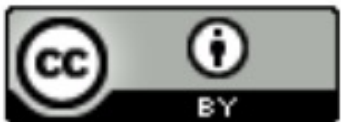


Convolutional Neural Networks

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University of Colorado Boulder

Spring 2022



Review

- Last class:
 - Universal approximation theorem
 - Selecting model capacity: avoid overfitting and underfitting
 - Selecting model hyperparameters
 - Learning efficiently: optimization methods
 - Programming tutorial
- Assignments (Canvas):
 - Lab assignment 1 due earlier today
 - Problem set 2 due next week
- Questions?

Today's Topics

- Neural Networks for Spatial Data
- History of Convolutional Neural Networks (CNNs)
- CNNs – Convolutional Layers
- CNNs – Pooling Layers

Today's Topics

- Neural Networks for Spatial Data
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- CNNs – Pooling Layers

What is Spatial Data?

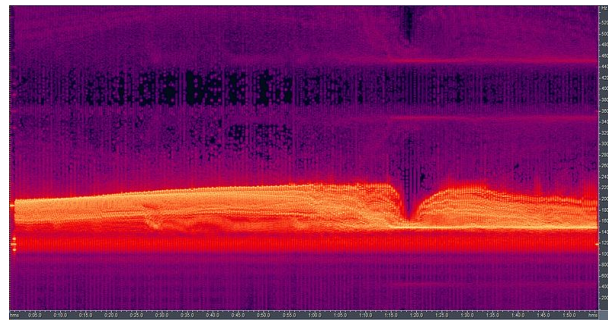
- Data where the order matters; e.g.,

2D

Images



Audio (spectrogram)



Text (word embeddings)

I
like
learning
about
deep
learning

3D

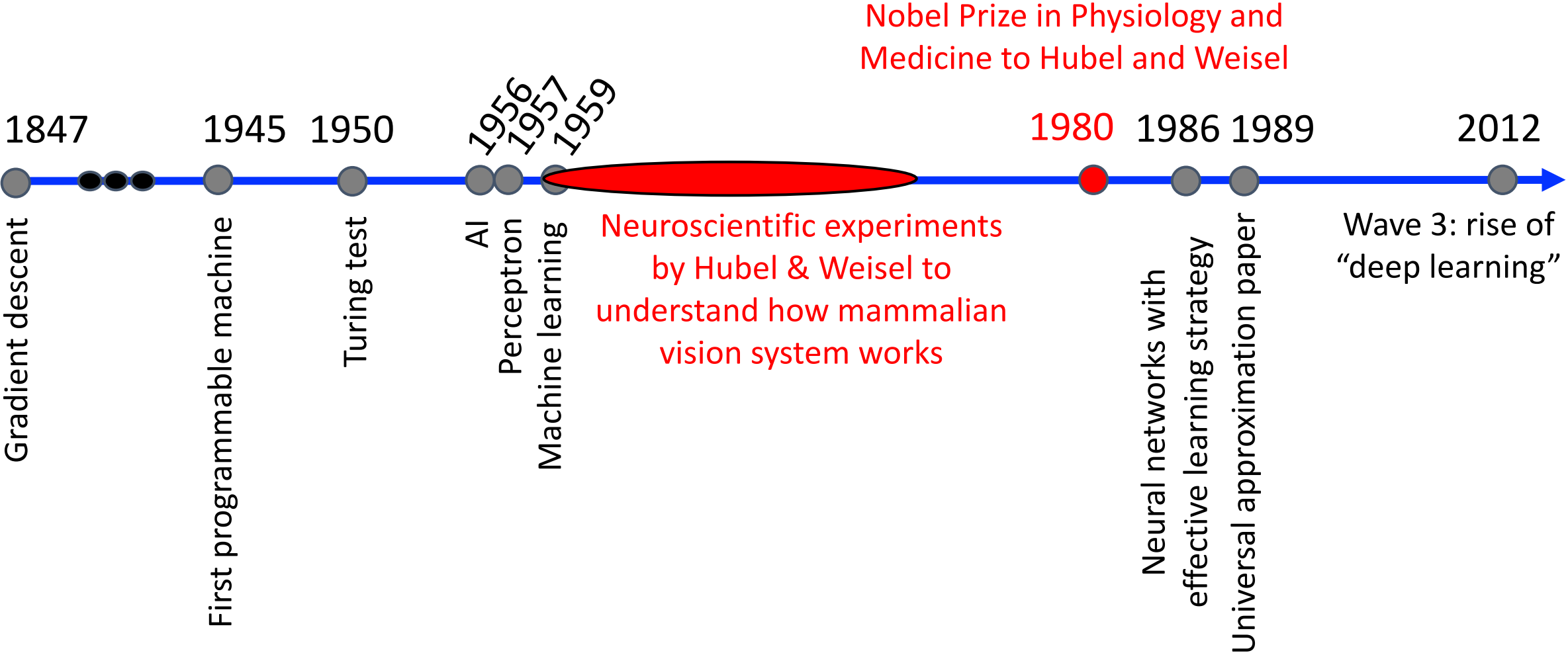
Video



Today's Topics

- Neural Networks for Spatial Data
- **History of Convolutional Neural Networks (CNNs)**
- CNNs – Convolutional Layers
- CNNs – Pooling Layers

Historical Context: Inspiration

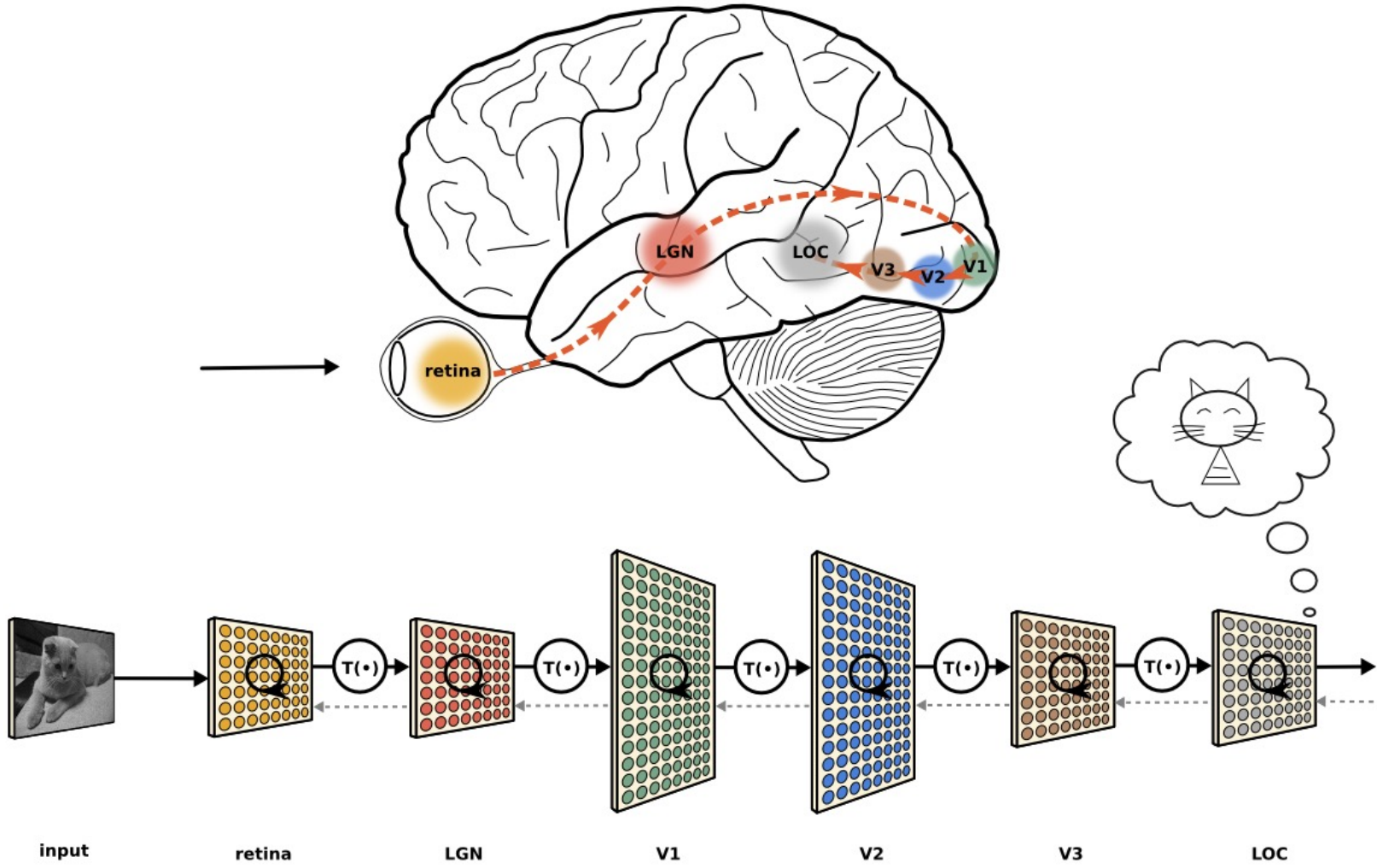


Motivation: How Vision System Works



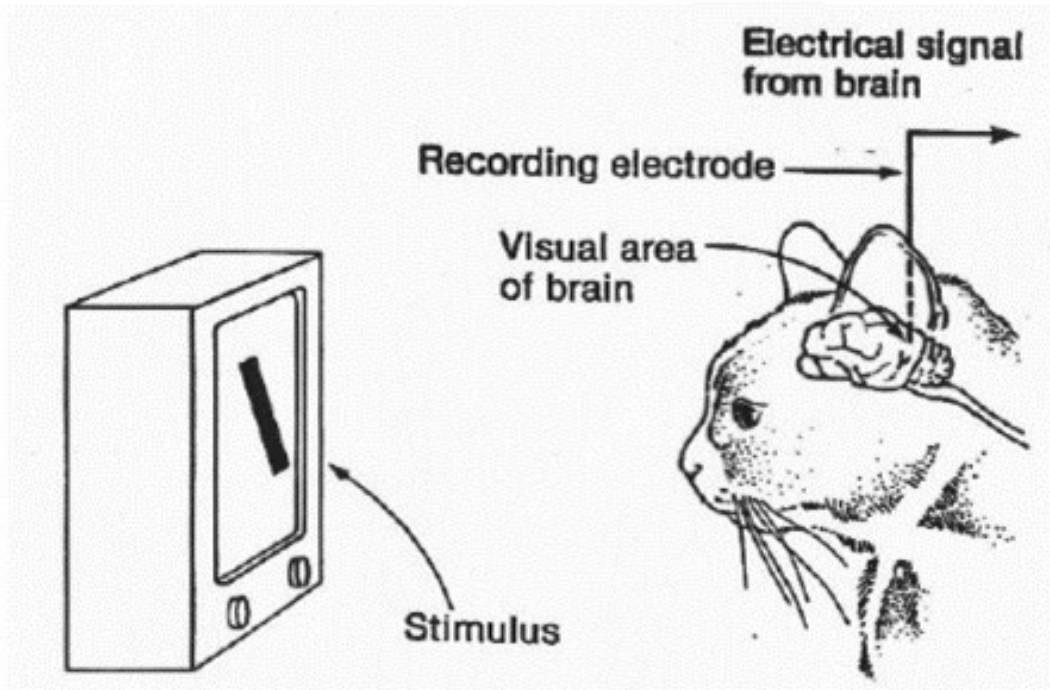
Image Source: <https://braintour.harvard.edu/archives/portfolio-items/hubel-and-wiesel>

Motivation: How Vision System Works



Motivation: How Vision System Works

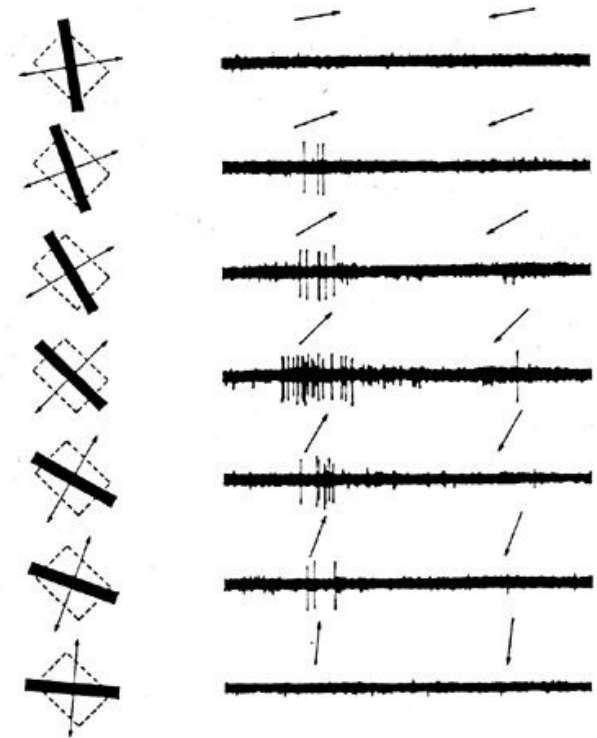
Experiment Set-up:



<https://www.esantus.com/blog/2019/1/31/convolutional-neural-networks-a-quick-guide-for-newbies>

Key Finding: initial neurons responded strongly only when light was shown in certain orientations

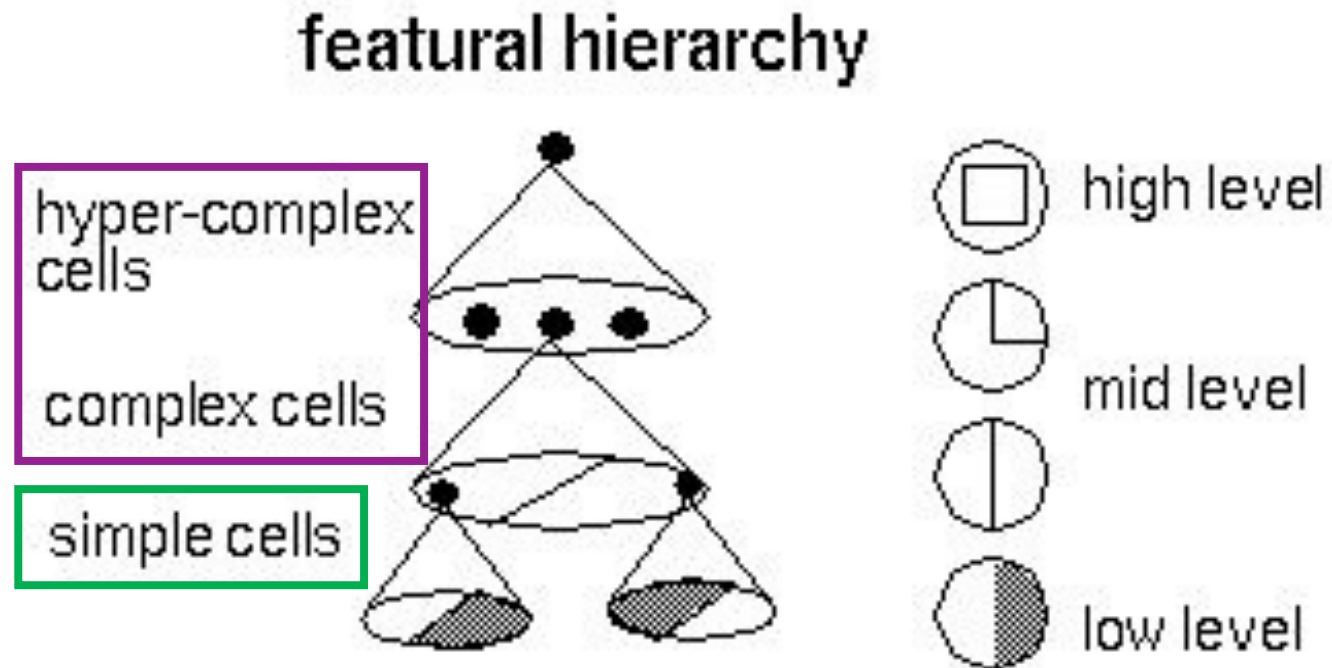
V1 physiology:
direction
selectivity



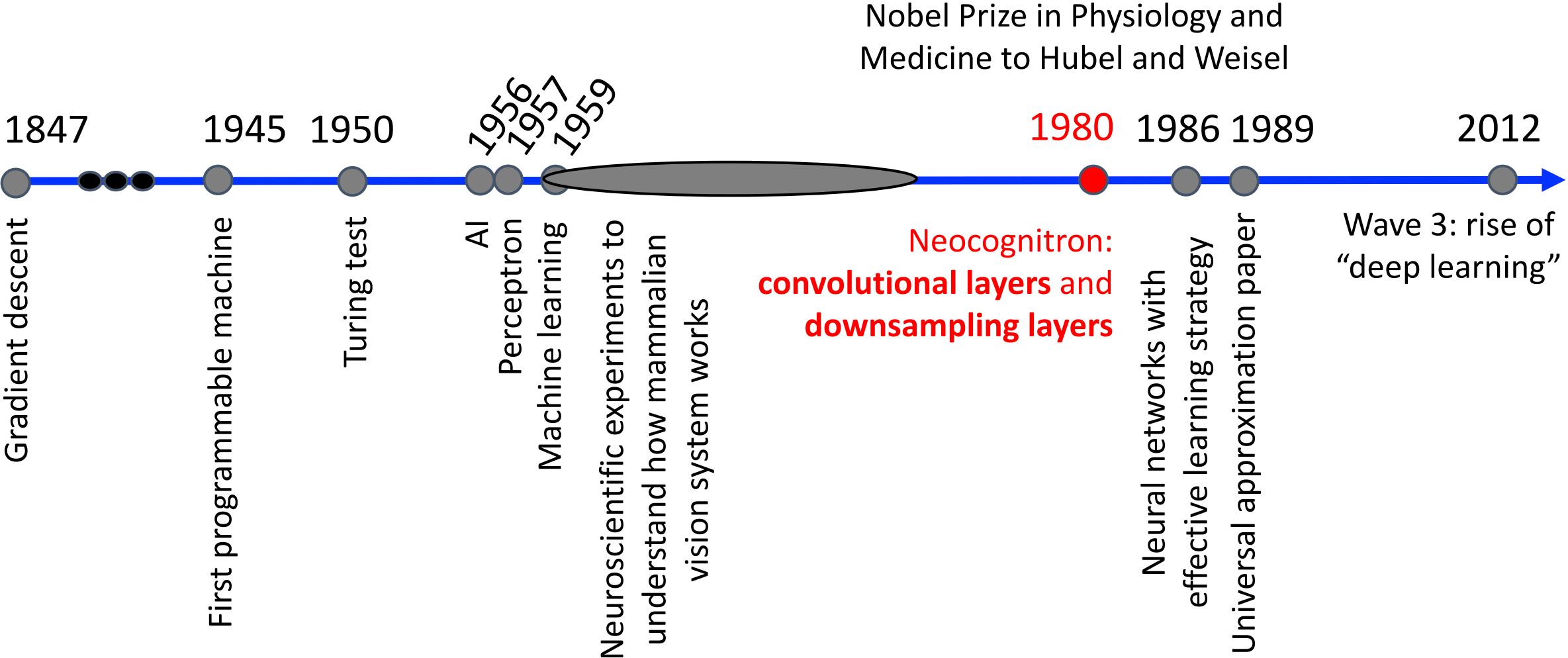
<https://www.cns.nyu.edu/~david/courses/perception/lecturenotes/V1/lgn-V1.html>

Motivation: How Vision System Works

Key Idea: cells are organized as a hierarchy of feature detectors, with **higher level features** responding to patterns of activation in **lower level cells**



Historical Context: Key Ingredients



Neocognitron: Key Ingredients



<http://personalpage.flsi.or.jp/fukushima/index-e.html>

“In this paper, we discuss how to synthesize a neural network model in order to endow it an ability of pattern recognition like a human being... the network acquires a similar structure to the hierarchy model of the visual nervous system proposed by Hubel and Wiesel.”

- Fukushima, Neocognitron: A Self-organizing Neural Network Model for a Mechanism of Pattern Recognition Unaffected by Shift in Position. *Biological Cybernetics*, 1980.

Neocognitron: Key Ingredients

Cascade of **simple** and **complex** cells:

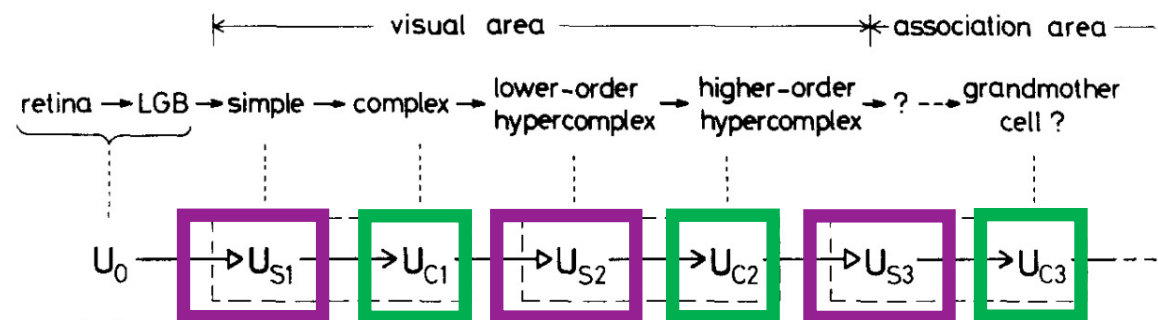


Fig. 1. Correspondence between the hierarchy model by Hubel and Wiesel, and the neural network of the neocognitron

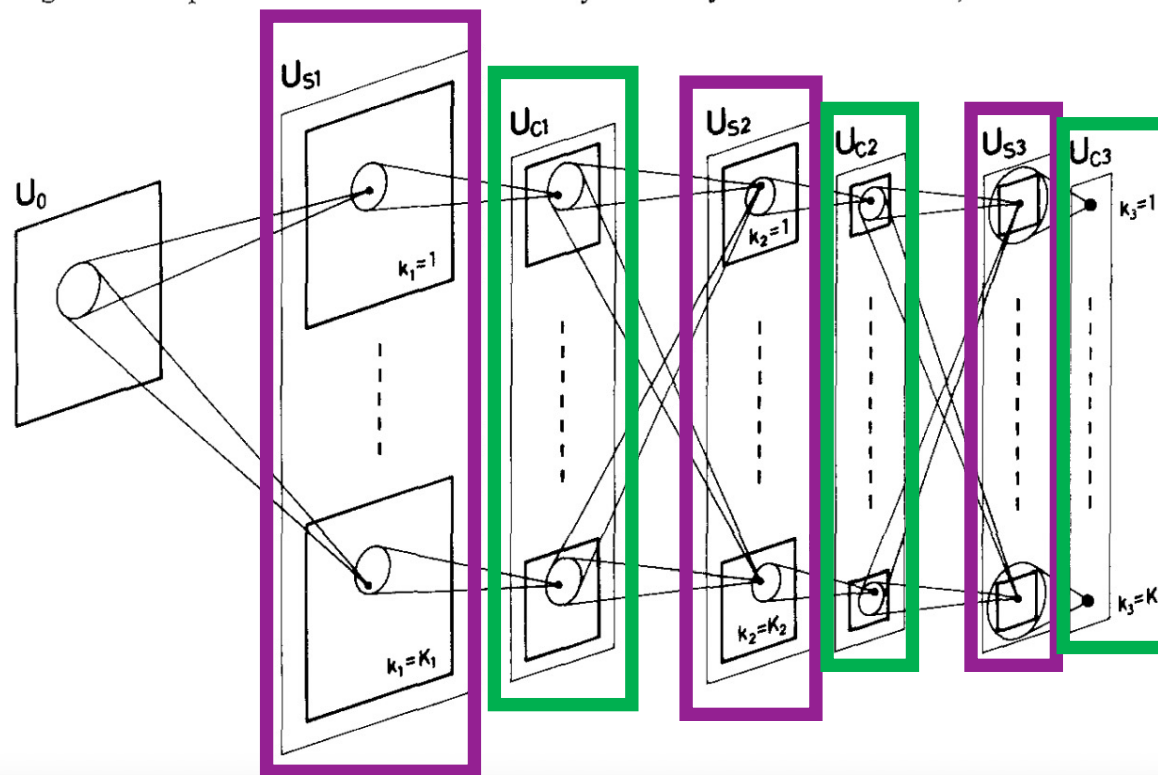


Fig. 2. Schematic diagram illustrating the interconnections between layers in the neocognitron
Fukushima, 1980.

Neocognitron: Key Ingredients

Simple cells extract local features using a sliding filter:

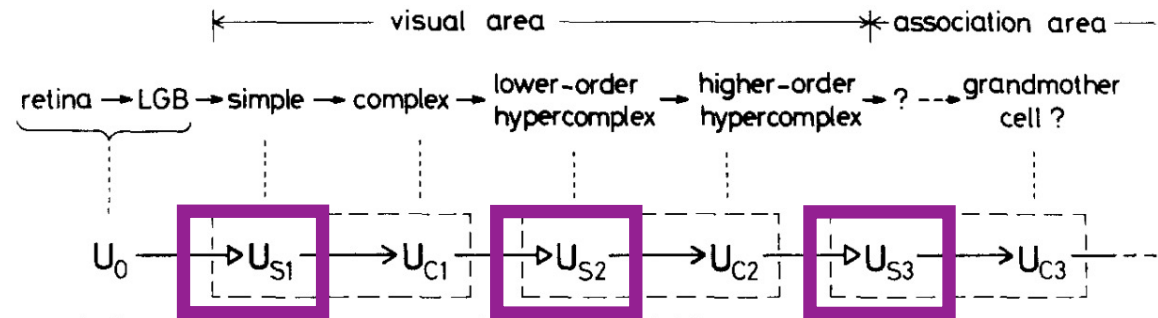
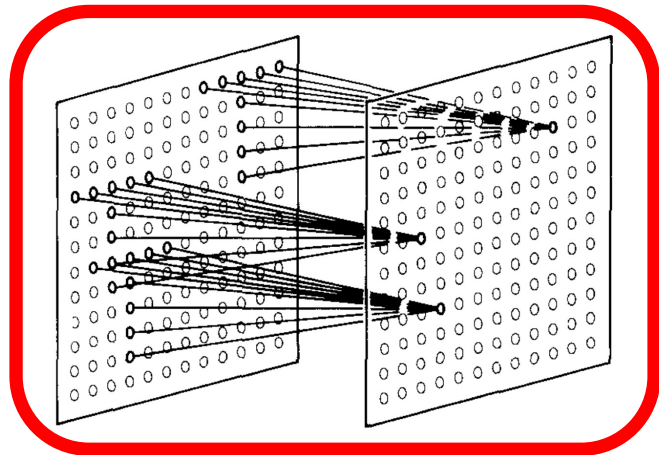


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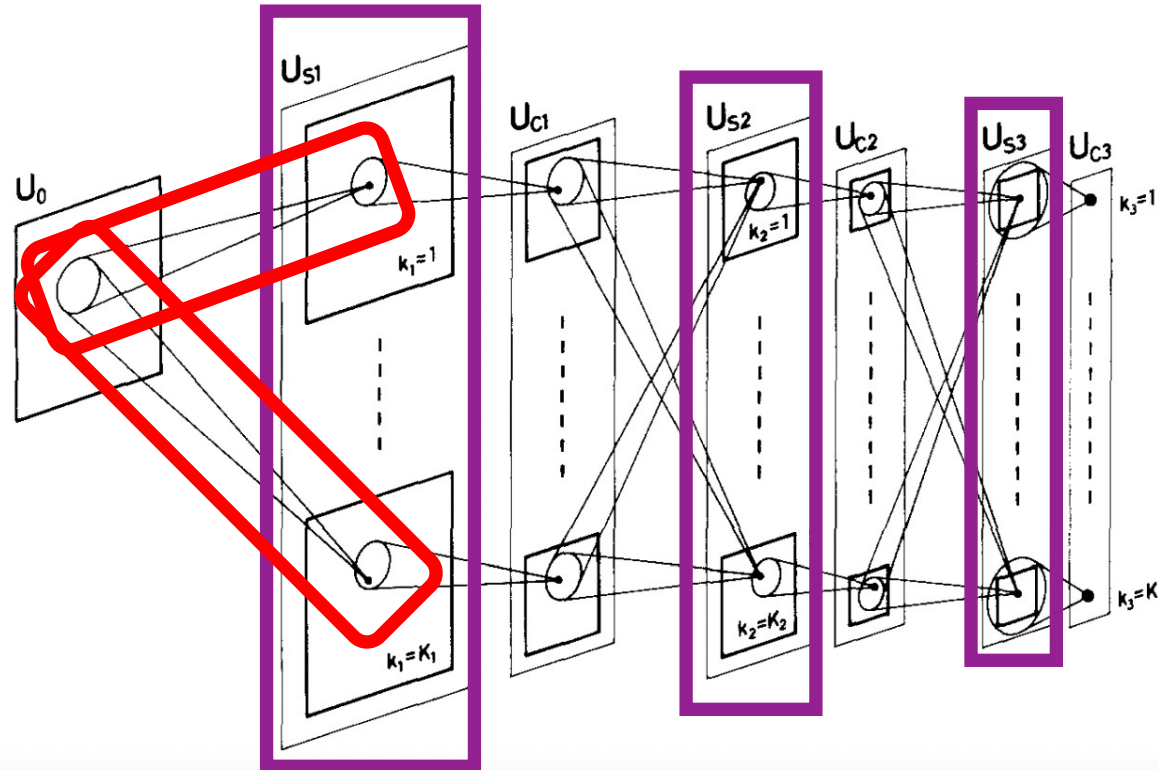


Fig. 2. Schematic diagram illustrating the interconnections between layers in the neocognitron
Fukushima, 1980.

Neocognitron: Key Ingredients

Complex cells fire when any part of the local region is the desired pattern

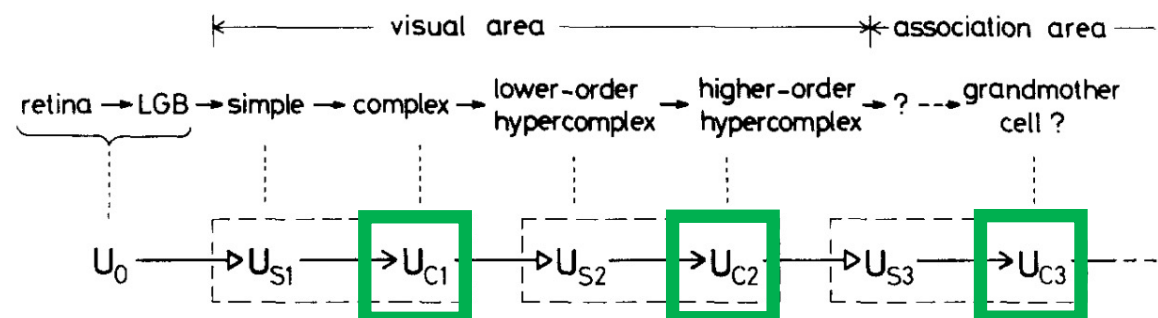


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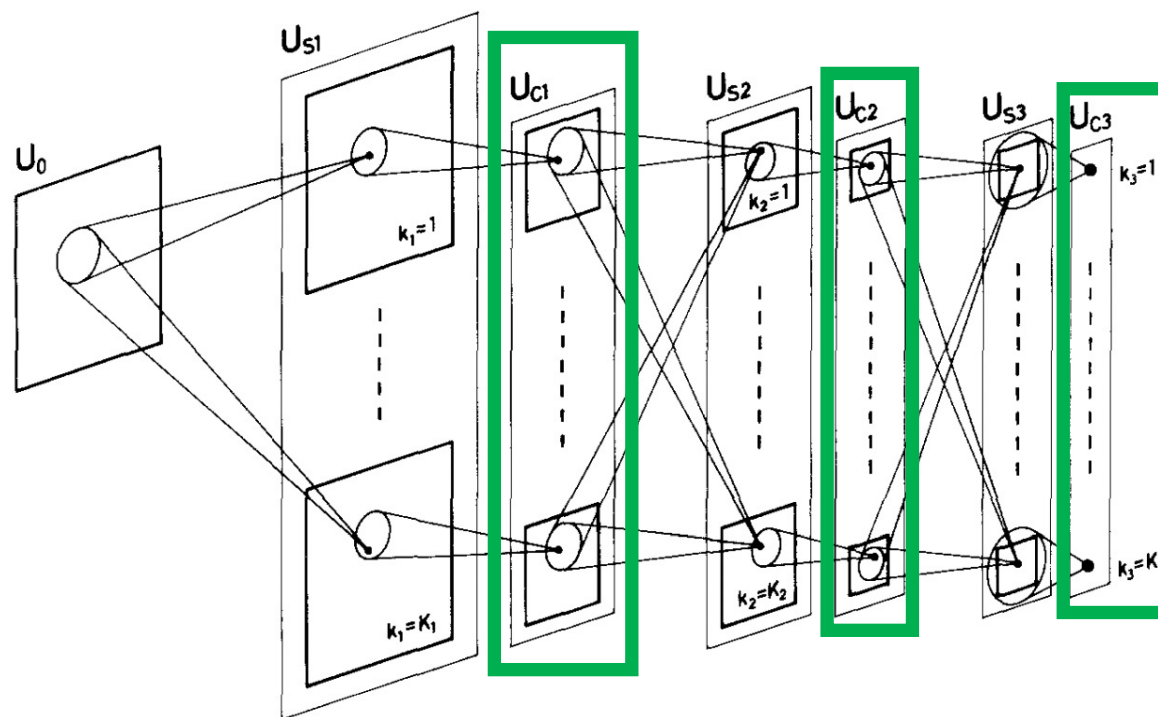


Fig. 2. Schematic diagram illustrating the interconnections between layers in the neocognitron Fukushima, 1980.

Neocognitron: Key Ingredients

1. ~ Convolutional layers

→ modifiable synapses

→ unmodifiable synapses

2. ~ Pooling Layers

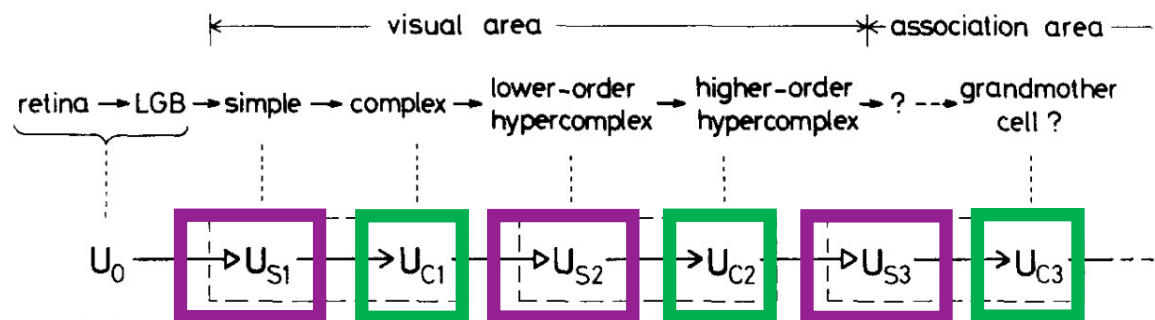


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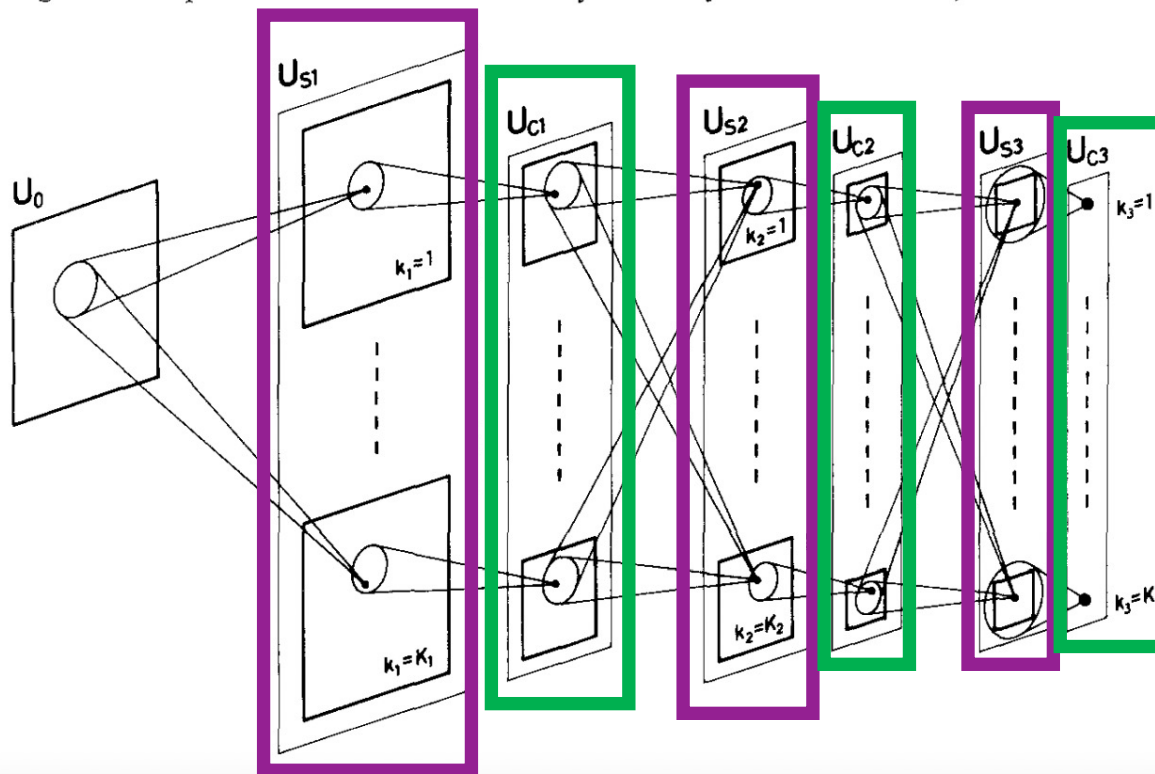
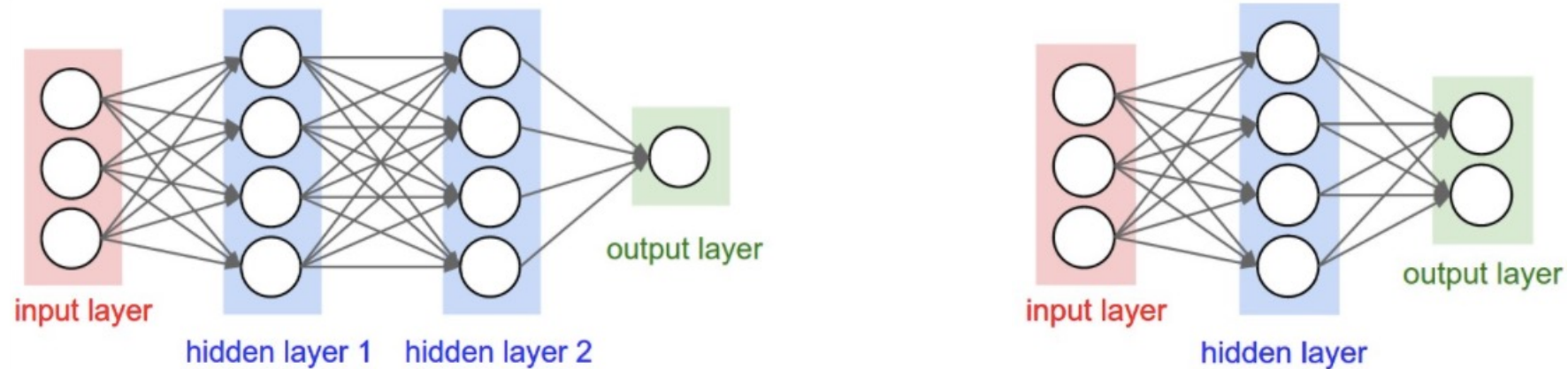


Fig. 2. Schematic diagram illustrating the interconnections between layers in the neocognitron
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Today's Topics

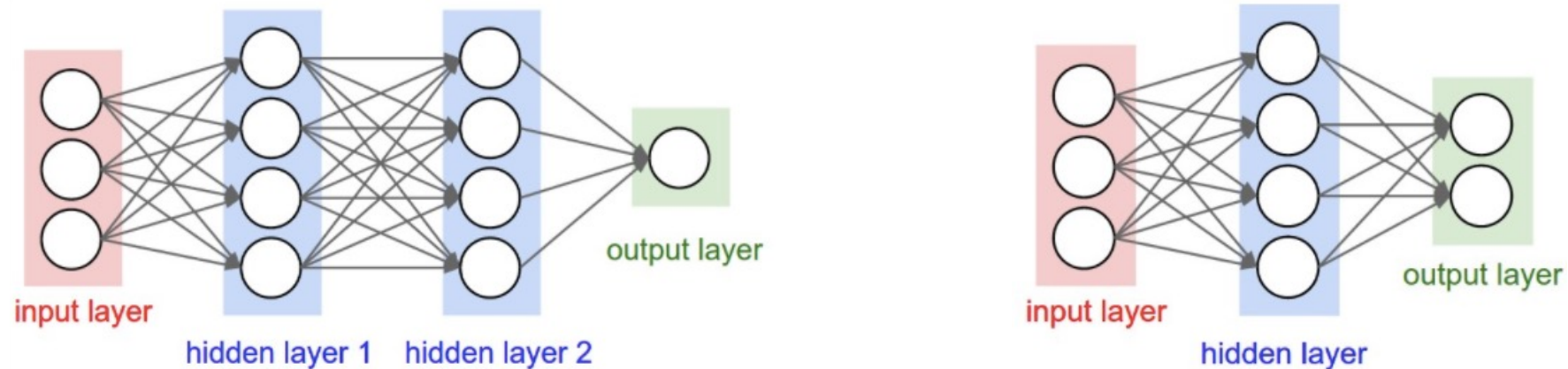
- Neural Networks for Spatial Data
- History of Convolutional Neural Networks (CNNs)
- **CNNs – Convolutional Layers**
- CNNs – Pooling Layers

Motivation: Fully-Connected Layers Are Limited



Each node provides input to each node in the next layer

Motivation: Fully-Connected Layers Are Limited



- Assume 2 layer model with 100 nodes per layer
 - e.g., how many weights are in a 640x480 image?
 - $640 \times 480 \times 3 \times 100 + 100 \times 100 + 100 \times 1 = 92,170,100$
 - e.g., how many weights are in a 2048X1536 image (3.1 Megapixel image)?
 - $2048 \times 1536 \times 3 \times 100 + 100 \times 100 + 100 \times 1 = 943,728,500$

Motivation: Fully-Connected Layers Are Limited

Issue: many model parameters in fully connected networks

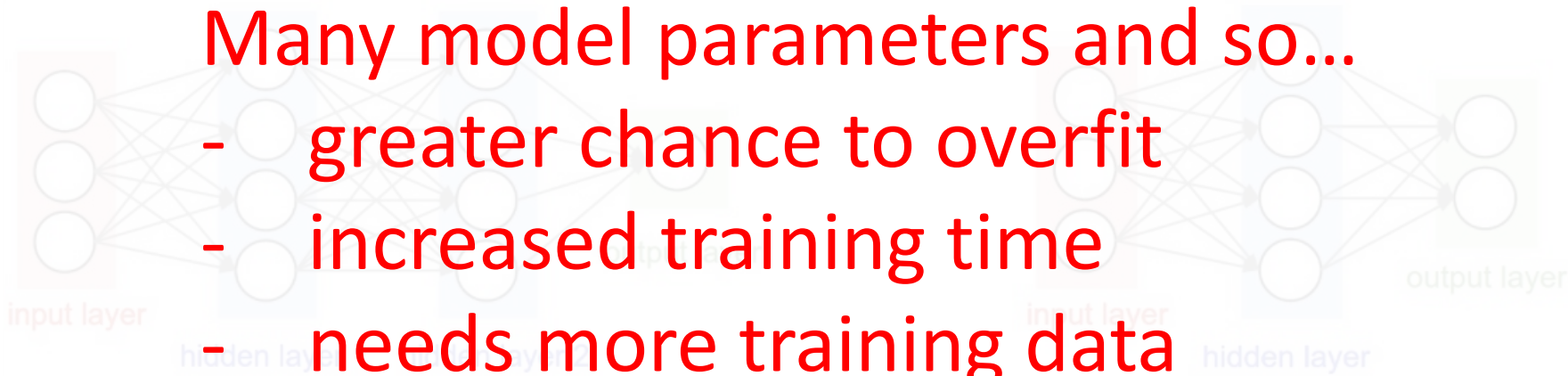


- Assume 2 layer model with 100 nodes per layer
 - e.g., how many weights are in a 640x480 image?
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 - $2048 \times 1536 \times 3 \times 100 + 100 \times 100 + 100 \times 1 = 943,728,500$

Motivation: Fully-Connected Layers Are Limited

Many model parameters and so...

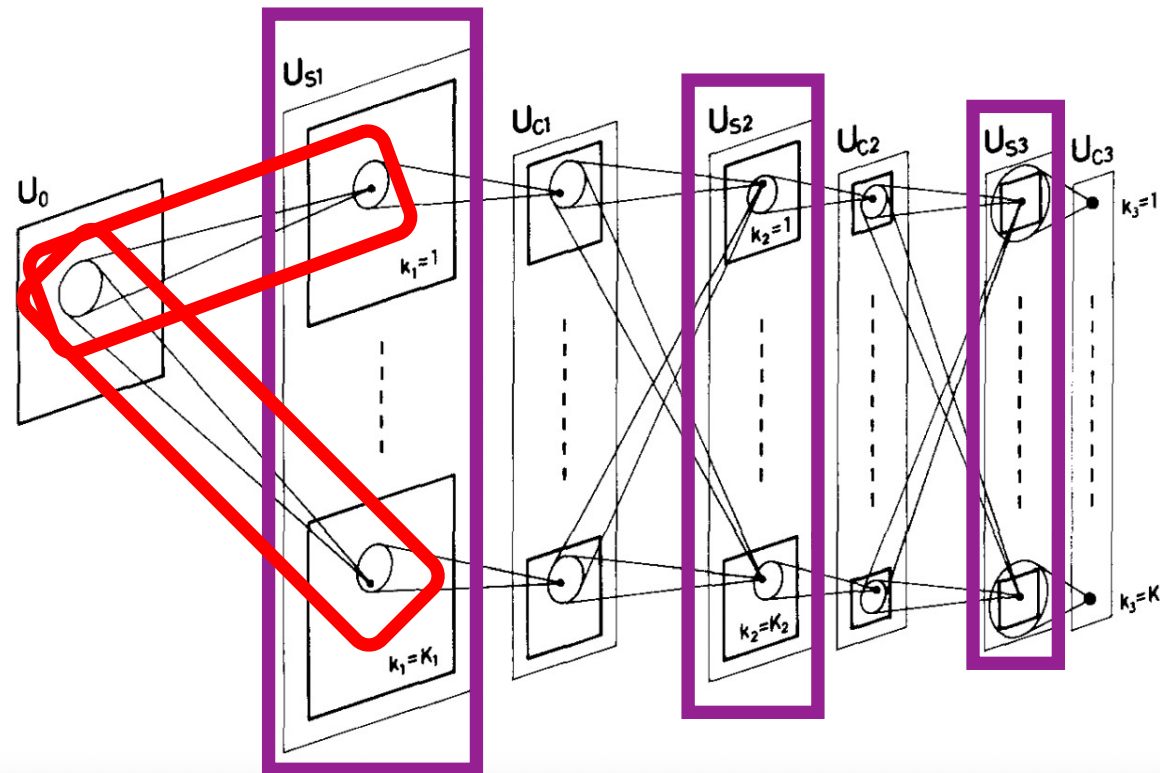
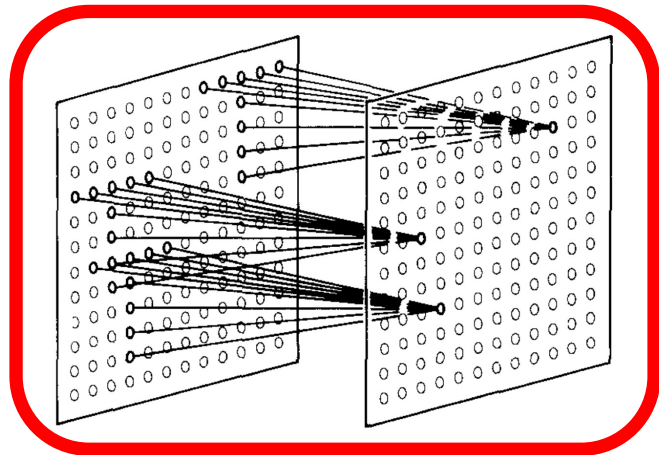
- greater chance to overfit
- increased training time
- needs more training data



- Assume 2 layer model with 100 nodes per layer
 - e.g., how many weights are in a 640x480 image?
 - $640 \times 480 \times 3 \times 100 + 100 \times 100 + 100 \times 1 = 92,170,100$
 - e.g., how many weights are in a 2048X1536 image (3.1 Megapixel image)?
 - $2048 \times 1536 \times 3 \times 100 + 100 \times 100 + 100 \times 1 = 943,728,500$

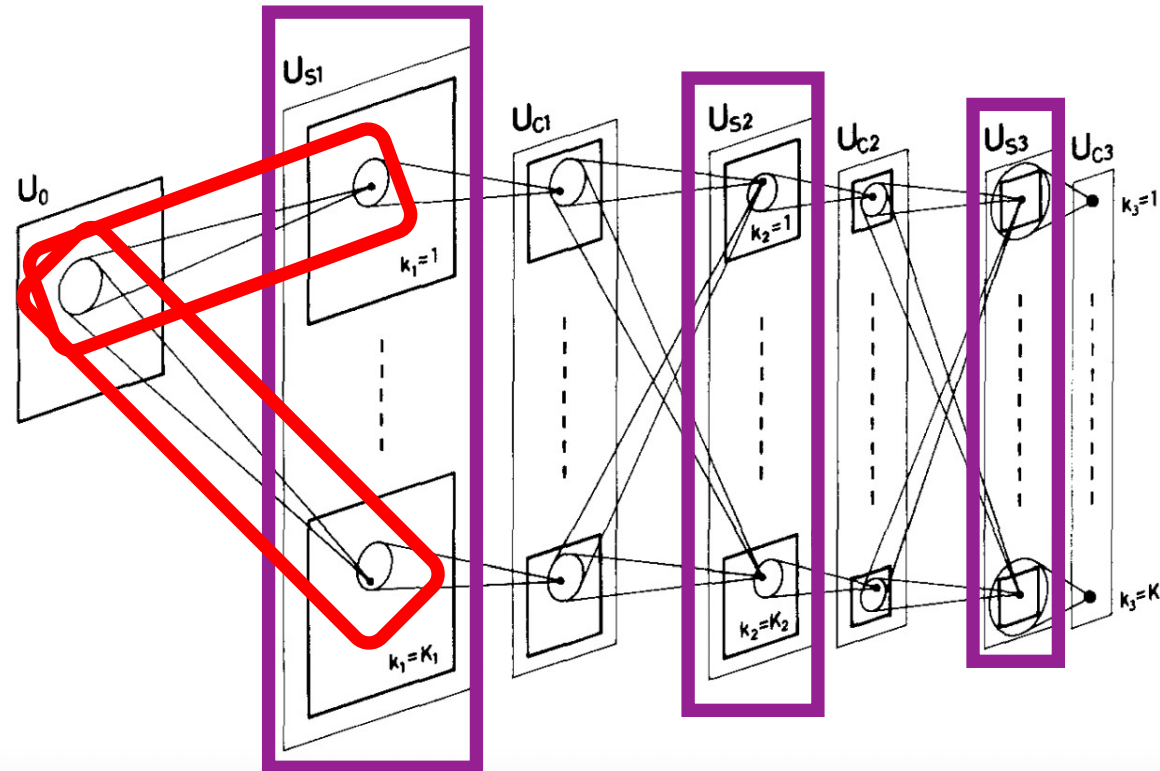
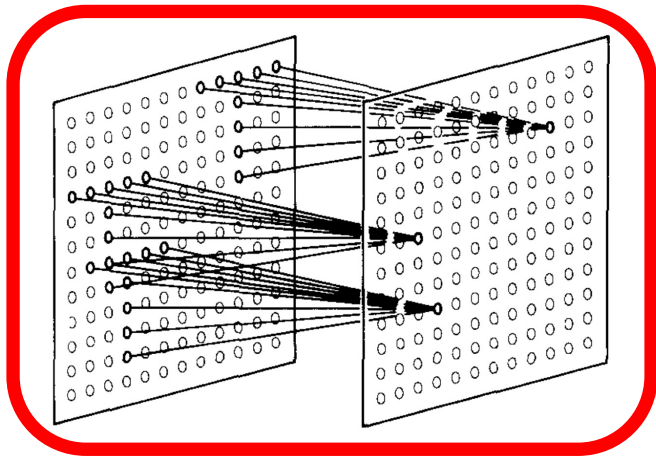
Convolutional Layer (Recall Neocognitron)

Idea: each node receives input only from a small neighborhood in previous layer and parameter sharing

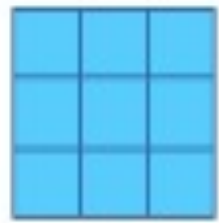


Convolutional Layer (Recall Neocognitron)

To do so, convolutions replace general matrix multiplication used in fully connected layers



Convolution: Applies Linear Filter (e.g., 2D)



Input

*



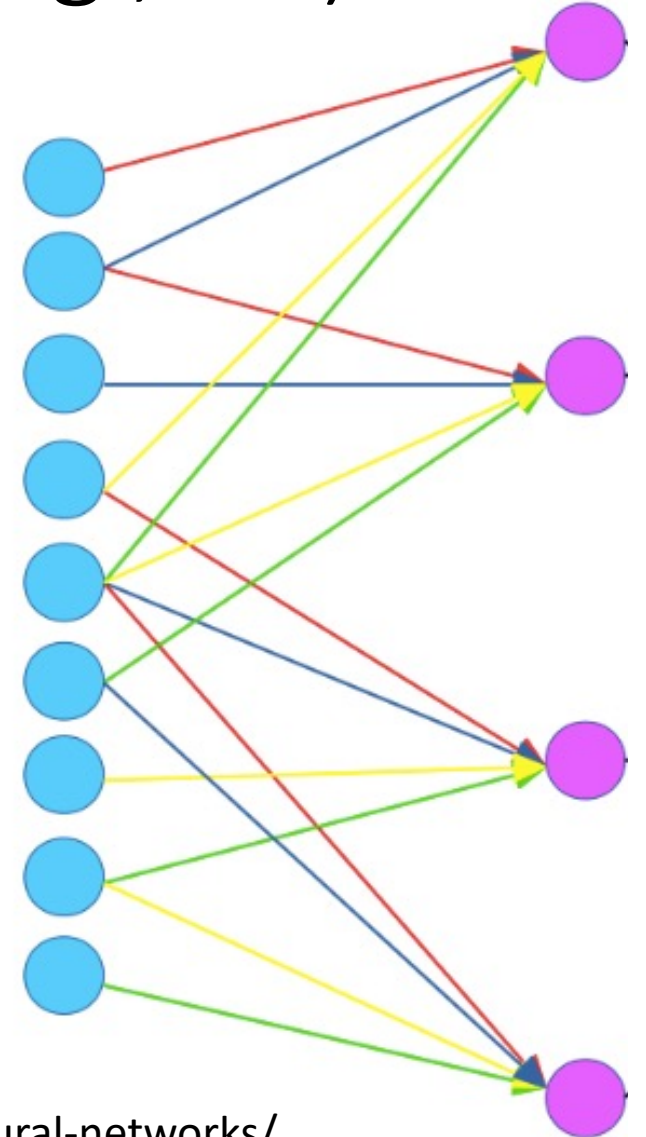
Filter
(aka – Kernel)

=



Feature
Map

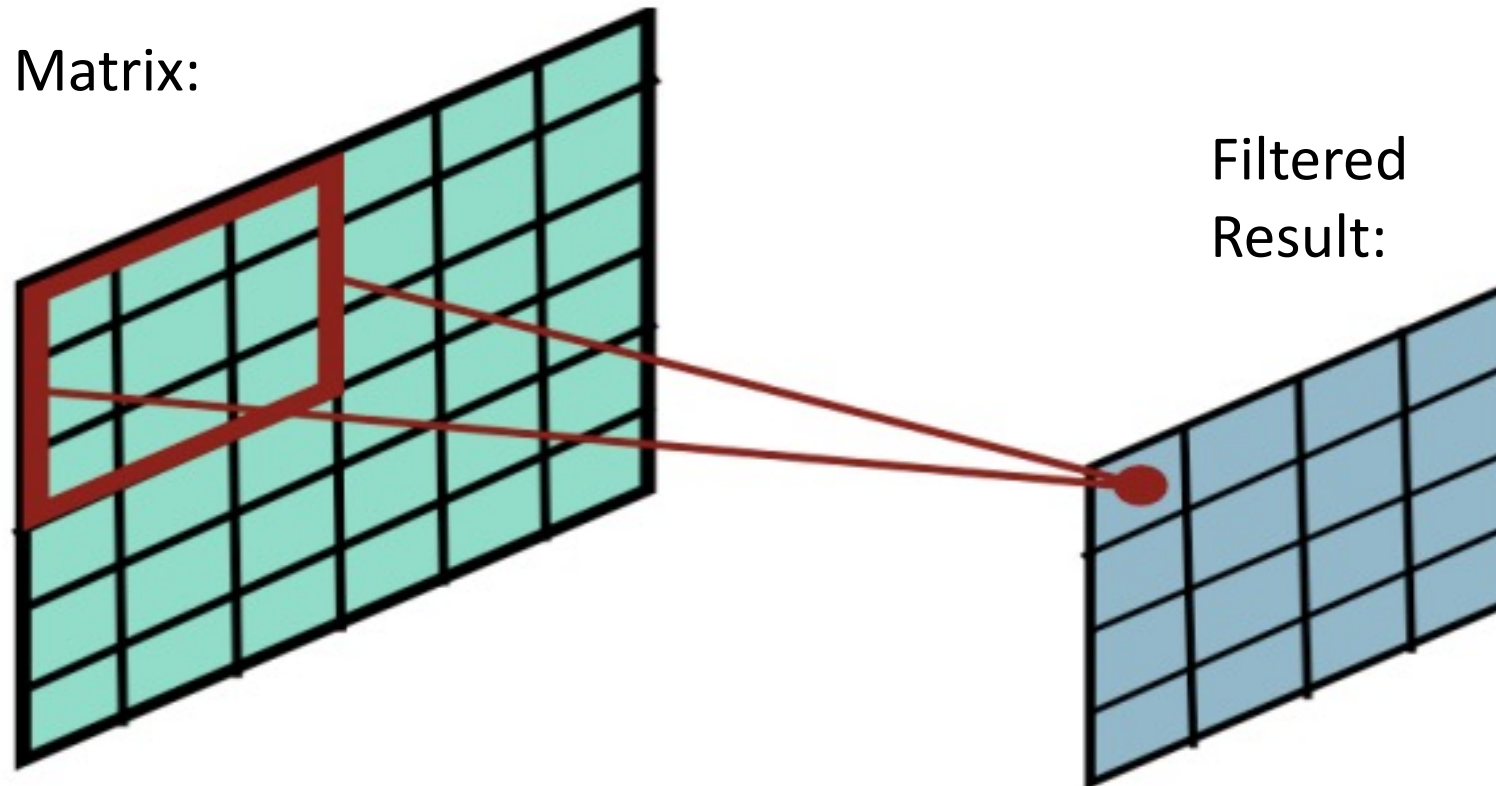
Way to Interpret
Neural Network



2D Filtering

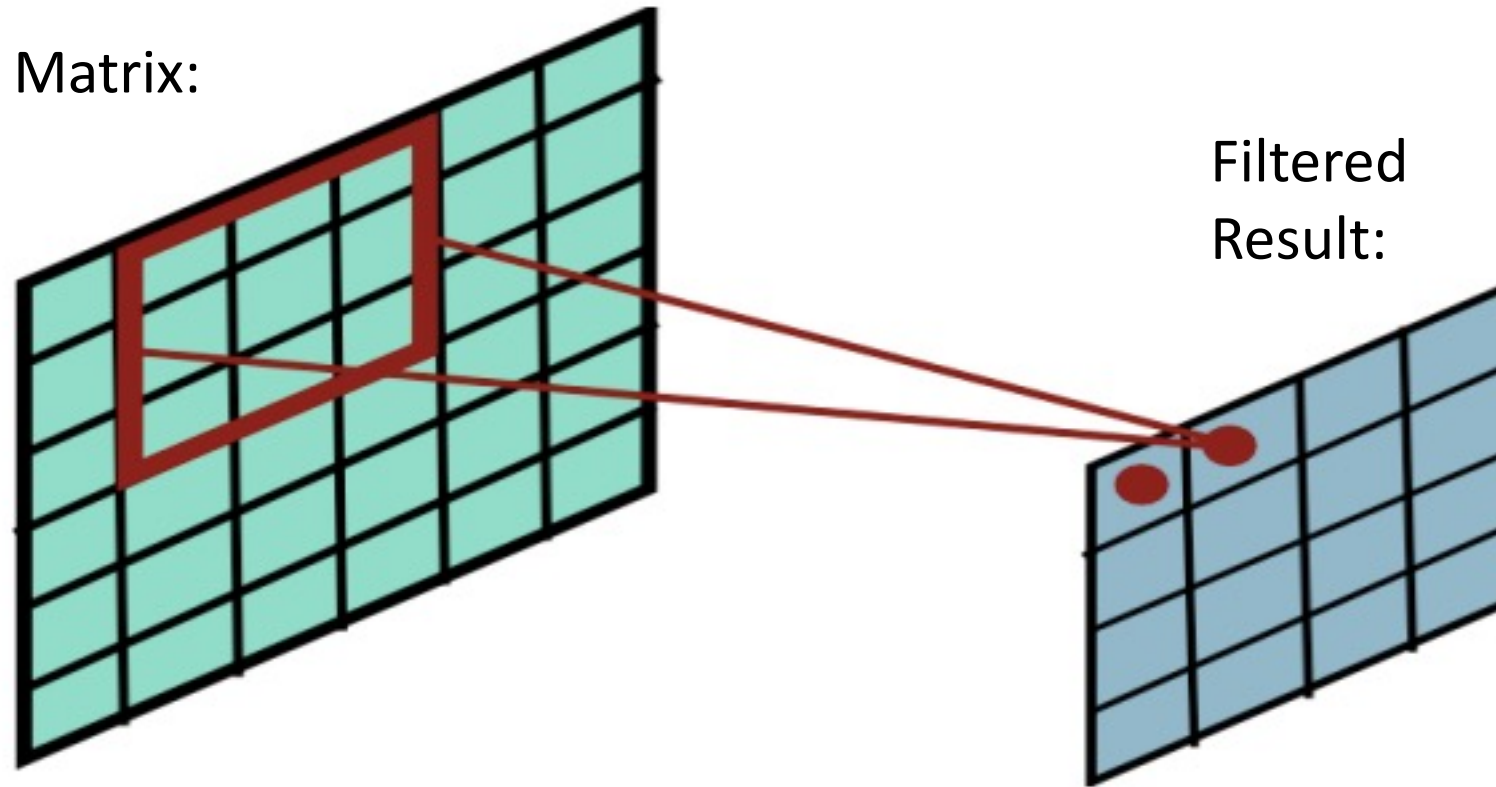
- Compute a **function of local neighborhood** for each location in matrix
- A **filter** specifies the function for how to combine neighbors' values

2D Filtering



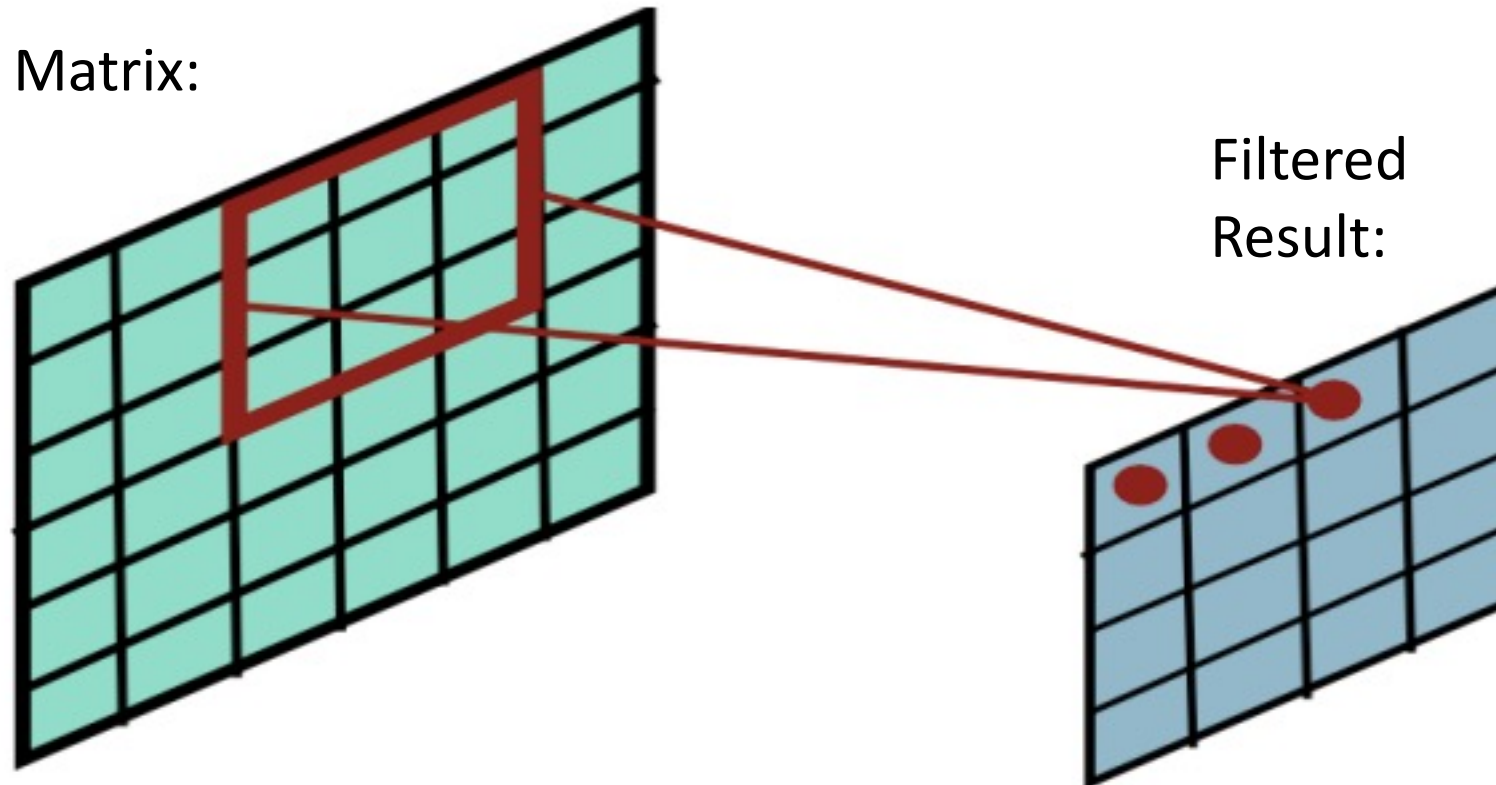
Slides filter over the matrix and computes dot products

2D Filtering



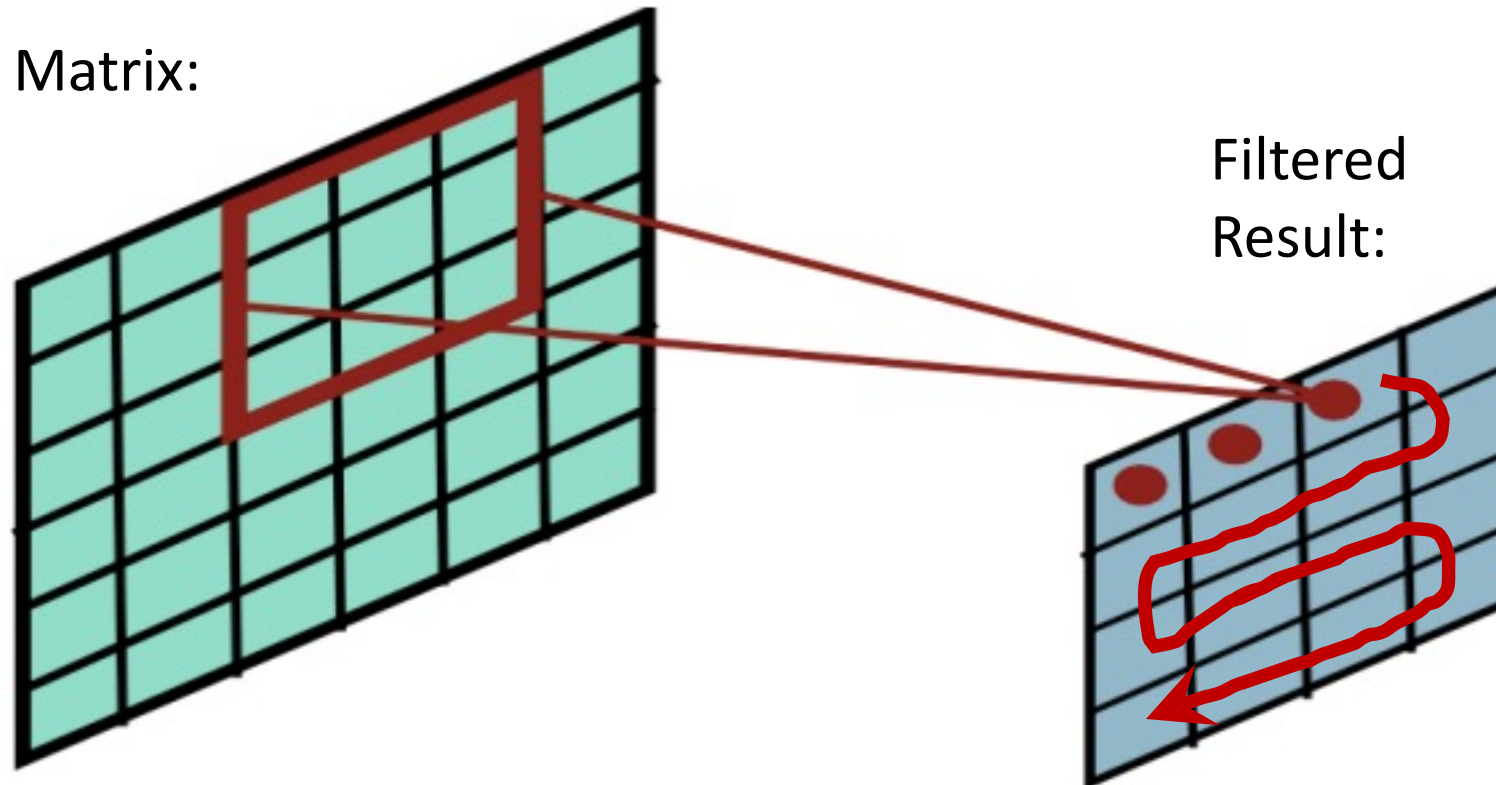
Slides filter over the matrix and computes dot products

2D Filtering



Slides filter over the matrix and computes dot products

2D Filtering



Slides filter over the matrix and computes dot products

2D Filtering: Toy Example

Input

1	1	1	0	0
0	1	1	1	0
0	0	1	1	1
0	0	1	1	0
0	1	1	0	0

Filter

1	0	1
0	1	0
1	0	1

Feature Map

?	?	?
?	?	?
?	?	?

Dot Product = $1*1 + 1*0 + 1*1 + 0*0 + 1*1 + 1*0 + 0*1 + 0*1 + 0*0 + 0*0 + 1*1$

Dot Product = 4

2D Filtering: Toy Example

Input

1	1	1	0	0
0	1	1	1	0
0	0	1	1	1
0	0	1	1	0
0	1	1	0	0

Filter

1	0	1
0	1	0
1	0	1

Feature Map

4	?	?
?	?	?
?	?	?

2D Filtering: Toy Example

Input

1	1	1	0	0
0	1	1	1	0
0	0	1	1	1
0	0	1	1	0
0	1	1	0	0

Filter

1	0	1
0	1	0
1	0	1

Feature Map

4	3	?
?	?	?
?	?	?

2D Filtering: Toy Example

Input

1	1	1	0	0
0	1	1	1	0
0	0	1	1	1
0	0	1	1	0
0	1	1	0	0

Filter

1	0	1
0	1	0
1	0	1

Feature Map

4	3	4
?	?	?
?	?	?

2D Filtering: Toy Example

Input

1	1	1	0	0
0	1	1	1	0
0	0	1	1	1
0	0	1	1	0
0	1	1	0	0

Filter

1	0	1
0	1	0
1	0	1

Feature Map

4	3	4
2	?	?
?	?	?

2D Filtering: Toy Example

Input

1	1	1	0	0
0	1	1	1	0
0	0	1	1	1
0	0	1	1	0
0	1	1	0	0

Filter

1	0	1
0	1	0
1	0	1

Feature Map

4	3	4
2	4	?
?	?	?

2D Filtering: Toy Example

Input

1	1	1	0	0
0	1	1	1	0
0	0	1	1	1
0	0	1	1	0
0	1	1	0	0

Filter

1	0	1
0	1	0
1	0	1

Feature Map

4	3	4
2	4	3
?	?	?

2D Filtering: Toy Example

Input

1	1	1	0	0
0	1	1	1	0
0	0	1	1	1
0	0	1	1	0
0	1	1	0	0

Filter

1	0	1
0	1	0
1	0	1

Feature Map

4	3	4
2	4	3
2	?	?

2D Filtering: Toy Example

Input

1	1	1	0	0
0	1	1	1	0
0	0	1	1	1
0	0	1	1	0
0	1	1	0	0

Filter

1	0	1
0	1	0
1	0	1

Feature Map

4	3	4
2	4	3
2	3	?

2D Filtering: Toy Example

Input

1	1	1	0	0
0	1	1	1	0
0	0	1	1	1
0	0	1	1	0
0	1	1	0	0

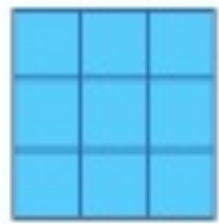
Filter

1	0	1
0	1	0
1	0	1

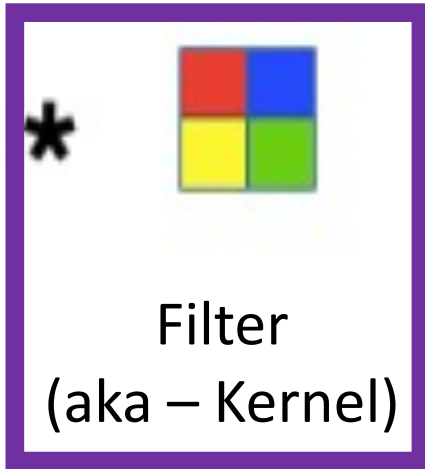
Feature Map

4	3	4
2	4	3
2	3	4

Convolutional Layer: Parameters to Learn



Input



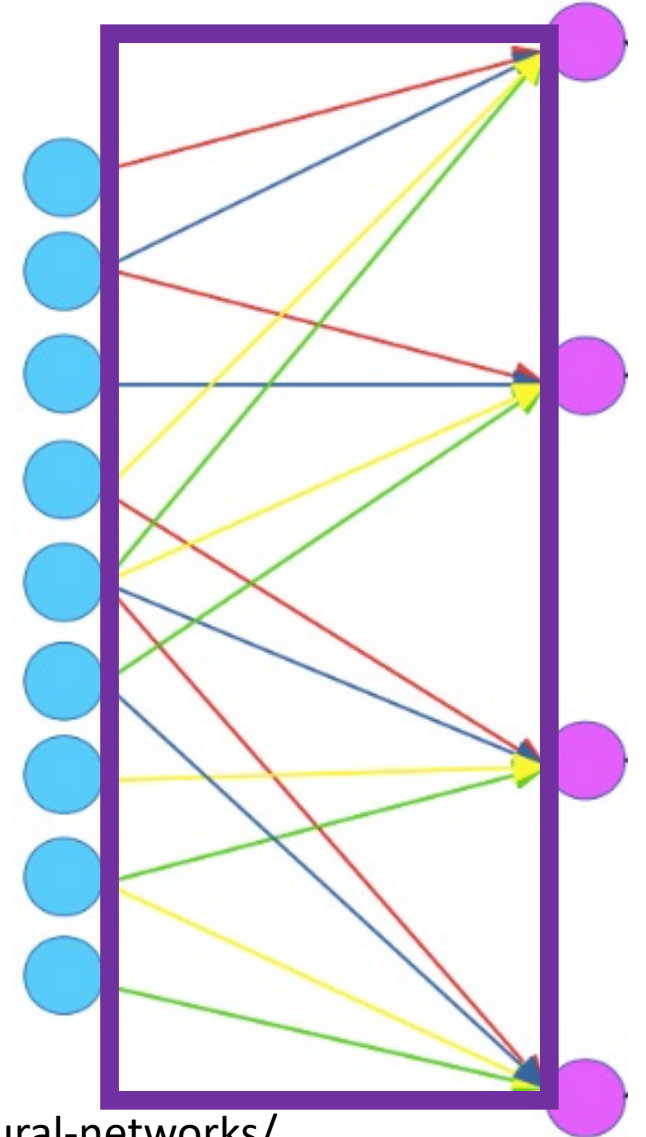
Filter
(aka – Kernel)

=



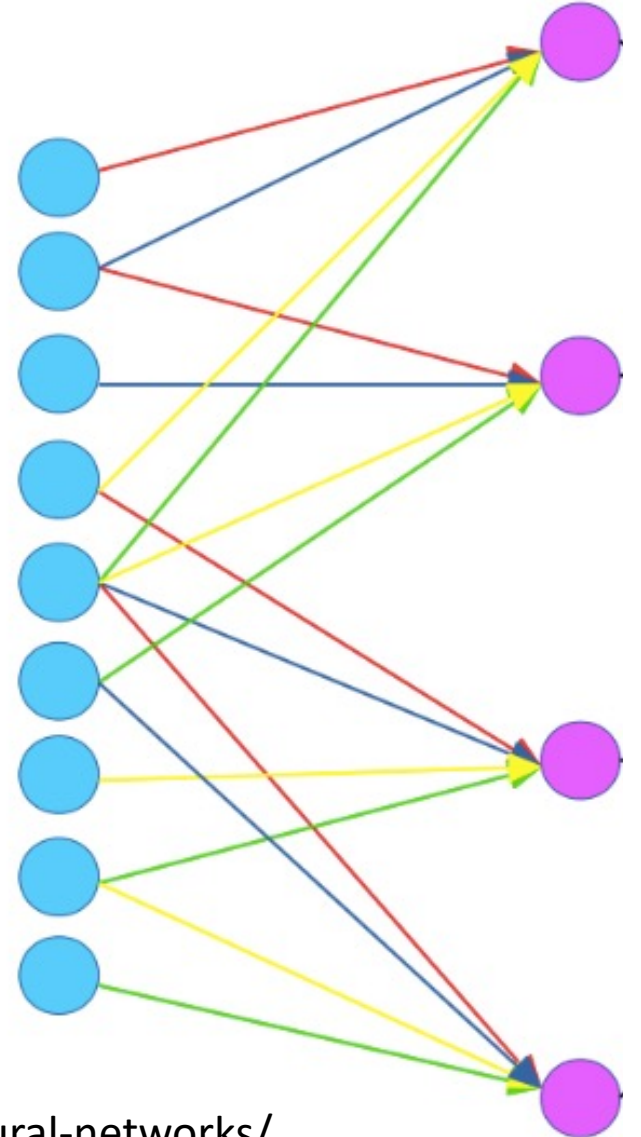
Feature
Map

Way to Interpret
Neural Network



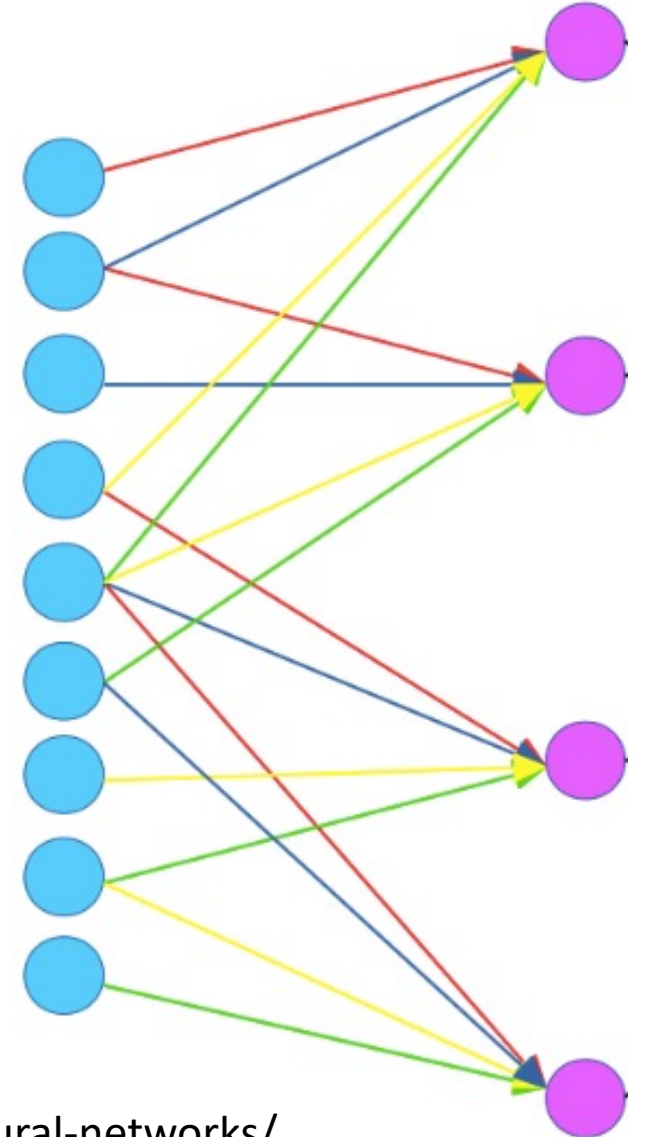
Convolutional Layer: Parameters to Learn

- For shown example, how many weights must be learned?
 - 4 (red, blue, yellow, and green values)
- If we instead used a fully connected layer, how many weights would need to be learned?
 - 36 (9 turquoise nodes x 4 magenta nodes)
- For shown example, how many parameters must be learned?
 - 5 (4 weights + 1 bias)
- If we instead used a fully connected layer, how many parameters would need to be learned?
 - 40 (36 weights + 4 bias)



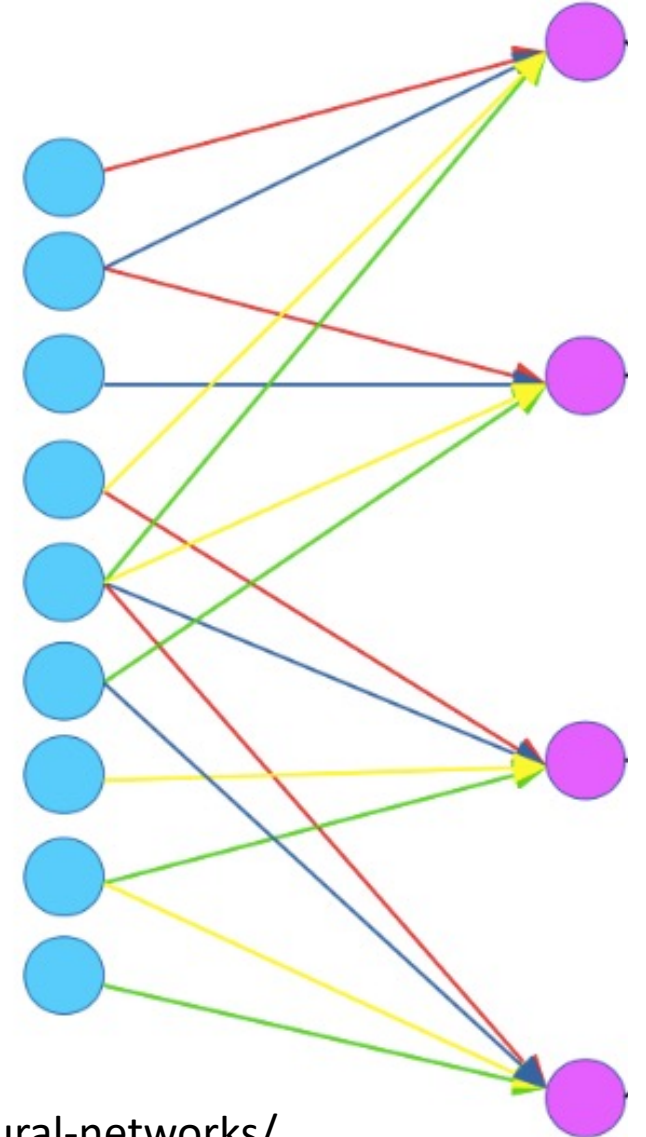
Convolutional Layer: Parameters to Learn

- Parameter sharing significantly reduces number of parameters to learn and so storage requirements
- Sparse (rather than full) connectivity also significantly reduces the number of computational operations required



Convolutional Layer: Parameters to Learn

- Neocognitron hard-coded filter values... we will cover models that learn the filter values in the next lecture



Convolutional Layer

- Many neural network libraries use “convolution” interchangeably with “cross correlation”; for mathematicians, these are technically different
- Examples in these slides show the “cross-correlation” function



Input

*



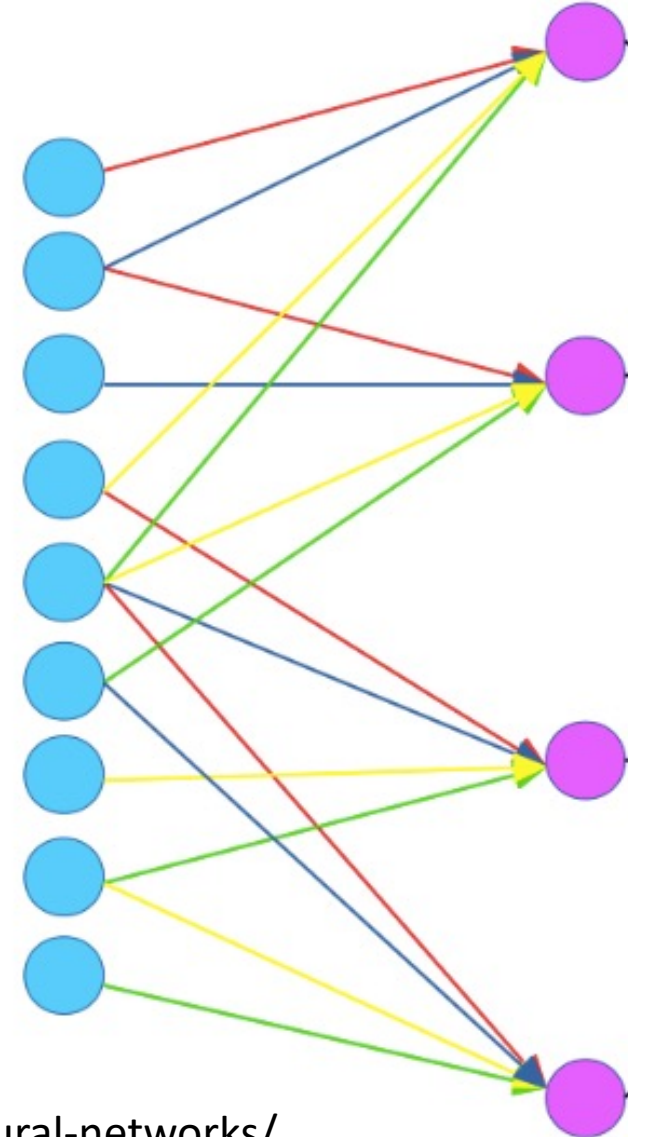
Filter
(aka – Kernel)

=

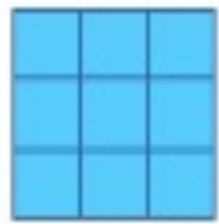


Feature
Map

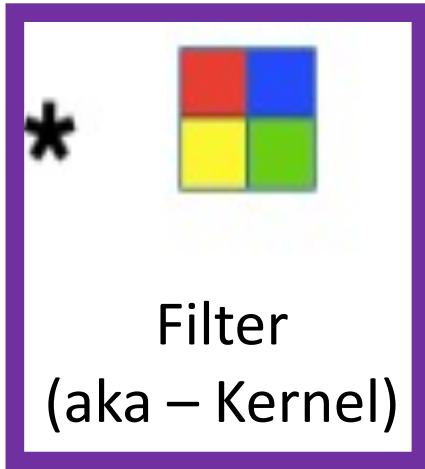
Way to Interpret
Neural Network



Convolutional Layer: What Does The Filter Do?



Input



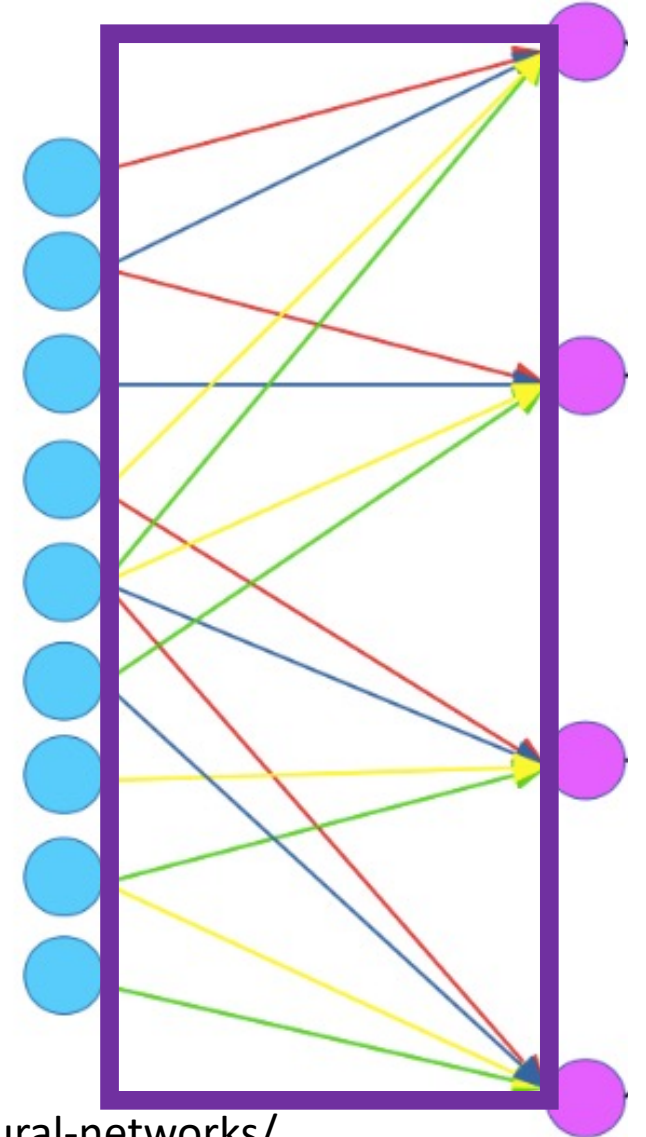
Filter
(aka – Kernel)

=



Feature
Map

Way to Interpret
Neural Network



Filter: What Does It Do?

Filter



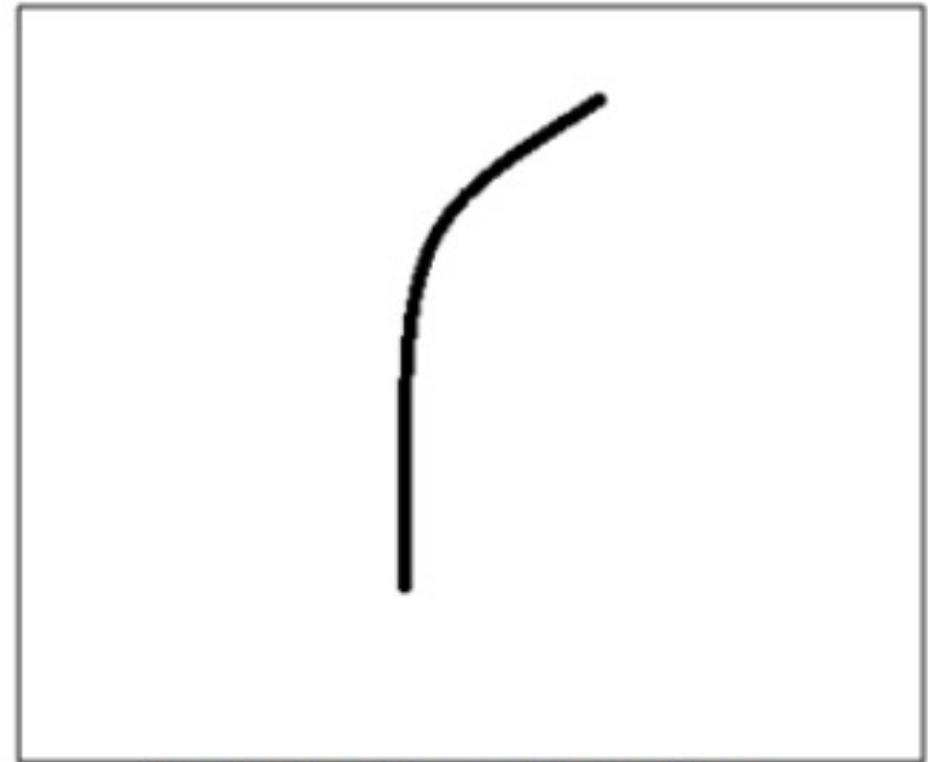
Filter: What Does It Do?

- e.g.,

Filter

0	0	0	0	0	30	0
0	0	0	0	30	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	0	0	0	0

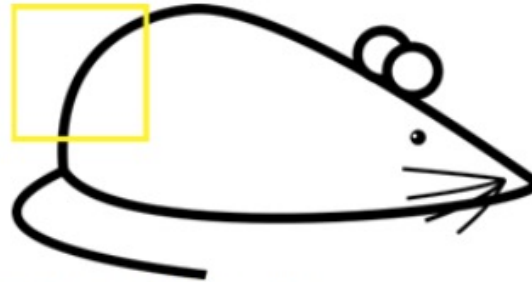
Visualization of Filter



Filter: What Does It Do?

- e.g.,

Filter Overlaid on Image



Image

0	0	0	0	0	0	30
0	0	0	0	50	50	50
0	0	0	20	50	0	0
0	0	0	50	50	0	0
0	0	0	50	50	0	0
0	0	0	50	50	0	0
0	0	0	50	50	0	0

Filter

*

0	0	0	0	0	30	0
0	0	0	0	30	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	0	0	0	0

Weighted Sum = ?

Weighted Sum = $(50 \times 30) + (20 \times 30) + (50 \times 30) + (50 \times 30) + (50 \times 30)$

Weighted Sum = 6600 (**Large Number!!**)

Filter: What Does It Do?

- e.g.,

Filter Overlaid on Image



Image

0	0	0	0	0	0	0
0	40	0	0	0	0	0
40	0	40	0	0	0	0
40	20	0	0	0	0	0
0	50	0	0	0	0	0
0	0	50	0	0	0	0
25	25	0	50	0	0	0

Filter

*

0	0	0	0	0	30	0
0	0	0	0	30	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	0	0	0	0

Weighted Sum = ?

Weighted Sum = 0 (**Small Number!!**)

Filter: What Does It Do?

- e.g.,

This Filter is a Curve Detector!

0	0	0	0	0	30	0
0	0	0	0	30	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	30	0	0	0
0	0	0	0	0	0	0





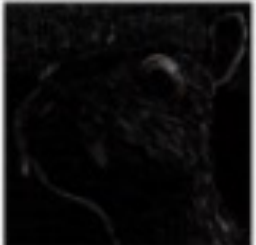
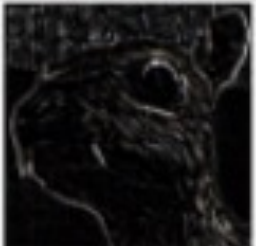
Filter Overlaid on Image (**Big Response!**)




Filter Overlaid on Image (**Small Response!**)




Filters Detect Different Features

	Filter	Feature Map
Identity	$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$	
Edge detection	$\begin{bmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \\ -1 & 0 & 1 \end{bmatrix}$	
	$\begin{bmatrix} 0 & 1 & 0 \\ 1 & -4 & 1 \\ 0 & 1 & 0 \end{bmatrix}$	
	$\begin{bmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{bmatrix}$	

	Filter	Feature Map
Sharpen	$\begin{bmatrix} 0 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 0 \end{bmatrix}$	
Box blur (normalized)	$\frac{1}{9} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$	
Gaussian blur (approximation)	$\frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$	

Different Filters Detect Different Features



Filter:
Sharpen

Image:
Bell

0	-3	0
-3	21	-3
0	-3	0

Divisor: 9

The Matrix

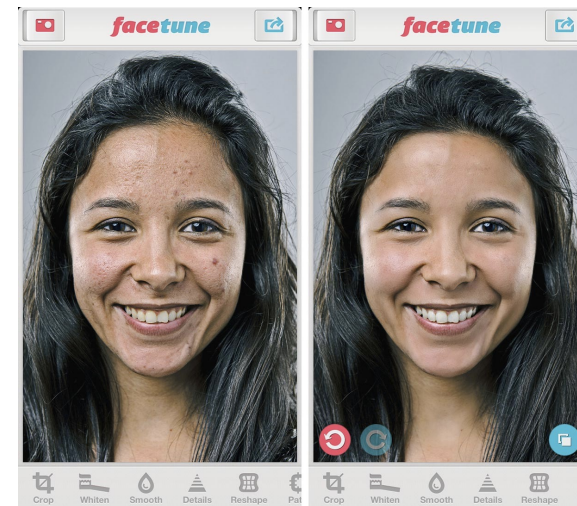
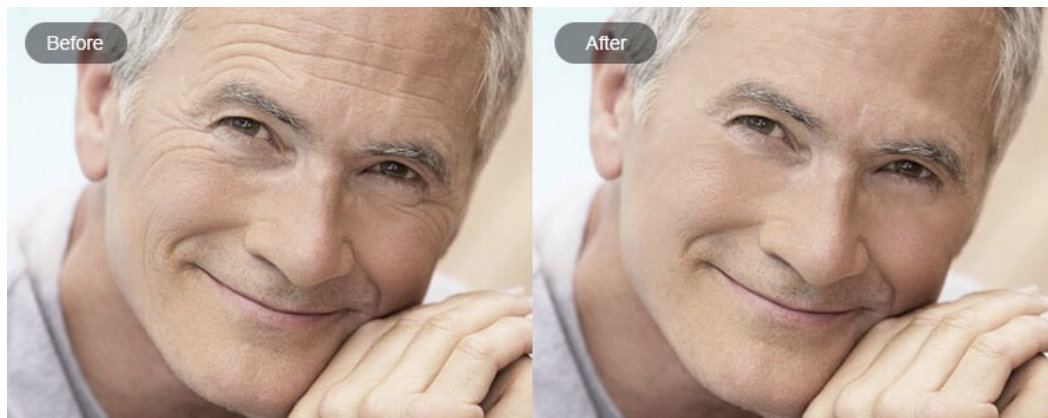
Demo: <http://beej.us/blog/data/convolution-image-processing/>

Group Discussion

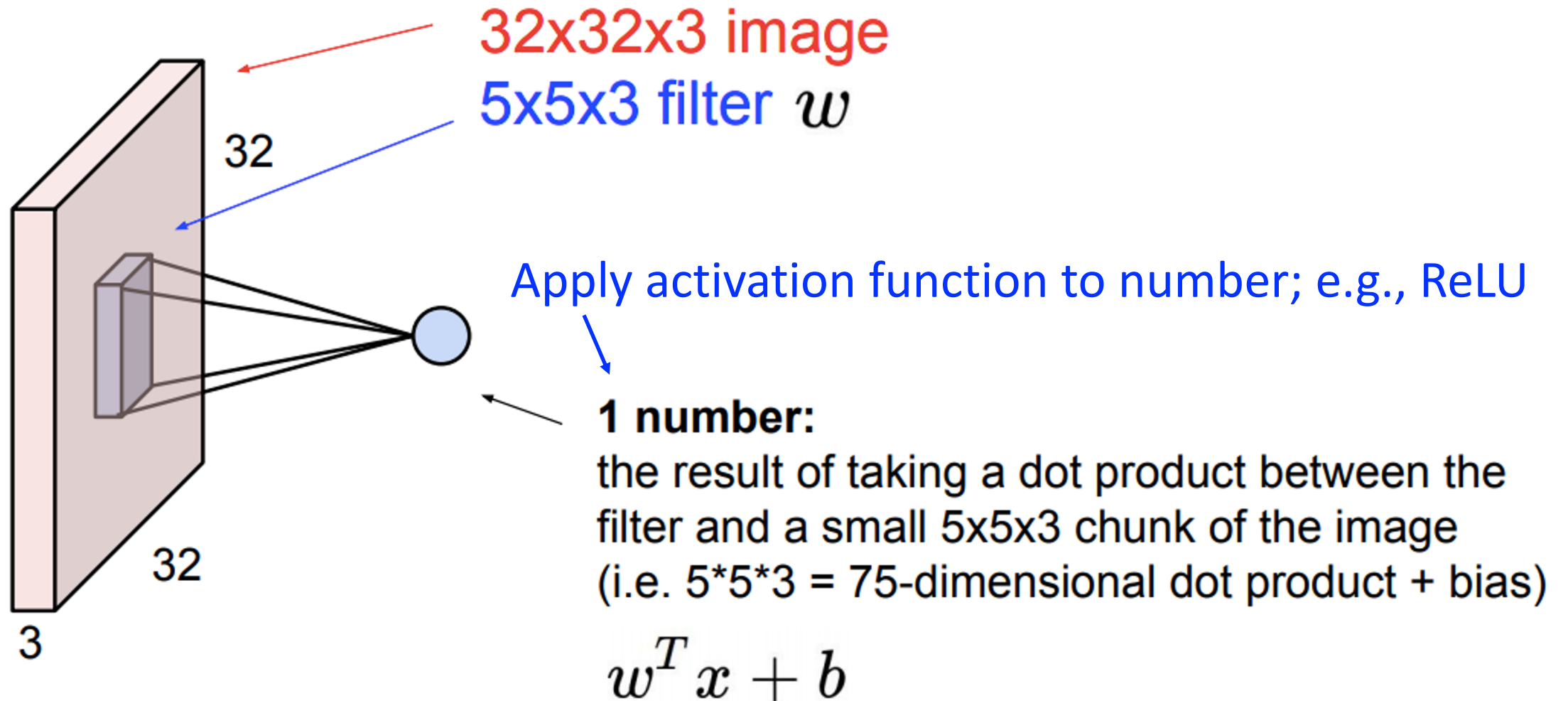
1. How would you design a filter to “brighten” an image?



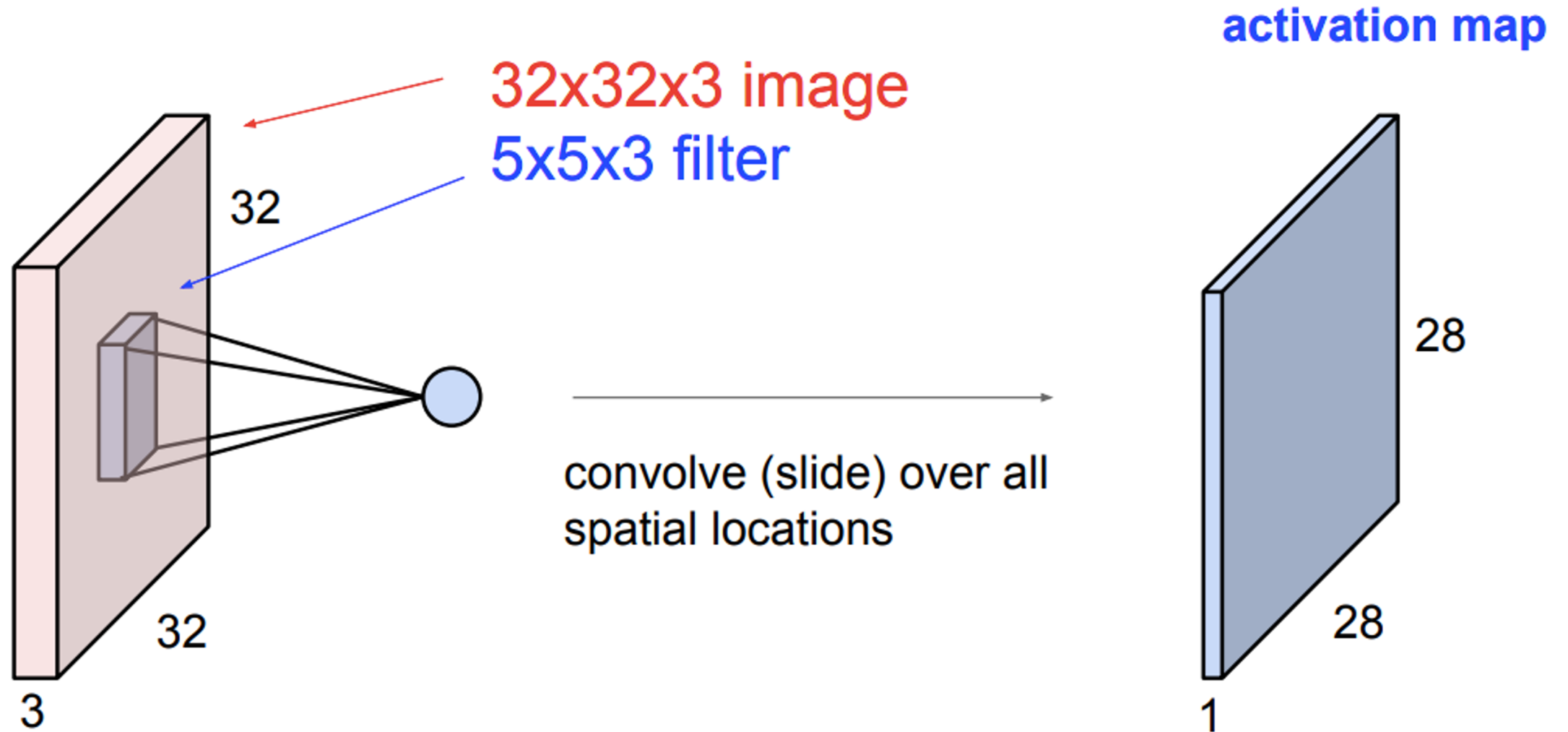
2. How would you design a filter to remove wrinkles/blemishes?



Convolutional Layer: After Applying Filter, Remember to Introduce Non-Linearity

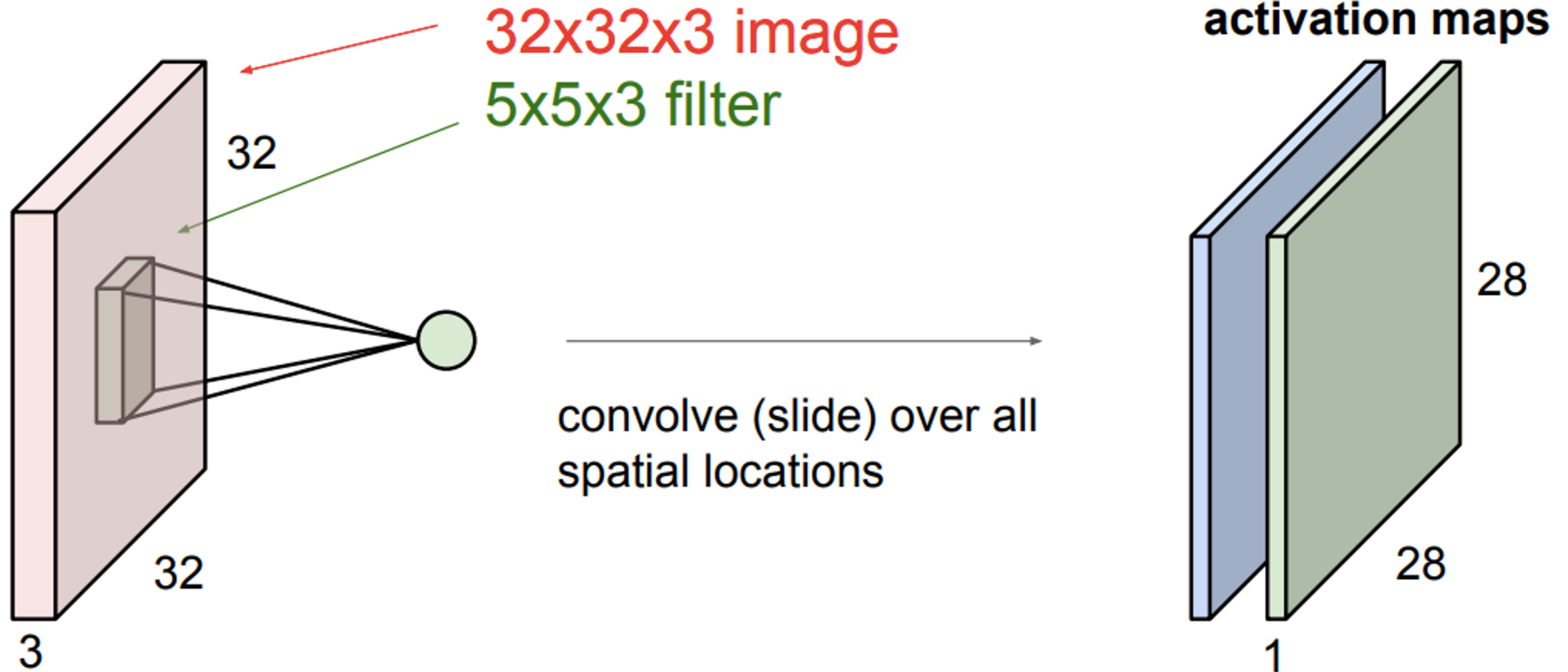


Convolutional Layer: Slide Filter Across Input



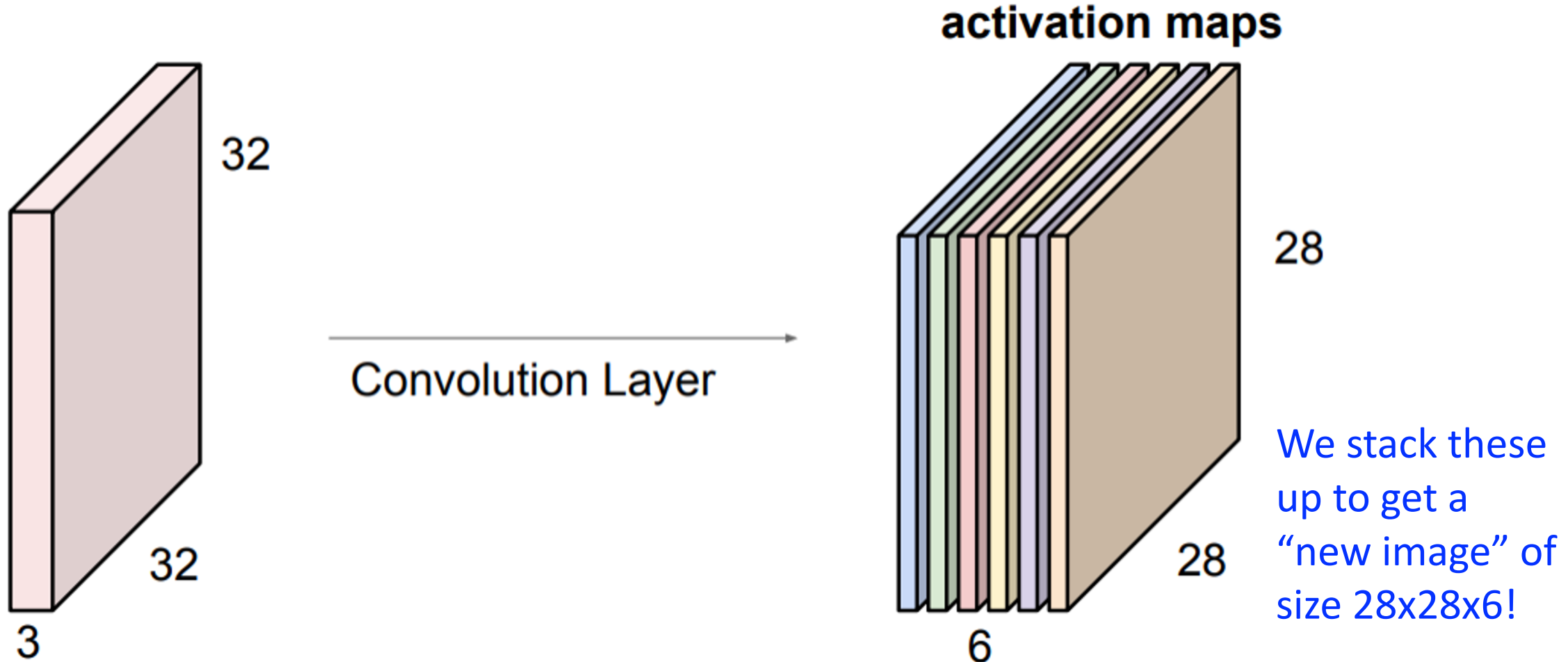
consider a second, **green** filter

Convolutional Layer: Slide Filter Across Input



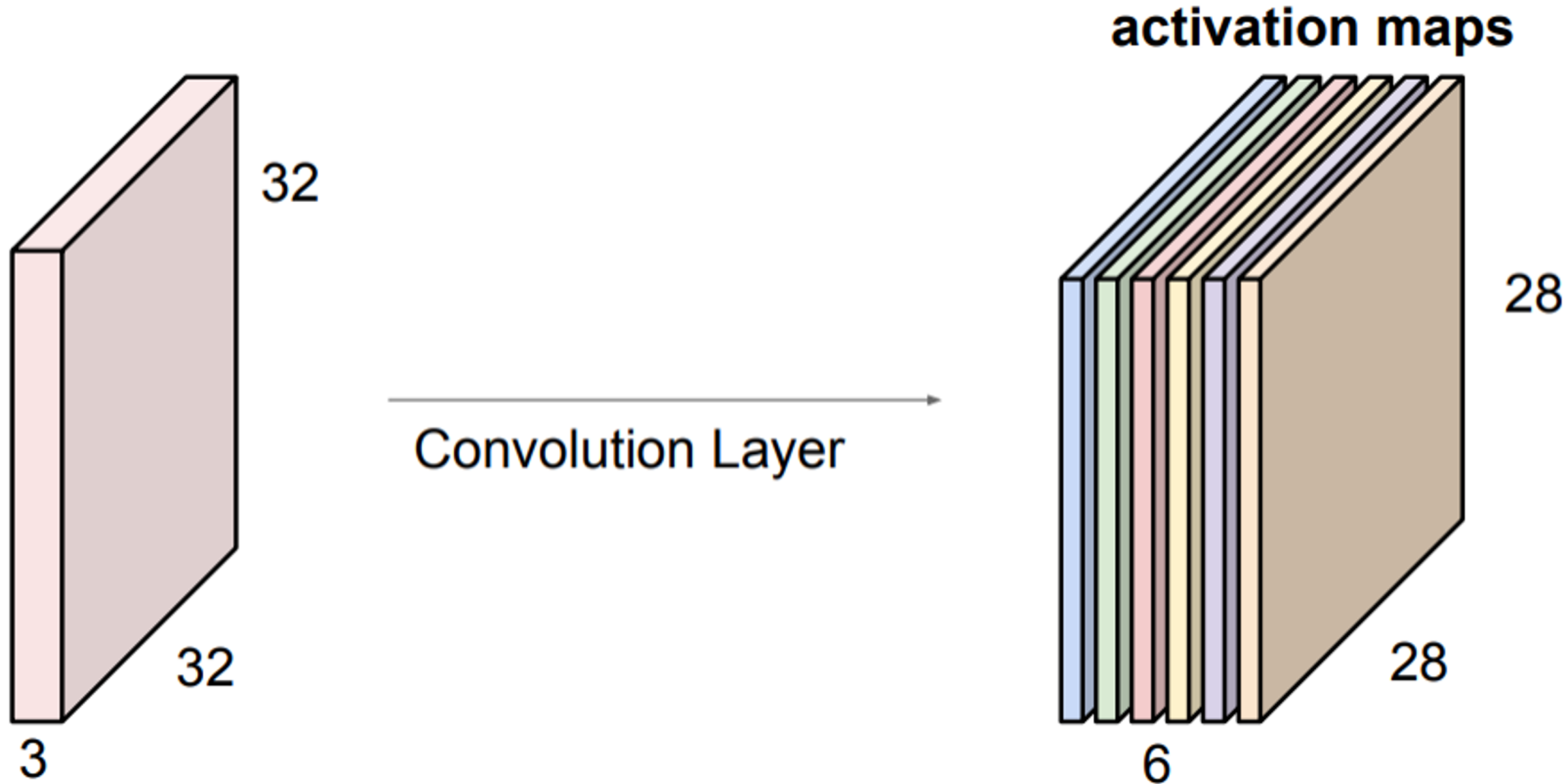
Convolutional Layer: Slide Filter Across Input

if we had 6 5x5 filters, we'll get 6 separate activation maps:



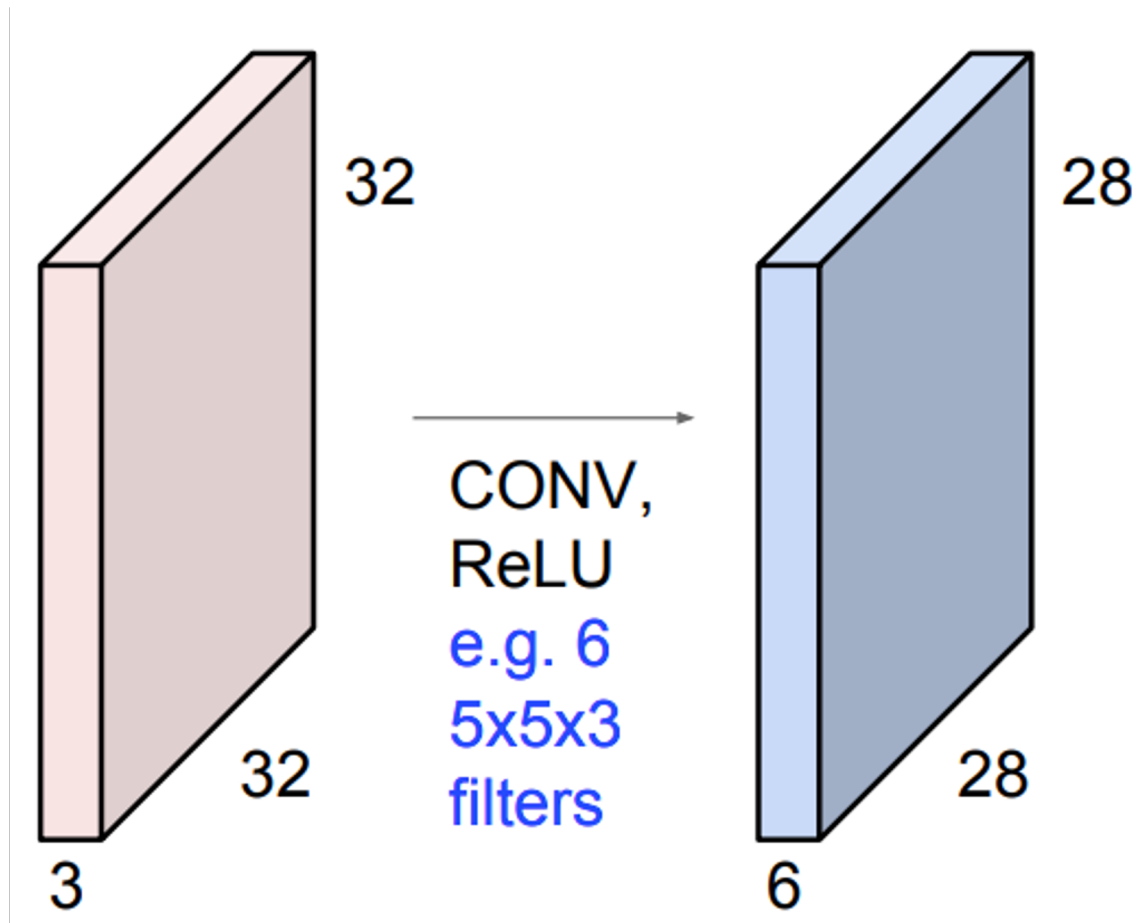
Convolutional Layer: Parameters to Learn

Parameters: bank of filters and biases used to create the activation maps (aka – feature maps)



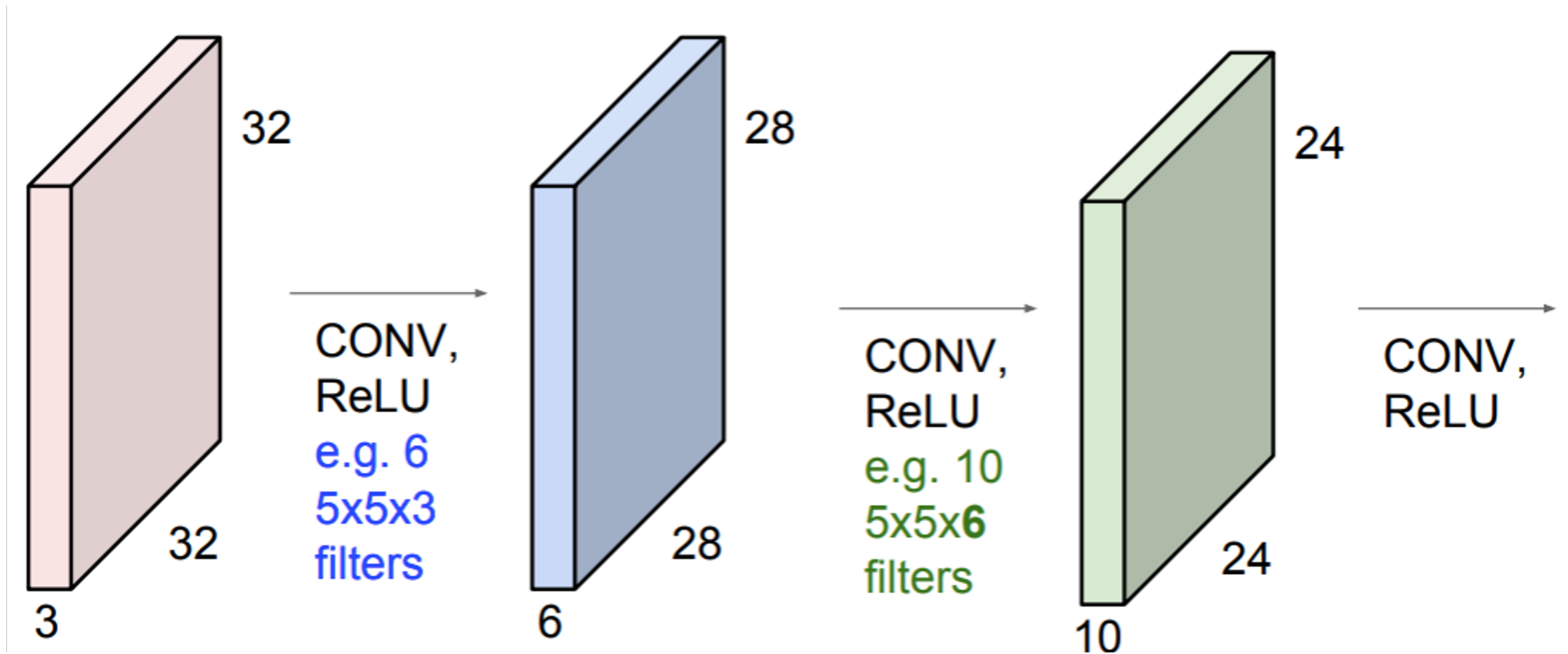
Convolutional Layers Stacked

Can then stack a sequence of convolution layers, interspersed with activation functions:



Convolutional Layers Stacked

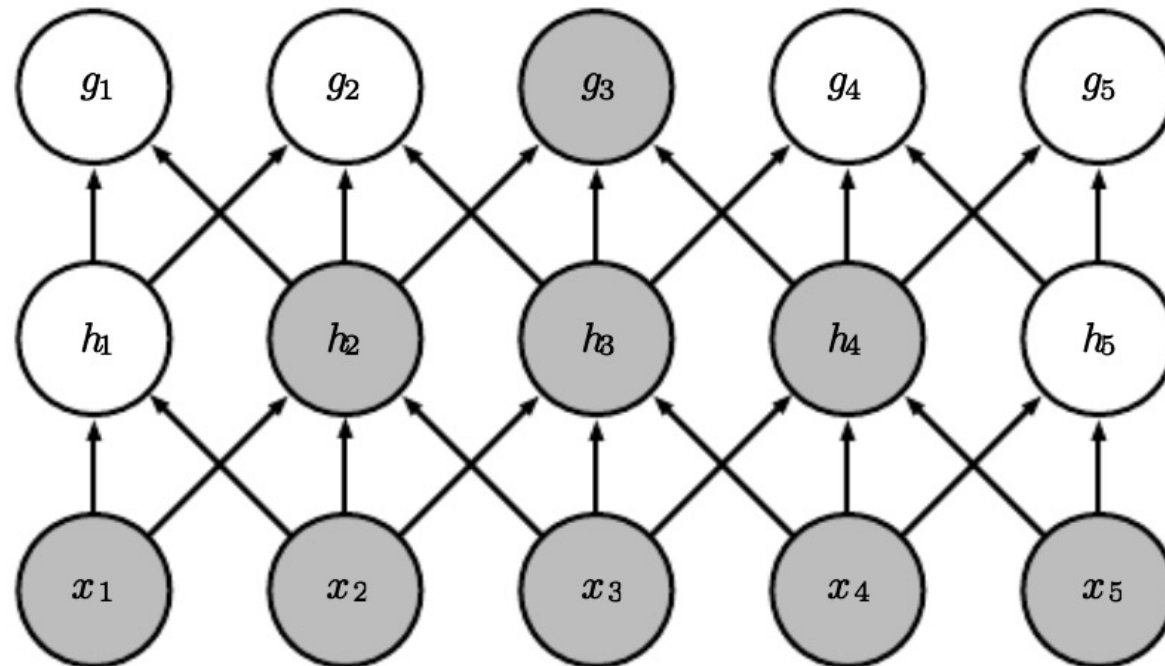
Can then stack a sequence of convolution layers, interspersed with activation functions:



Convolutional Layers Stacked

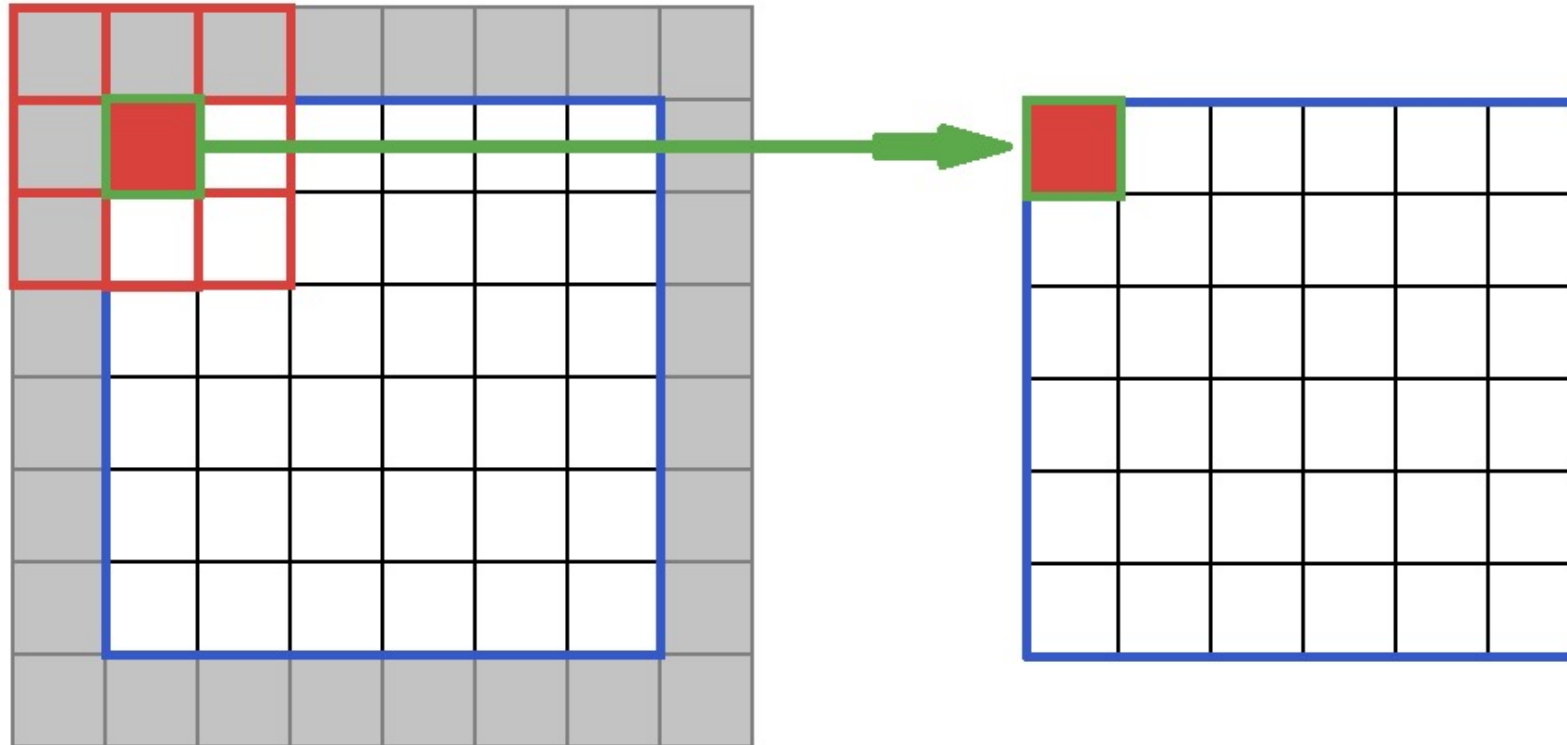
Can then stack a sequence of convolution layers, interspersed with activation functions:

Stacking many convolutional layers leads to identifying patterns in increasingly **larger regions of the input (e.g., pixel) space.**



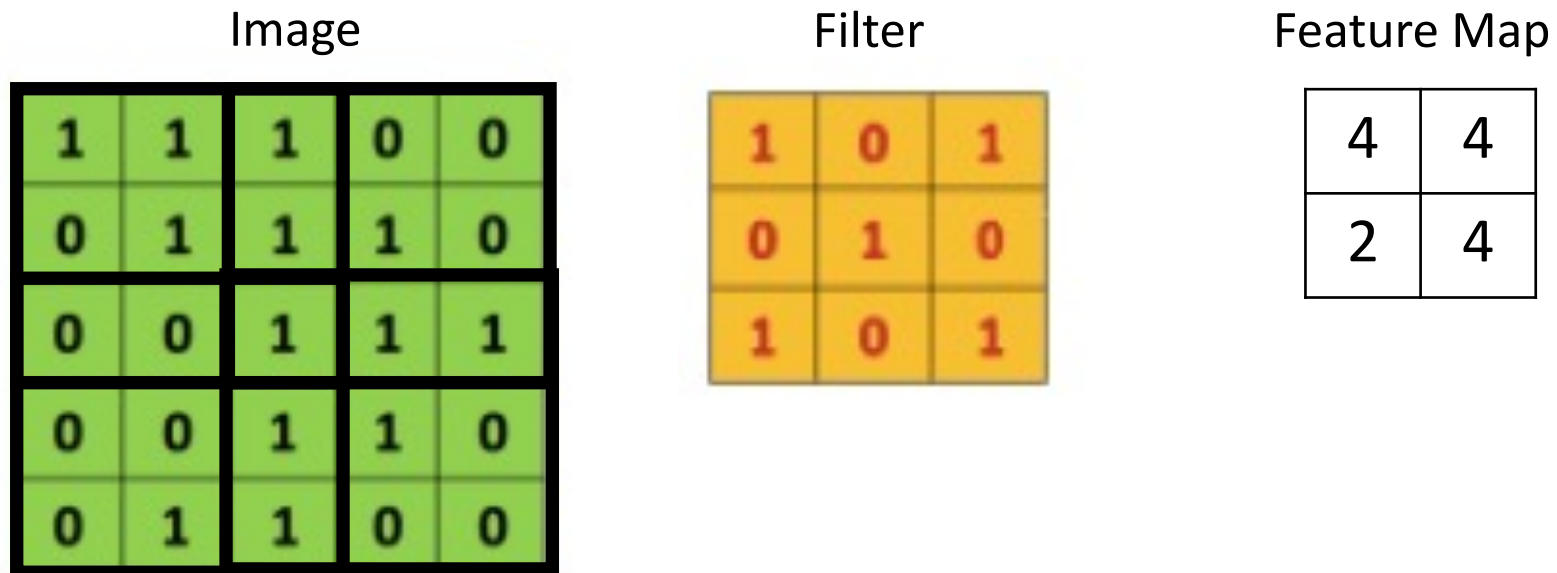
Convolution: Implementation Details

- **Padding:** add values at the boundaries to control output size



Convolution: Implementation Details

- **Stride:** how many steps taken spatially before applying a filter
 - e.g., 2x2



Convolution: Implementation Details

- Demo:

- https://theano-pymc.readthedocs.io/en/latest/tutorial/conv_arithmetic.html

Parameters vs Hyperparameters In Convolutional Layers

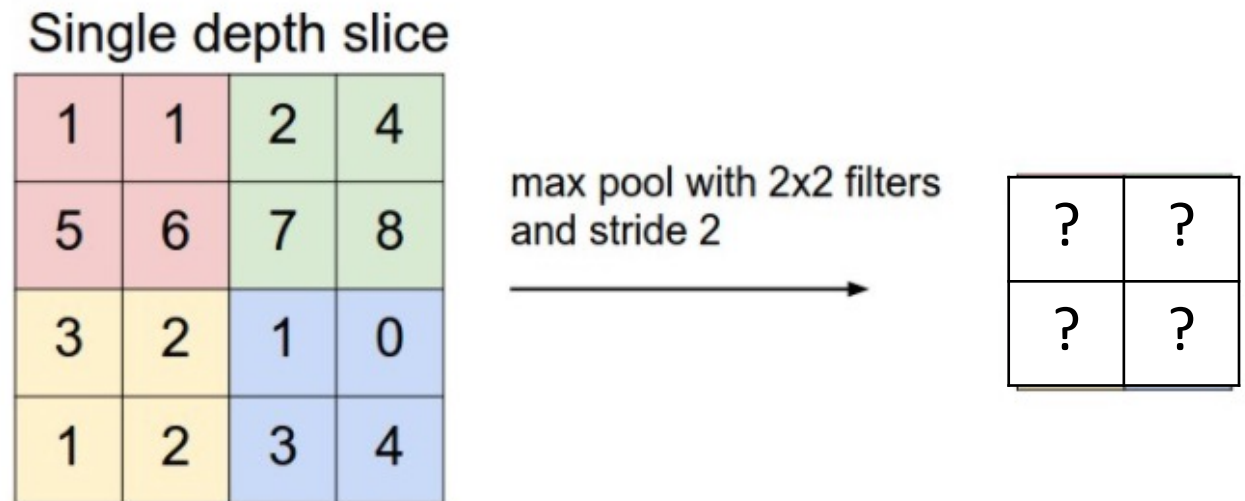
- Hyperparameters:
 - Number of filters, including height and width of each
 - Strides
 - Padding type
- Parameters
 - Weights
 - Biases

Today's Topics

- Neural Networks for Spatial Data
- History of Convolutional Neural Networks (CNNs)
- CNNs – Convolutional Layers
- CNNs – Pooling Layers

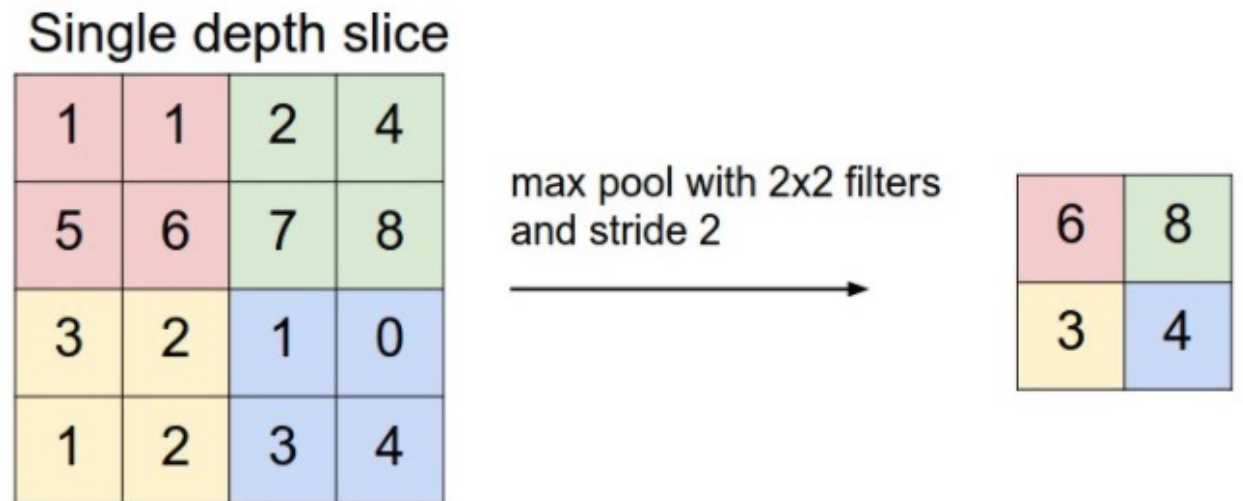
Pooling Layer: Summarizes Neighborhood

- **Max-pooling:** partitions input into a set of non-overlapping rectangles and outputs the maximum value for each chunk



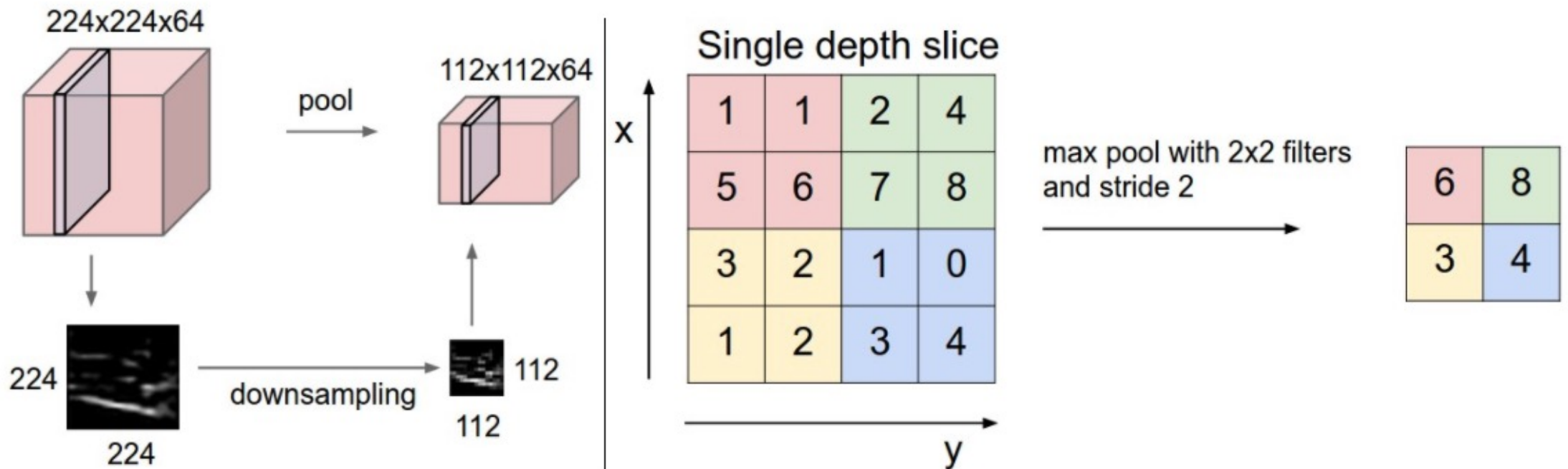
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Pooling Layer: Summarizes Neighborhood

- **Max-pooling:** partitions input into a set of non-overlapping rectangles and outputs the maximum value for each chunk

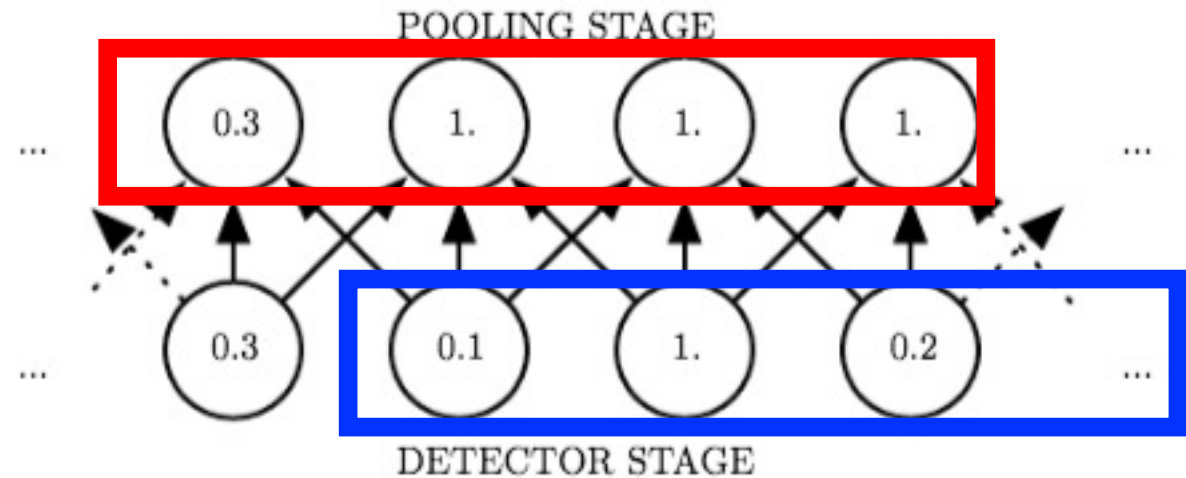
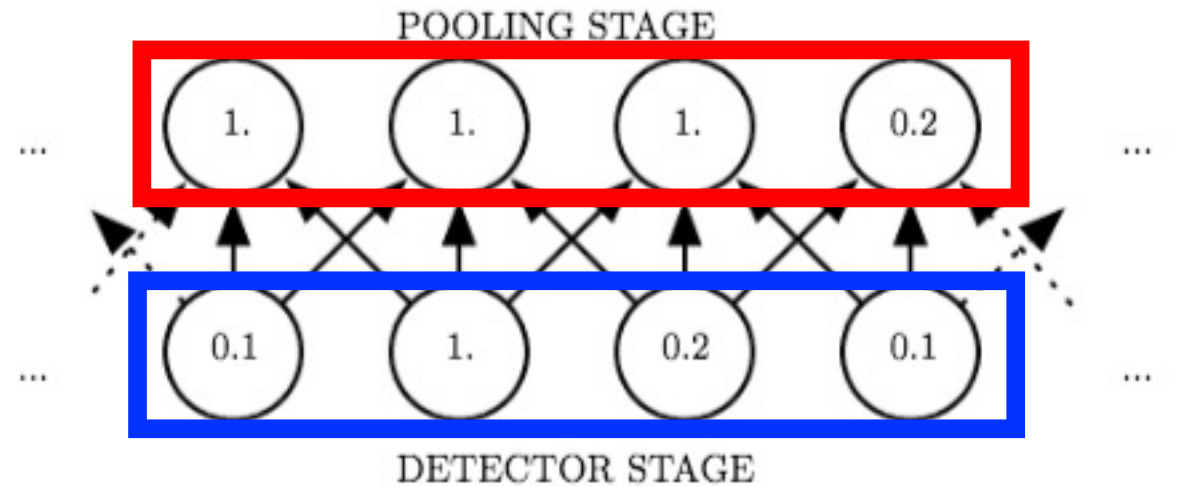


Pooling Layer

- Resilient to small translations

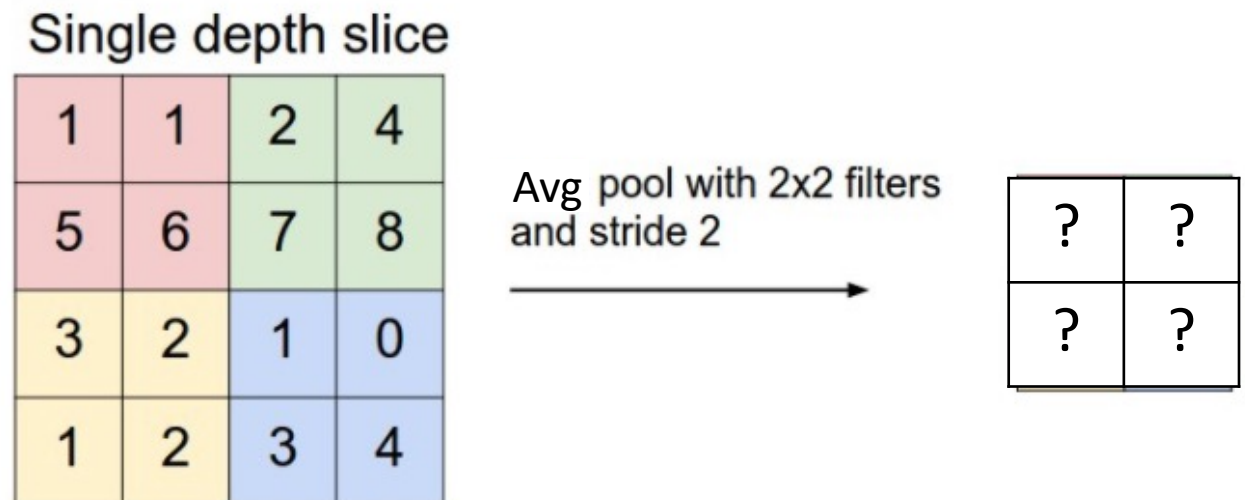
• e.g.,

- Input: all values change (shift right)
- Output: only half the values change



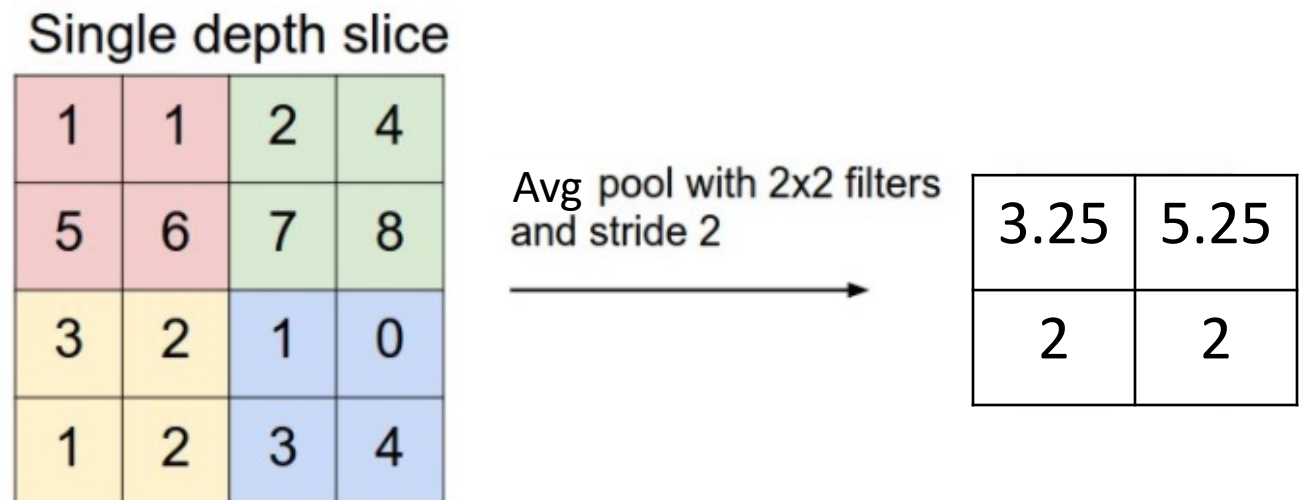
Pooling Layer: Summarizes Neighborhood

- **Max-pooling:** partitions input into a set of non-overlapping rectangles and outputs the maximum value for each chunk
- **Average-pooling:** partitions input into a set of non-overlapping rectangles and outputs the average value for each chunk



Pooling Layer: Summarizes Neighborhood

- **Max-pooling:** partitions input into a set of non-overlapping rectangles and outputs the maximum value for each chunk
- **Average-pooling:** partitions input into a set of non-overlapping rectangles and outputs the average value for each chunk



Pooling Layer: Benefits

- How many parameters must be learned?
 - None
- Benefits?
 - Builds in invariance to translations of the input
 - Reduces memory requirements
 - Reduces computational requirements

Today's Topics

- Neural Networks for Spatial Data
- History of Convolutional Neural Networks (CNNs)
- CNNs – Convolutional Layers
- CNNs – Pooling Layers

A dark gray background with a white film strip border on the left and right sides. The film strip has rectangular sprocket holes. In the center, there is a faint, circular white glow. The text "The End" is written in a white, cursive script font with a slight drop shadow, centered within the glow.

The End