGENET

BERT
(Devlin et al, 2018)

Google's Conceptual
Captions

www.microsoft.com/en-us/research/publication/oscar-object-semantics-aligned-pre-training-for-vision-language-tasks/

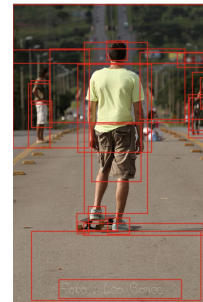
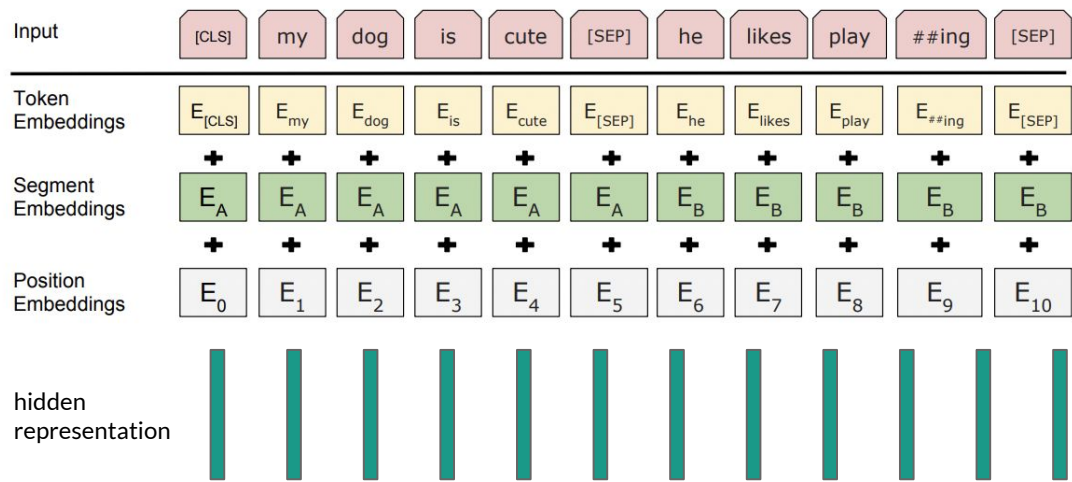


Masked Language Model (MLM)

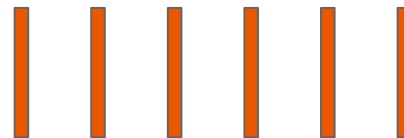
input: regular sentence with [MASK] token

output: hidden representation of [MASK]

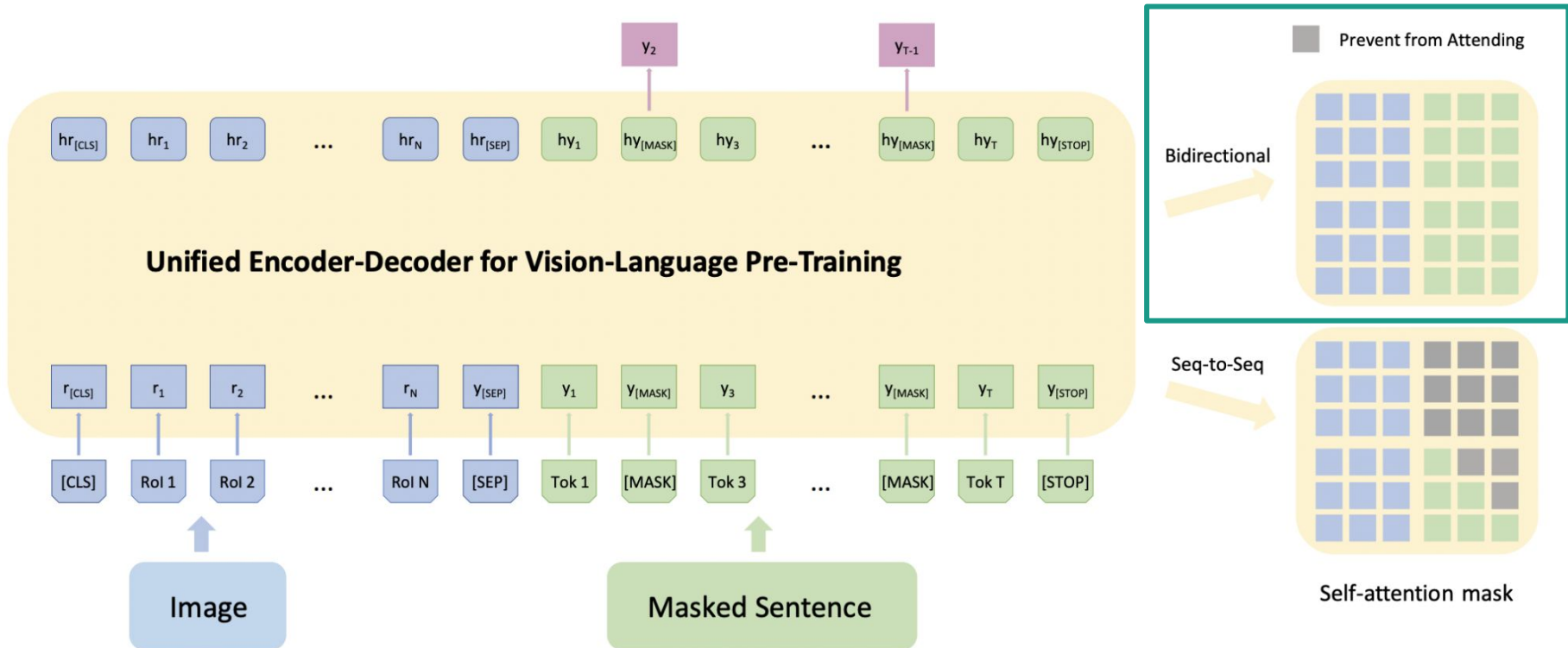
objective: predict vocabulary ID



ROI features + linear transform



Transformer



www.microsoft.com/en-us/research/publication/oscar-object-semantic-aligned-pre-training-for-vision-language-tasks/
 Unified Vision-Language Pre-Training for Image Captioning and VQA. In AAAI, 2020.



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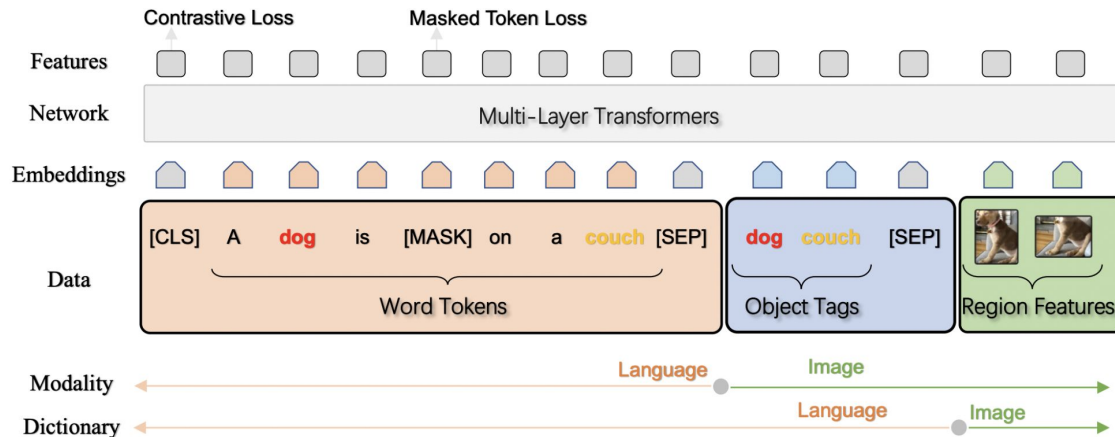
Grid Features vs Region Based Features

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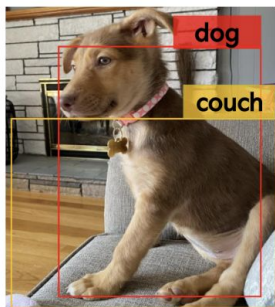
OSCAR Model

Objects tags is a language representation of visual concepts.

This is the key reason why OSCAR outperforms previous methods.

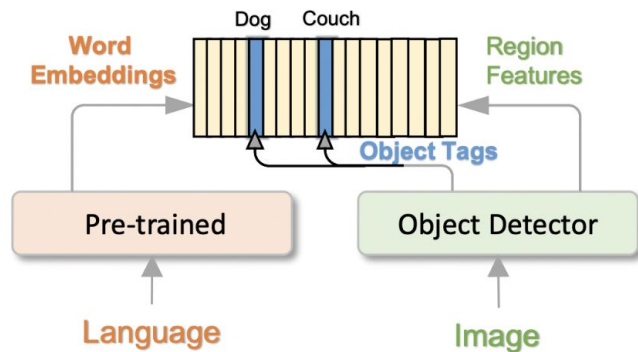


OSCAR Model

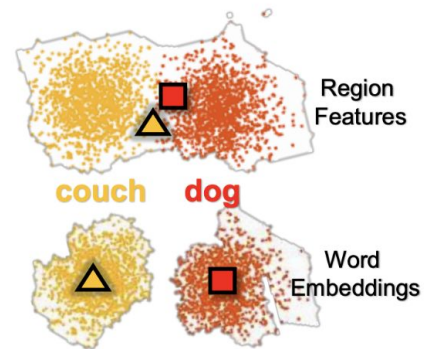


A **dog** is sitting on a **couch**

(a) Image-text pair

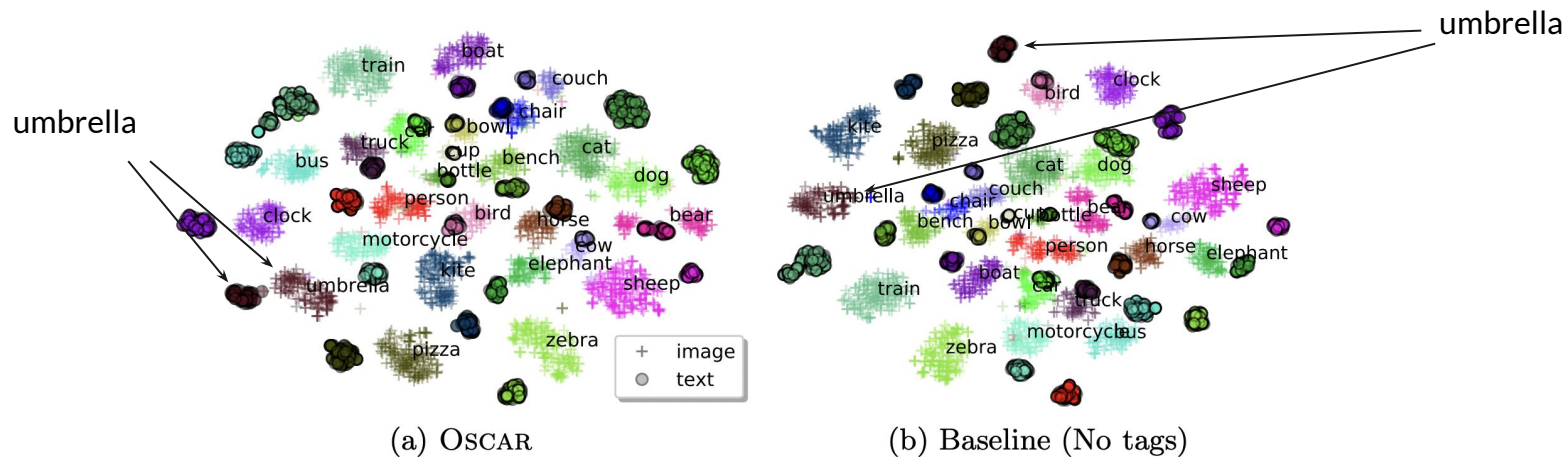


(b) Objects as anchor points



(c) Semantics spaces

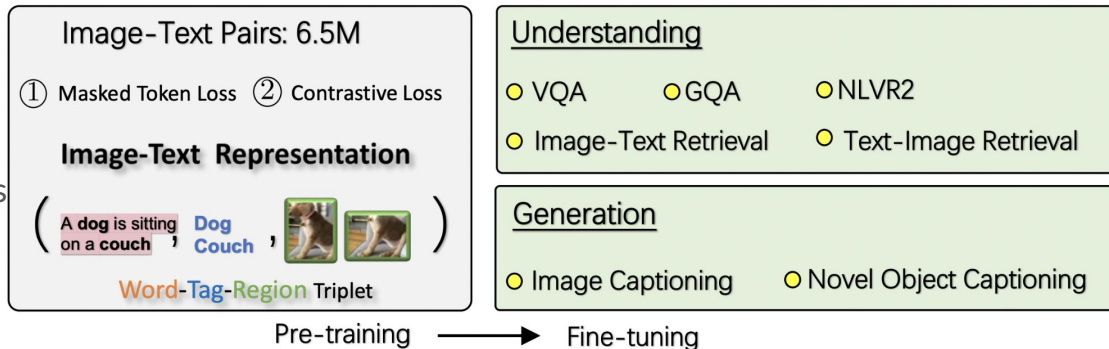
OSCAR Model - Feature space visualization



OSCAR Model

A masked token loss over words & tags

A contrastive loss between tags and others.





Dataset

Table 5: Statistics of the pre-training corpus.

Source	COCO (train)	CC (all)	SBU (all)	Flicker30k (train)	VQA (train)	GQA (bal-train)	VG-QA (train)	Total
Image/Text	112k/560k	3.0M/3.0M	840k/840k	29k/145k	83k/444k	79k/1026k	48k/484k	4.1M/6.5M

Oscar model is pre-trained on a large-scale V+L dataset composed of 6.5 million pairs



Contrastive Loss

a contrastive loss for the modality view, which measures the model's capability of distinguishing an original triple and its "polluted" version (that is, where an original object tag is replaced with a randomly sampled one).

$$\mathcal{L}_C = -\mathbb{E}_{(\mathbf{h}', \mathbf{w}) \sim \mathcal{D}} \log p(y | f(\mathbf{h}', \mathbf{w}))$$



Masked Token Loss

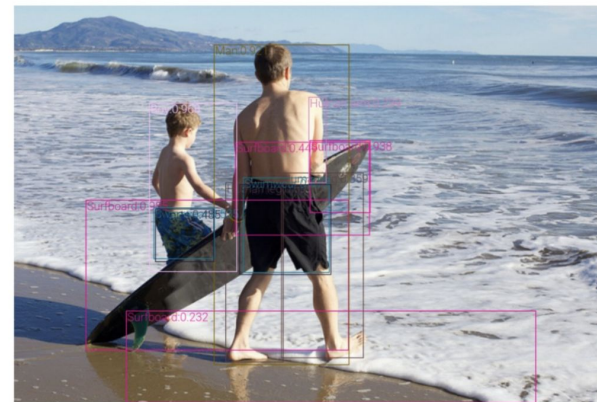
a masked token loss for the dictionary view, which measures the model's capability of recovering the masked element (word or object tag) based on its context

$$\mathcal{L}_{\text{MTL}} = -\mathbb{E}_{(\mathbf{v}, \mathbf{h}) \sim \mathcal{D}} \log p(h_i | \mathbf{h}_{\setminus i}, \mathbf{v})$$

VinVL: Revisiting Visual Representations in Vision-Language Models

VinVL captures much richer image semantics

datarelease.blob.core.windows.net/tutorial/VQA2VLN2021/VLP_part1.pdf
VinVL: Revisiting Visual Representations in Vision-Language Models. In CVPR, 2021



X152-FPN model trained on OpenImages



X152-C4 model trained on four public object detection datasets

Visual feature	VQA		GQA		Image Captioning				NoCaps		Image Retrieval			Text Retrieval			NLVR2	
	test-dev	test-std	test-dev	test-std	B@4	M	C	S	C	S	R@1	R@5	R@10	R@1	R@5	R@10	dev	test-P
Anderson <i>et al.</i> [2]	73.16	73.44	61.58	61.62	40.5	29.7	137.6	22.8	86.58	12.38	54.0	80.8	88.5	70.0	91.1	95.5	78.07	78.36
Ours	75.95	76.12	65.05	64.65	40.9	30.9	140.6	25.1	92.46	13.07	58.1	83.2	90.1	74.6	92.6	96.3	82.05	83.08
Δ	2.79 \uparrow	2.68 \uparrow	3.47 \uparrow	3.03 \uparrow	0.4 \uparrow	1.2 \uparrow	3.0 \uparrow	2.3 \uparrow	5.9 \uparrow	0.7 \uparrow	4.1 \uparrow	2.4 \uparrow	1.6 \uparrow	4.6 \uparrow	1.5 \uparrow	0.8 \uparrow	3.98 \uparrow	4.71 \uparrow

Table 1: Uniform improvements on seven VL tasks by replacing visual features from Anderson *et al.* [2] with ours. The NoCaps baseline is from VIVO [9], and our results are obtained by directly replacing the visual features. The baselines for rest tasks are from OSCAR [21], and our results are obtained by replacing the visual features and performing OSCAR+ pre-training. All models are BERT-Base size. As analyzed in Section 5.2, the new visual features contributes 95% of the improvement.

Visual feature matter!



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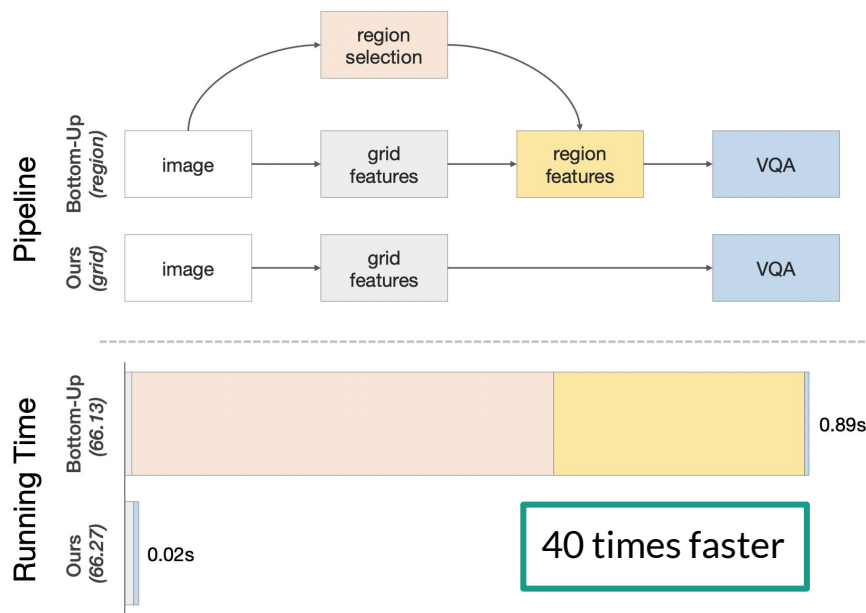
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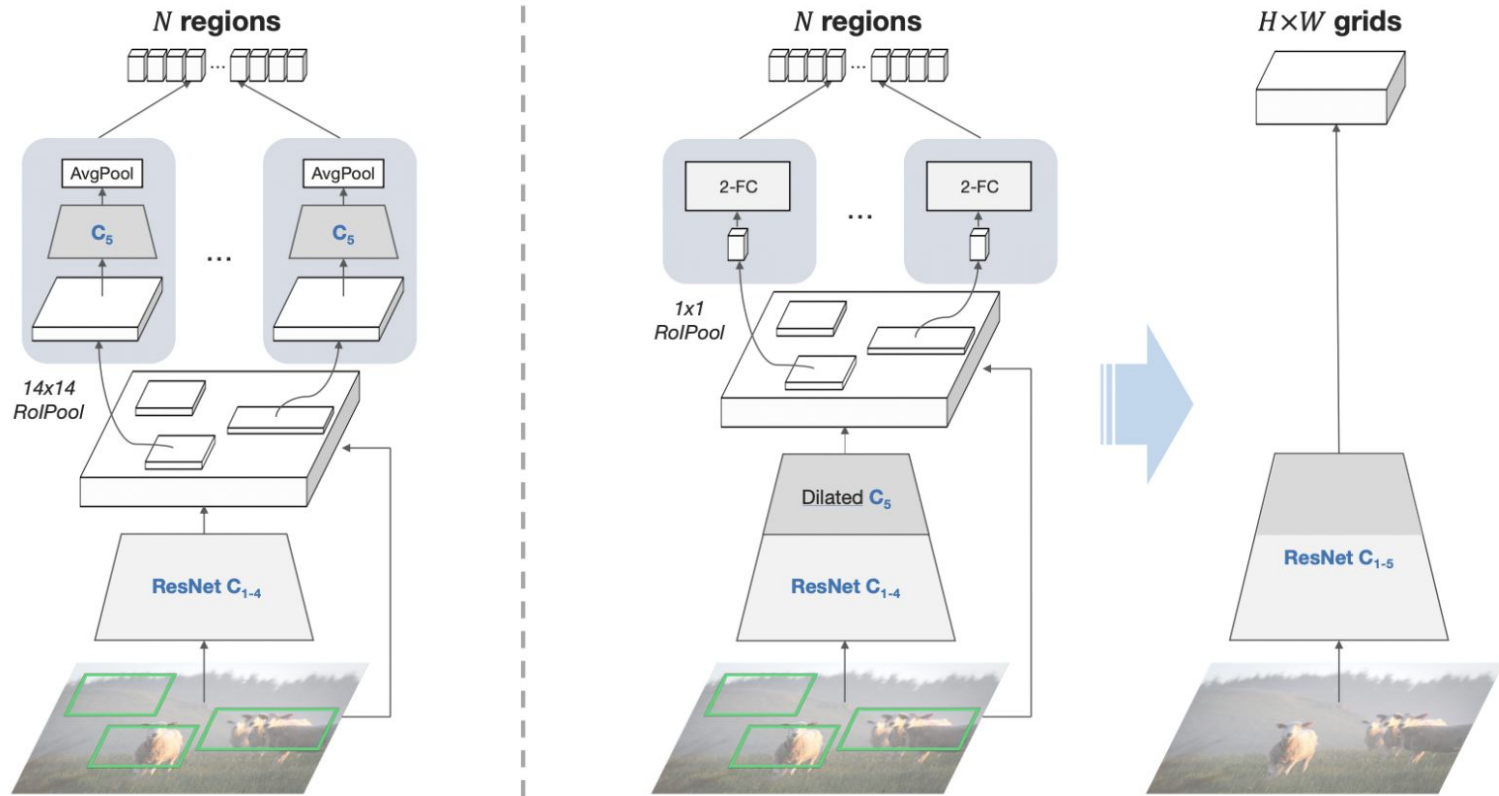
**Grid Features vs Region Based
Features**

Without Convolution or Region Supervision


In Defense of Grid Features for Visual Question Answering

Using grid features is fast, and it can achieve comparable performance with regional features.






In Defense of Grid Features for Visual Question Answering. In CVPR, 2020.



In Defense of Grid Features for Visual Question Answering


Why previous methods based on grid features cannot outperform **Bottom-Up and Top-Down Attention** features?



In Defense of Grid Features for Visual Question Answering

Why previous methods based on grid features cannot outperform **Bottom-Up and Top-Down Attention** features?

1. **Pre-training task**
2. **Input image size**



In Defense of Grid Features for Visual Question Answering

	accuracy	time (ms)
Pythia [16]	68.31	-
R	68.21	929
G	67.76	39

(a)

	accuracy	time (ms)
MCAN [50]	70.93	-
R	72.01	963
G	72.59	72

(b)

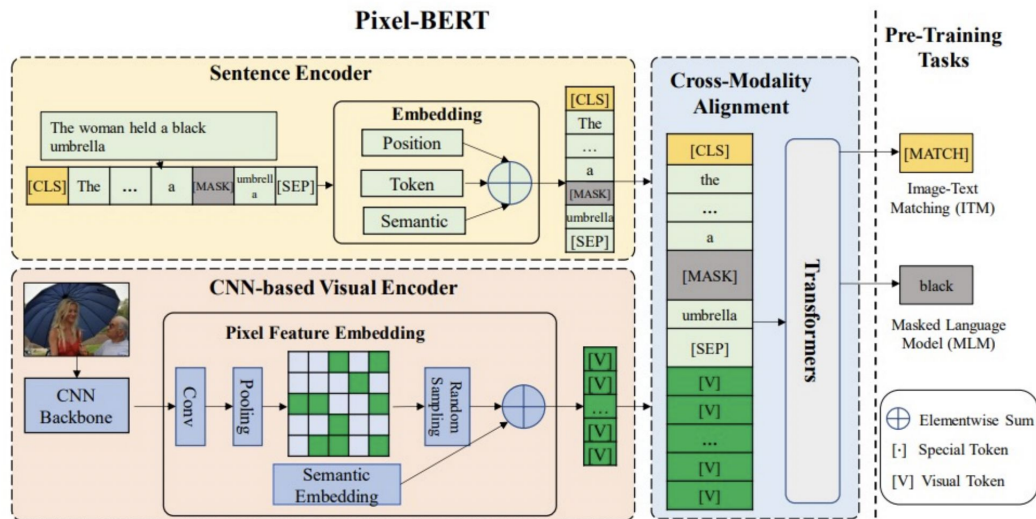
	accuracy	time (ms)
Pythia [16]	54.22	-
R	54.28	874
G	54.17	38

(c)

	B4	M	C	S	time (ms)
BUTD [2]	36.2	27.0	113.5	20.3	-
R	36.2	27.7	113.9	20.8	1101
G	36.4	27.4	113.8	20.7	240

(d)

Pixel-BERT: An E2E Pre-training Framework



datarelease.blob.core.windows.net/tutorial/VQA2VLN2021/VLP_part1.pdf

Pixel-BERT: Aligning Image Pixels with Text by Deep Multi-Modal Transformers. In arXiv, 2020



From grid features to region features, and to grid features again?



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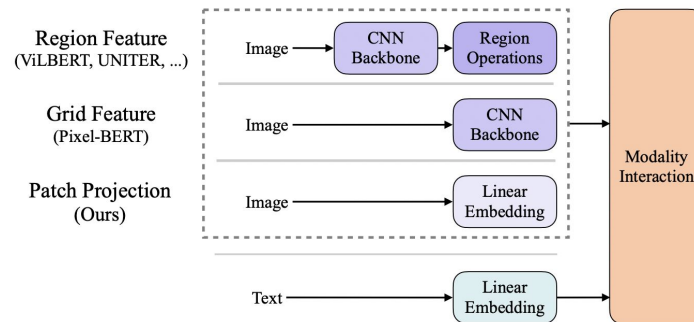
Grid Features vs Region Based Features

**Without Convolution or Region
Supervision**

ViLT: Without Convolution or Region Supervision

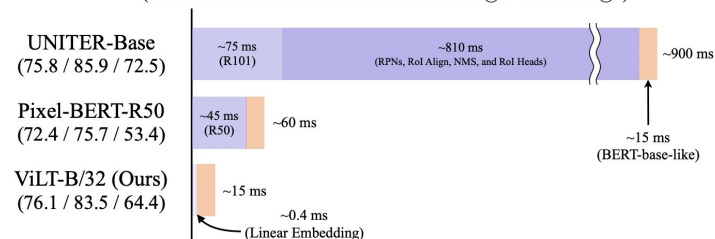
ViLT is very fast since both object detection models and CNNs are not used.

Visual Embedding Schema



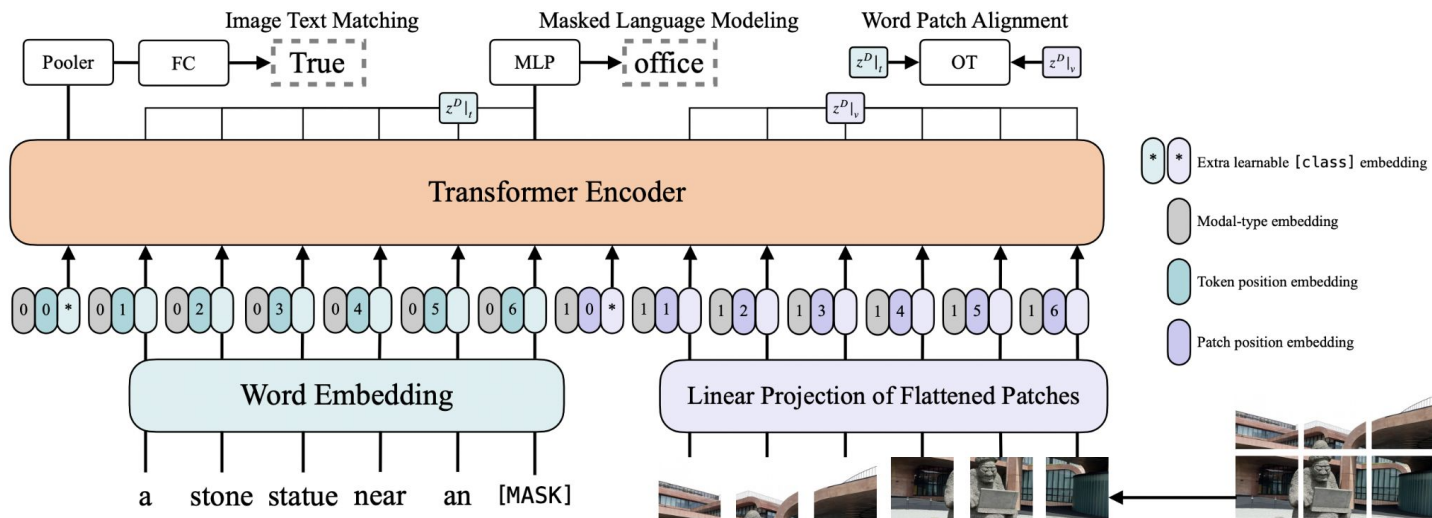
Running Time

(Performances : NLVR2 test-P Acc. / F30K TR R@1 / F30K IR R@1)

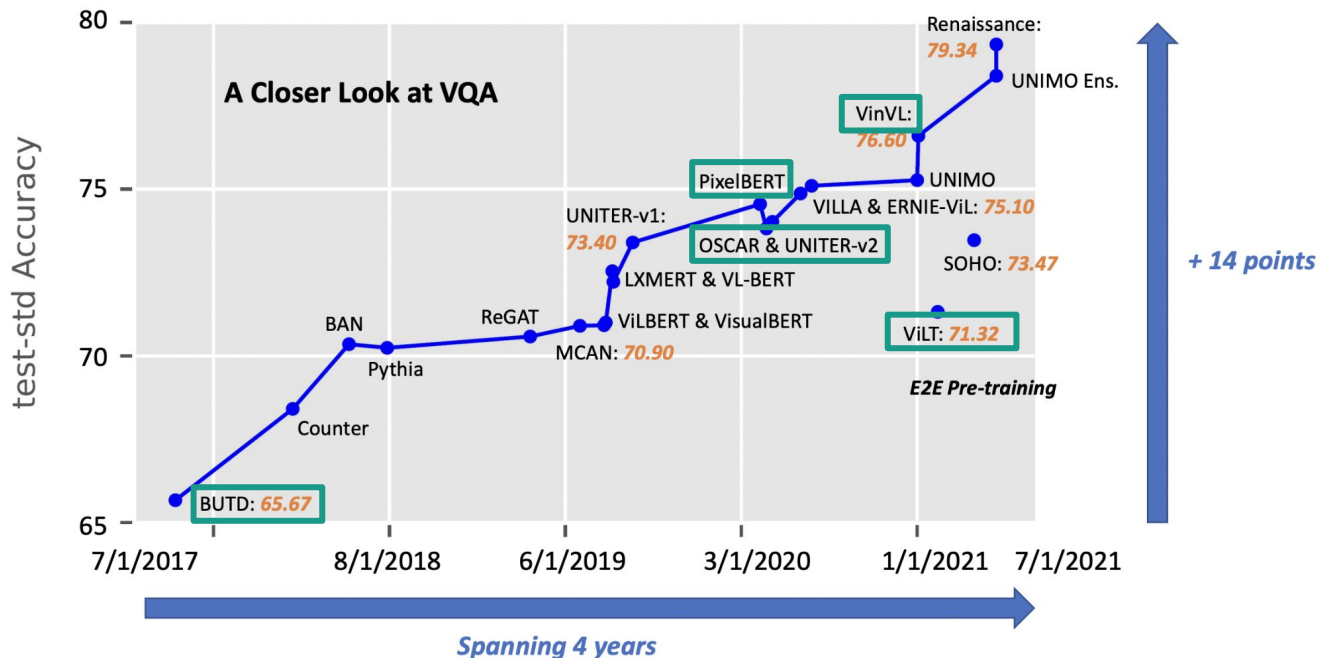


datarelease.blob.core.windows.net/tutorial/VQA2VLN2021/VLP_part1.pdf

ViLT: Vision-and-Language Transformer Without Convolution or Region Supervision. In ICML, 2021



A single unified transformer is learned



However, performance-wise, it is still not ideal!

Thank you! Any Questions?





References

Papers:

- Bottom-up and top-down attention for image captioning and vqa. In CVPR. IEEE, 2018.
- Faster R-CNN: Towards real-time object detection with region proposal networks. In NIPS, 2015
- ViLT: Vision-and-Language Transformer Without Convolution or Region Supervision. In ICML, 2020
- In Defense of Grid Features for Visual Question Answering. In CVPR, 2020.
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