# Object Tracking

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The University of Texas at Austin Fall 2019



#### Review

- Last week:
  - Video classification and localization applications
  - Evaluating video classification and localization
  - Crowdsourcing video classification and localization
- Assignments (Class Website & Canvas)
  - Project proposal due yesterday
  - Project outline due in two weeks
- Questions?

## Today's Topics

- Object tracking applications
- Evaluating object tracking methods
- Crowdsourcing object tracking strategies
- Object tracking datasets & challenges
- Lab: video annotation & creating figures/tables in latex

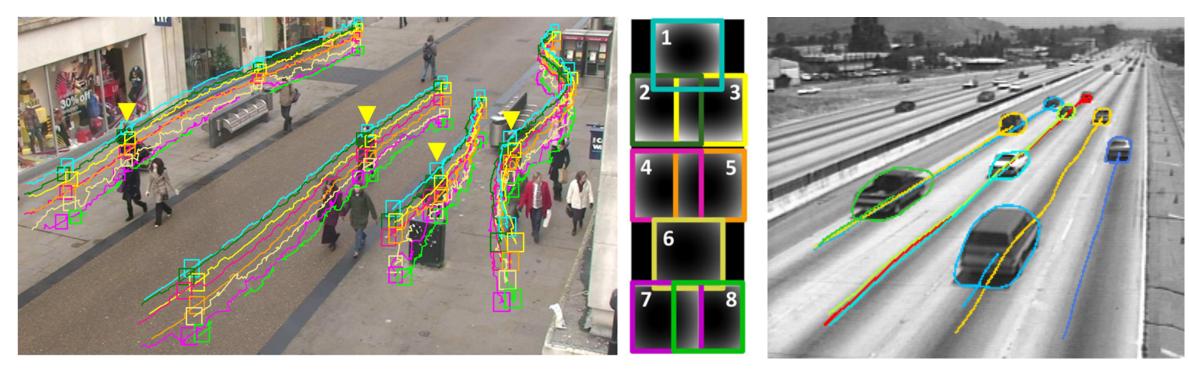
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#### Definition

• Each object in a video is localized (object detection) and followed as it moves over time (tracking)

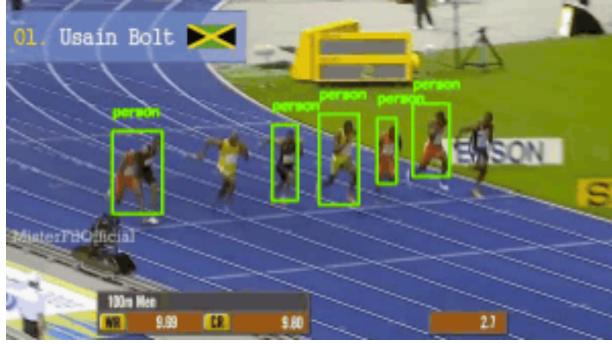
## Application: Surveillance



People Tracking Traffic Control

## Application: Sports Analysis





#### Application: Performance Analytics

Calculate Bat speed from video!



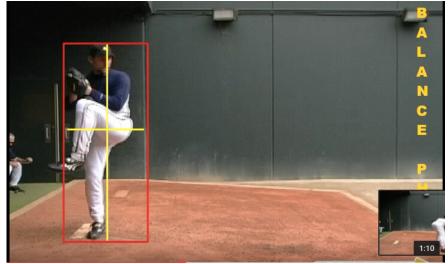
NEW! Track Bowling Ball Path!



Works great for putting!



http://www.motionprosoftware.com/



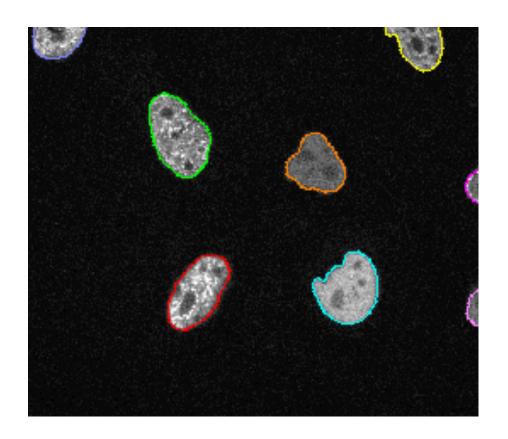
Watch: Dartfish Analysis

Watch: Pitch Analysis

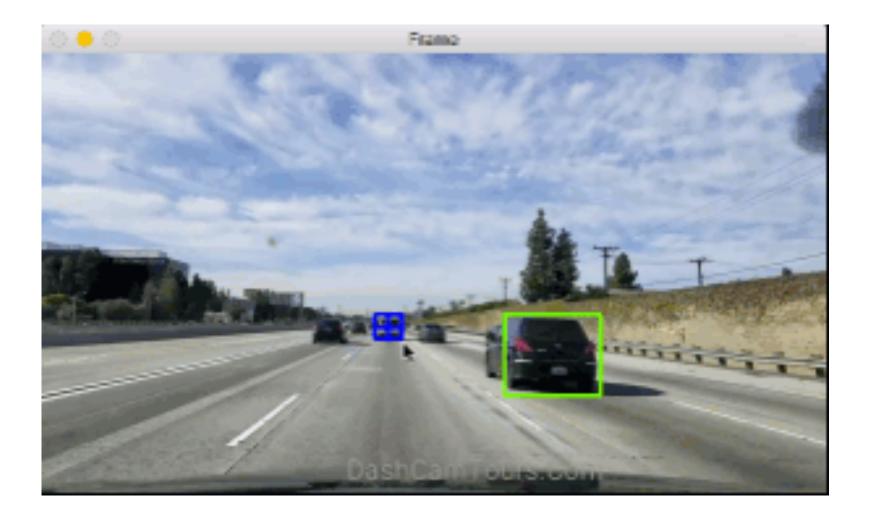
## Application: Military Defense



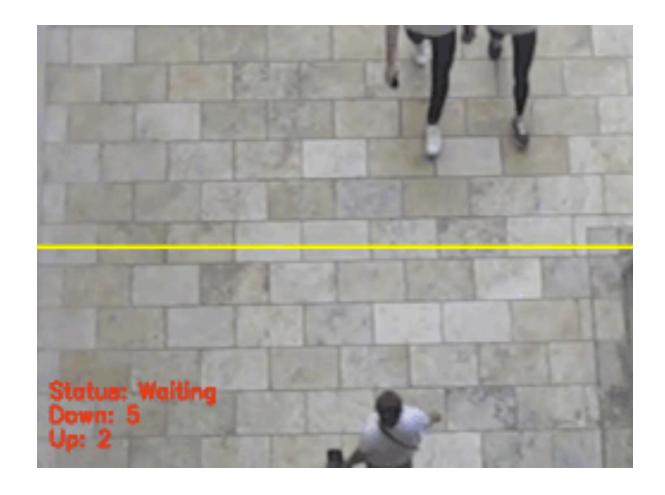
## Application: Cell Tracking & Mitosis Detection



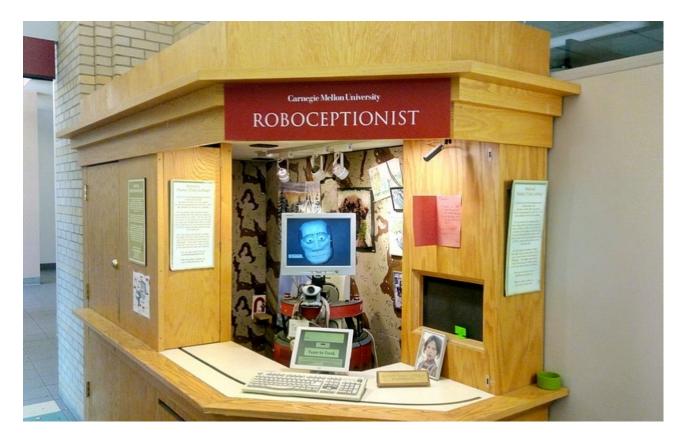
## Application: Self-driving Cars



## Application: People Counting



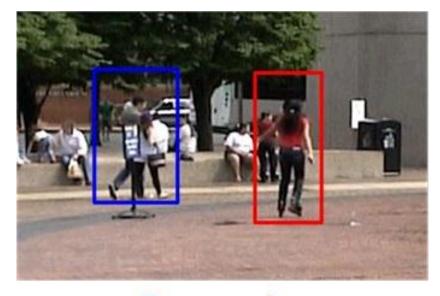
#### Application: Human Computer Interaction



Roboceptionist

## Application: Activity Recognition



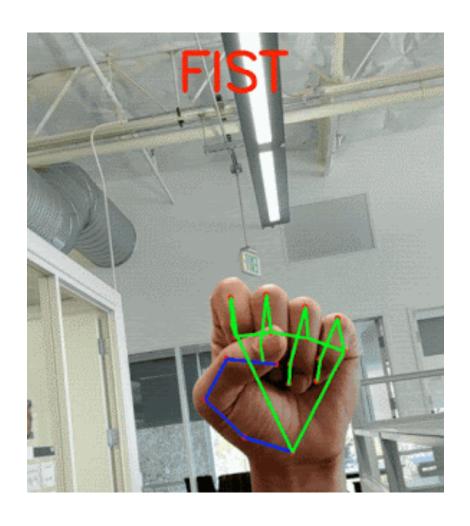


walk

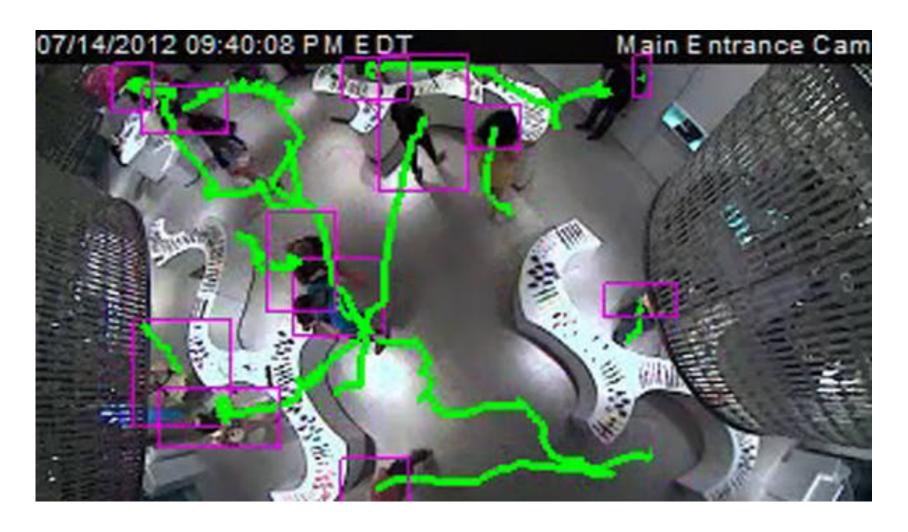
skate

https://www.bu.edu/ids/research-projects/action-recognition/
https://www.crcv.ucf.edu/projects/realistic action recognition/

### Application: Sign Language Recognition



## Application: Marketing



## Application: Augmented Reality





https://www.geekwire.com/2017/augmented-reality-shopping-phone-patent-hints-amazons-aspirations/https://virtualrealitypop.com/object-recognition-in-augmented-reality-8f7f17127a7a

#### Applications

What other applications can you think of where object tracking could be useful?

#### Applications: Many More

- Robotics
- Space and satellite
- Industrial production
- Ecological monitoring
- Healthcare
- Anomaly detection

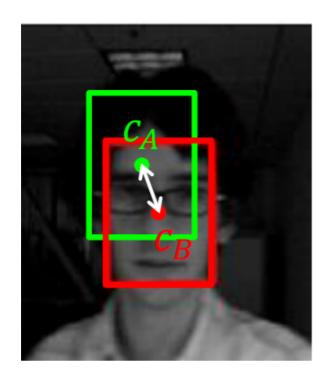
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#### Evaluation Metrics - I

#### **Precision**

Distance between the centers of bounding boxes for each frame



A = Ground Truth

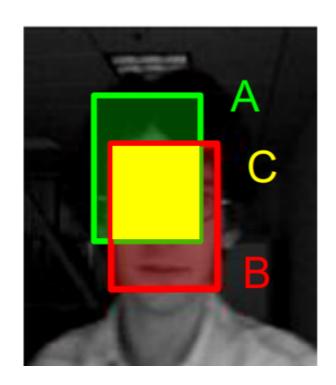
**B** = Predicted Track

$$p = \|c_A - c_B\|$$

#### **Evaluation Metrics - II**

#### **Overlap**

Intersection over Union (IoU) of the bounding boxes for each frame



A = Ground Truth

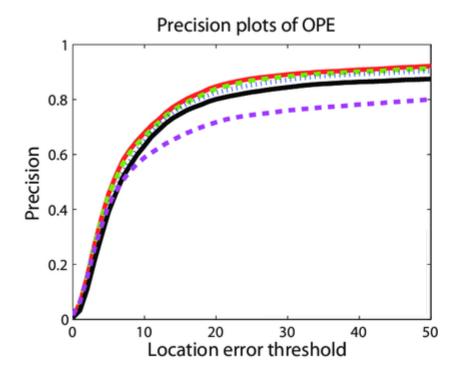
**B** = Predicted Track

C = Intersection

$$o = \frac{C}{A + B - C}$$

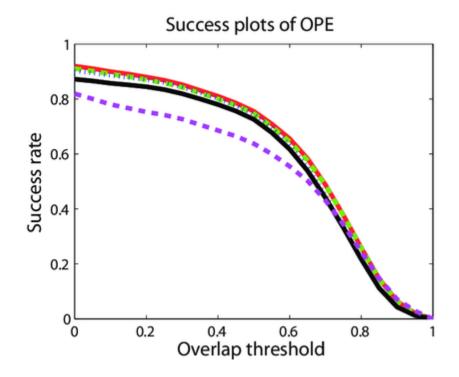
#### Visualization of Evaluation Metrics - I

• **Precision plot**: Percentage of frames with predicted location within a given threshold distance of ground truth (for e.g., 20 pixels)



#### Visualization of Evaluation Metrics - II

• Overlap plot: Percentage of frames where the overlap between the bounding boxes is larger than a given threshold (for e.g., 0.5)



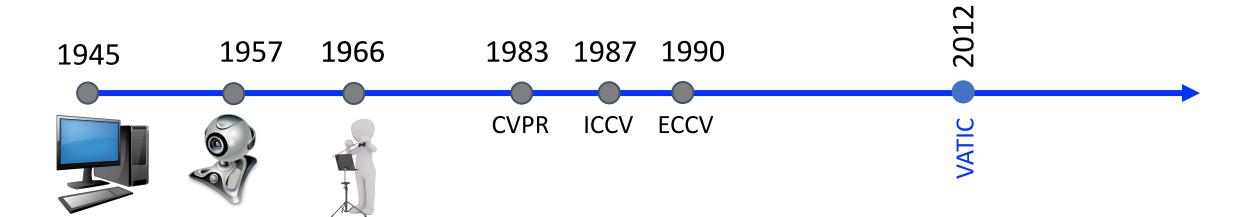
#### **Evaluation References**

- Gao, C., Shi, H., Yu, J. G., & Sang, N. (2016). Enhancement of elda tracker based on cnn features and adaptive model update. Sensors, 16(4), 545
- Wu, Y., Lim, J., & Yang, M. H. (2013). Online object tracking: A benchmark. In *Proceedings of the IEEE conference on computer vision and pattern recognition* (pp. 2411-2418)

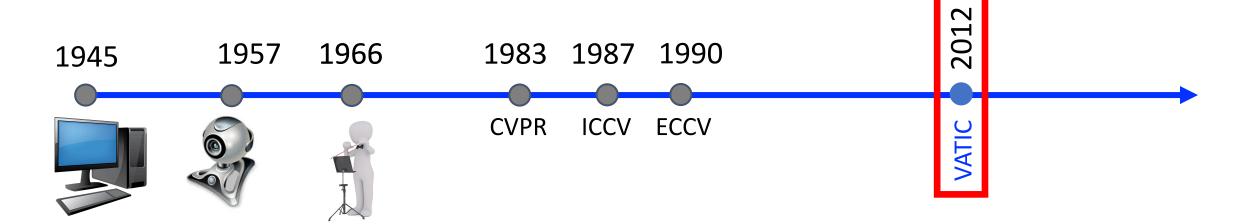
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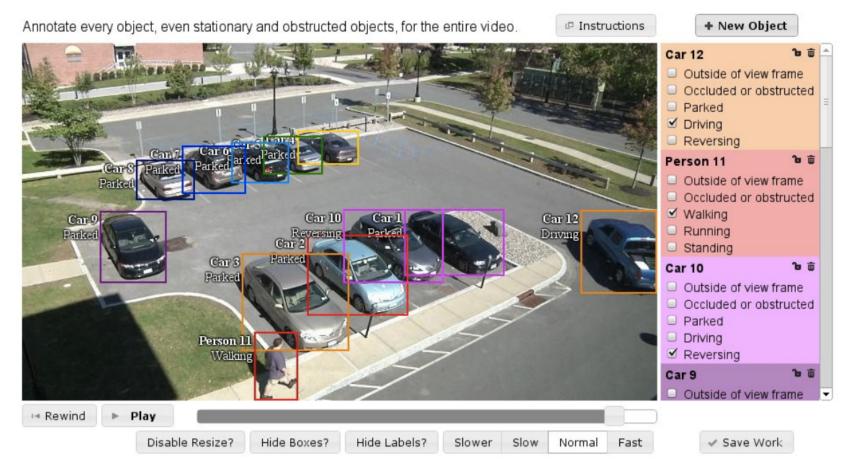
### Object Tracking Approaches



### Object Tracking Approaches: VATIC

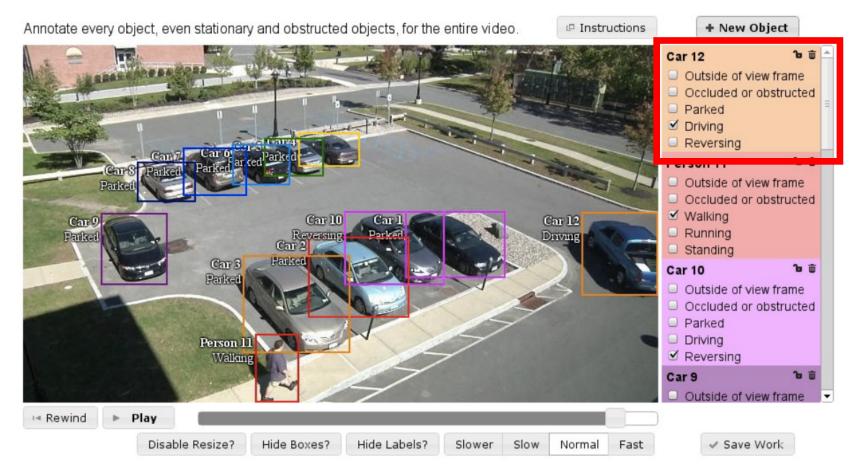


#### Object Tracking Approaches: VATIC



Demo: https://www.youtube.com/watch?v=ljI5pAowACc

#### Object Tracking Approaches: VATIC



Metadata about each object: e.g., activity, attributes, etc.

#### VATIC Design

- Goal: user studies to establish best-practices
- Data: 3 videos



1. Scripted: large objects, linear motion



2. Basketball: small object occluded frequently, nonlinear motion



3. VIRAT: slow moving/stationary cars, linear motion

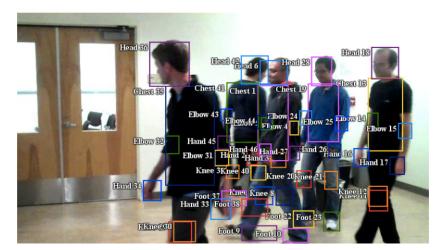
#### VATIC Studies: Task Design

		Scr	ipted			Bask	etball		VIRAT			
Subject	User	Fixed	Ratio	Saved	$_{ m User}$	$\mathbf{Fixed}$	Ratio	Saved	$_{ m User}$	Fixed	Ratio	Saved
A	599	463	0.77	136	1,457	1,323	0.91	134	220	244	1.11	-24
В	653	<b>247</b>	0.38	406	$4,\!555$	2,275	0.50	$2,\!280$	176	178	1.03	-2
C	476	<b>27</b> 5	0.58	201	$1,\!216$	830	0.68	386	338	<b>215</b>	0.64	123
D	772	<b>432</b>	0.56	340	1,505	1,497	0.99	8	489	<b>302</b>	0.62	187
*E	605	371	0.61	234	935	1501	1.61	-566	269	231	0.85	38
*F	654	$\boldsymbol{472}$	0.72	182	1,672	1,858	1.11	-186	372	<b>326</b>	0.87	46
*G	235	193	0.82	42	591	696	1.18	-105	165	120	0.73	45
*H	312	331	1.06	-19	656	748	1.14	-92	172	<b>164</b>	0.95	8
Mean	538	348	0.66	190	1,573	1,341	0.96	232	275	223	0.83	53

Fixed interval key frames significantly faster than user defined key frames!

#### VATIC Studies: Task Design

			Human Joints						Basketball					
Subject	One		Group		A	11	One		Group		All		Preferred	Order
A	1639	1.00	1763	1.07	-	-	476	1.00	358	0.75	253	0.53	One	OGA
В	2071	1.00	2100	1.01	2440	1.17	1382	1.00	1618	1.17	2403	1.73	One	AOG
C	1867	1.00	1 2106	1.12	-	-	681	1.00	813	1.19	<b>599</b>	0.87	One	GAO
D	2399	1.00	I -	_ !	_	-	494	1.00	448	0.91	960	1.94	One	AOG
Mean	1994	1.00	1989	1.07	2440	1.17	759	1.00	809	0.99	1085	1.12		

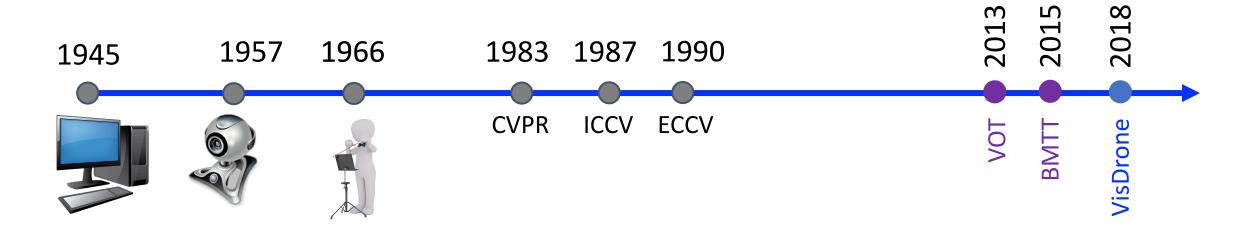


#### Annotating one object at a time is more efficient and preferred!

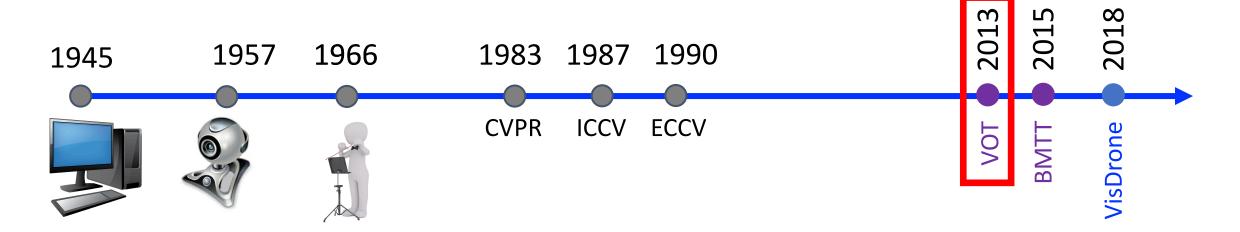
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### **Object Tracking Datasets**



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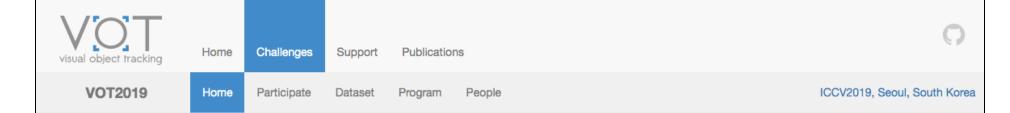


### Object Tracking Datasets: VOT

• Collected existing datasets, which resulted in inconsistent annotation methodologies across videos (e.g., different bounding box criteria)

 Authors re-annotated object tracking for videos they deemed to have unsuitable annotations

## VOT Annual Challenge (7<sup>th</sup> year now)



#### VOT2019 Challenge

The VOT challenges provide the tracking community with a precisely defined and repeatable way of comparing short-term trackers and long-term trackers as well as a common platform for discussing the evaluation and advancements made in the field of visual tracking. Following six highly successful VOT challenges, the 7th Visual Object Tracking Challenge VOT2019 workshop will be held in conjunction with the ICCV2019.

#### **Highlights**

- · Two new challenges introduced (VOT-RGBT & VOT-RGBD)
- VOT-RGBT2019 challenge will evaluate trackers that use 4 channels (RGB + IR) in tracking.
- VOT-RGBD2019 challenge will evaluate trackers that use 4 channels (RGB + depth) in tracking.
- Updated VOT toolkit to support multi-channel inputs.
- · Authors of well-performing trackers will be invited to coauthor the VOT2019 results papers.
- · Authors of top-performing trackers will be invited to present their trackers at VOT2019 workshop.

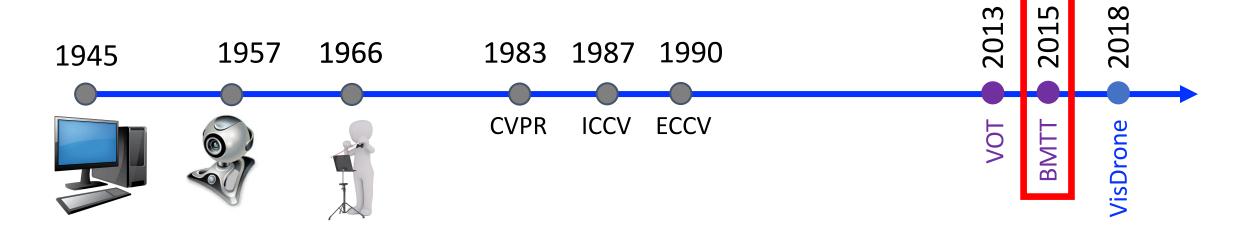
#### The VOT2019 Challenges

- VOT short-term tracking challenge VOT-ST2019 (same as in VOT2018) Robust short-term tracking under appearance variation, occlusion and clutter.
- VOT short-term real-time challenge VOT-RT2019 (same as in VOT2018) Robust short-term tracking under time constraints.
- VOT long-term tracking challenge VOT-LT2019 (same as in VOT2018) Robust tracking with target disappearance.



http://www.votchallenge.net/vot2019/

### **Object Tracking Datasets**



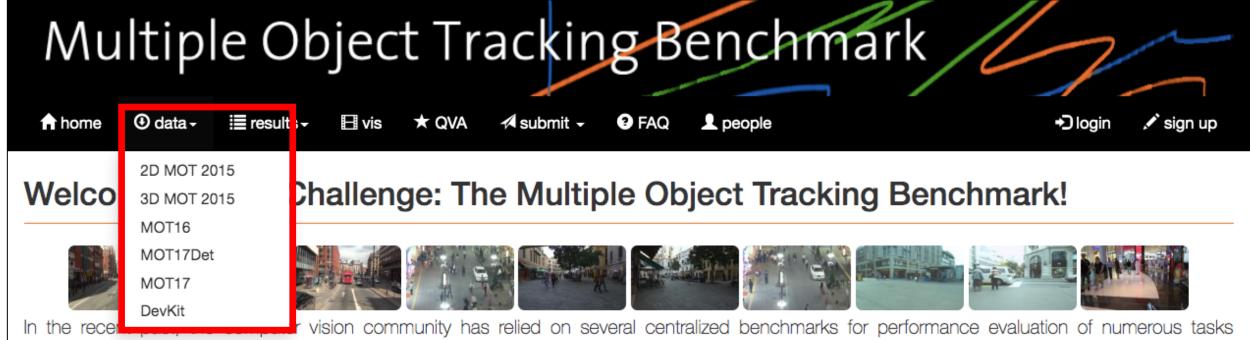
#### Object Tracking Datasets: BMTT

Authors collected 22 videos



Unspecified how object tracking annotations were collected

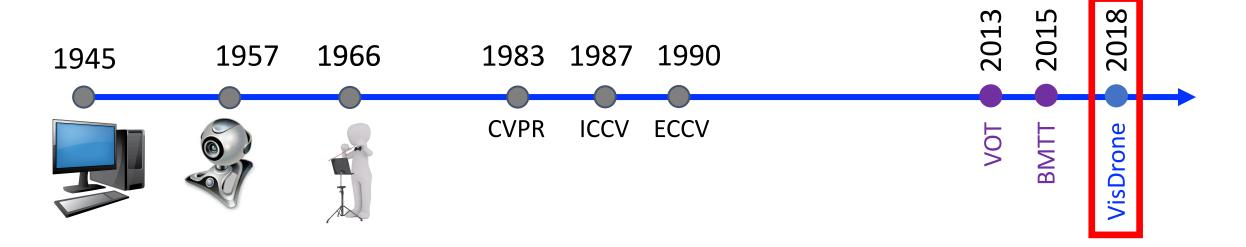
#### BMTT MOT Annual Challenge



including object detection, pedestrian detection, 3D reconstruction, optical flow, single-object short-term tracking, and stereo estimation. Despite potential pitfalls of such benchmarks, they have proved to be extremely helpful to advance the state-of-the-art in the respective research fields. Interestingly, there has been rather limited work on the standardization of multiple target tracking evaluation. One of the few exceptions is the well-known PETS dataset, targeted primarily at surveillance applications. Even for this widely used benchmark, a common technique for presenting tracking results to date involves using different subsets of the available data, inconsistent model training and varying evaluation scripts.

With this benchmark we would like to pave the way for a unified framework towards more meaningful quantification of multi-target tracking.

## **Object Tracking Datasets**



#### Object Tracking Datasets: VisDrone

• Authors collected 263 video clips (179,264 frames) from drones in Asia















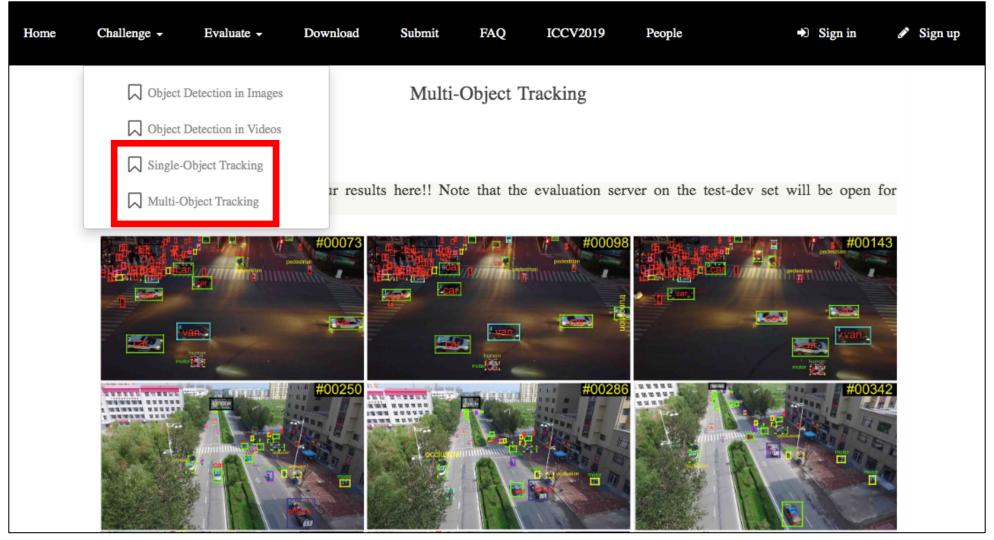






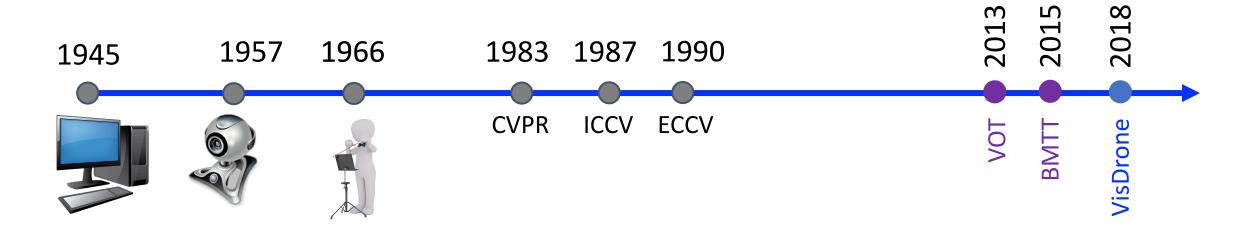
 Annotations created for over 2.5 million object instances, however it is unspecified how these annotations were collected

#### VisDrone Challenge



http://www.aiskyeye.com/views/index

### **Object Tracking Datasets**



#### Discussion

- Design a crowdsourcing system to collect high quality object tracking annotations. Specify how your system design will handle difficult scenarios such as when an object is:
  - Partially visible
  - Occluded
  - Is reflected in reflective surfaces such as mirrors or windows
- What will be the total crowdsourcing task cost if we use your system to annotate 1,000 1-minute videos where you need to track 5 humans/video (assume 30 frames/second)?

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